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PREFACE

This book has been written to meet the requirements of the students who are preparing for B.Sc. and/or **SECOND YEAR AND THIRD YEAR** of the **Three Year Degree** course examinations. This book is a modest attempt to present the experimental procedure in the most simple and lucid style. Students will find the treatment helpful in the present day laboratory conditions. The treatment is neither too voluminous nor too brief. The book possesses the following special features :

1. A large number of self-explanatory diagrams incorporating all physical principles are included. An elaborate description of the apparatus has been given to facilitate easy manipulation with a view to make an allowance for various types of instruments used for the same experiment in different laboratories.

2. Necessary and sufficient theory concerning the intelligent performance of an experiment has been given.

3. Method has been described in such a great detail and with such clarity that a student will find it very simple to do the experiment. Detailed description will enable him to fully grasp the intricacies of an experiment.

4. Clear and systematic tables have been drawn to take various observations.

5. At the graduation stage students are expected to fully know the various errors made in doing an experiment. Keeping this fact in view, precautions and sources of error have been dealt with in details. Thorough and exhaustive criticism has been added to enable a student to know the process by which percentage accuracy can be increased.

6. Oral questions in the form of an exercise has been added at the end of each experiment. It is to ascertain whether the experiment has been completely understood.

Before beginning any experiment students are advised to study carefully the introduction.

We are very much thankful to Prof. B.L. Jain, Prof. Behari Lal, Prof. D. T. Chandwani and Prof. T.N. Bhatnagar, for giving valuable suggestions in the preparation of this book. Our thanks are also due to our publishers Ramesh Book Depot and the printers, for bringing out this book in such a short time. Suggestions towards the improvement of this book will be highly appreciated.

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PART I

(For II Year)



INTRODUCTION

Laboratory is the most important place for a student of science. It is the place where he verifies the validity of various laws governing the physical phenomenon. This requires perseverance, keen observation and accurate measurements. Physics is a science of measurements. Hence, more accurate the measurement of various entities, the nearer the truth will be the result.

For measuring various quantities, selection of proper units is essential. Three quantities are fundamental. (i) Length, (ii) Mass and (iii) Time. They are independent of each other. All other quantities can be expressed in terms of these three, cited above. For example, if we know the length of a box in three perpendicular directions, its volume can be determined. Thus, it is neither necessary nor convenient to select independent unit for each quantity. In C. G. S. system, *the unit of length is a cm., of mass a gm. and of time a second.* The respective units for these quantities in F. P. S. system are *foot, pound and second.* Temperature readings also involve the measurement of length of the mercury thread, which is proportional to the rise in temperature. It is expressed in *degrees Centigrade or Fahrenheit.* All other units which can be expressed in terms of the fundamental units are known as *derived units.*

Measurement of length :—The simplest and the most common way of measuring length is by the help of a metre scale or an ordinary foot rule. The accuracy obtained in such measurements is extremely limited. They can measure up to only 1 mm. or 0.5 mm. For attaining greater accuracy *vernier scales, (screw gauges and spherometers etc.)* are to be employed. They can measure lengths accurately up to 0.001 to 0.005 cm. depending upon their least counts.

Measurement of mass :—Mass can be measured with the help of a *balance.* The accuracy of mass determination will depend upon the *sensitivity of the balance used.* Ordinarily, by an ordinary physical balance masses up to one milligram can be measured. A *chemical balance* using a rider can be used to measure masses correct up to 0.1 milligram. Where much accuracy is not needed, a *spring balance* can also be employed for this purpose.

Measurement of time :—Generally, time is measured with help of *stop-clocks* or *stop-watches*. They can ordinarily measure correct up to 1 to 1/10th of a second, depending upon their least count. Specially made pocket stop watches can measure time, even up to 1/50th or 1/100th of a second. Time can also be measured with the help of a *metronome*, or a *tuning fork*. Where high accuracy is to be obtained, *chronometers* are used.

Getting ready for an experiment :—Before you begin an experiment, thoroughly study the principle involved in it. At the B, Sc stage the performance should not be at all mechanical. It is almost a sheer wastage of time to perform an experiment without the exact grasp of its full details. After knowing the procedure, carefully study the formula which is going to be used for calculating the result. From the formula find out the quantities which are to be measured. Knowing the quantities, determine the accuracy with which each quantity is to be measured. Accordingly select the apparatus possessing the proper range.

Absolute error and proportional error :—In measuring any quantity, it is the *relative error* which is more important than the *absolute error*. The proportional error can be determined by taking the ratio of the magnitude of the error to the total magnitude of the quantity which is to be measured. More importance should be attached to reduce this proportional error present in the measurement of each quantity. As for example, in determining η by dynamical method, radius of the wire r should be measured more accurately than the length of the wire. Suppose an error of 2 cm. has been made in determining the length of the wire which is say, 300 cm. Then the *percentage error* committed in measuring this length will be equal to 0.66%. But a mistake of 0.002 cm. done in measuring the diameter of a wire which is say, 0.1 cm. will be 2%. Furthermore, the radius is to be raised to the fourth power in the formula, this error consequently becomes 8%. Though the *absolute error* made in the determination of r is much less than the error made in determining l the *percentage error* in the former case is quite large. It is altogether useless to measure one quantity more accurately, when there is present a considerable error in the measurement of other quantities. The final percentage error is the resultant effect of the errors present in measuring the various quantities involved. Thus, the final result will not possess an accuracy greater than that possessed by the least accurately determined quantity. Similarly, in determining acceleration

due to gravity by simple pendulum, the periodic time should be determined more accurately than the length of the pendulum. A number of such examples can be cited.

Thus, first of all determine the *probable percentage* in the measurement of each quantity, and then decide which quantities are to be measured to which accuracy. All the quantities must be measured to the same degree of accuracy. The quantities which involve greater percentage error should be measured for a number of times, and precision instruments should be used to measure them, so that the percentage error is reduced to the same value in all quantities measured.

Calculation of percentage error:—In order to determine percentage error, take the logarithm of the quantity to be determined in terms of the quantities to be measured, and differentiate, substitute proper values for the entities occurring in this equation and calculate the percentage error. Suppose the volume of a cylinder is to be measured. Then, $V = \frac{\pi}{4} D^2 l$, where V is the volume, D the diameter and l the length of the cylinder. Taking logs we get

$$\log V = \log \frac{\pi}{4} + 2 \log D + \log l$$

Differentiating this equation we get,

$$\frac{dV}{V} = 2 \frac{\delta D}{D} + \frac{\delta l}{l}$$

We are using a vernier callipers to measure the diameter and length of the cylinder. An error of one division can be made in reading the vernier on either side of actual coincidence. Hence, the probable error may be ± 0.02 cm. when the least count of the instrument is 0.01 cm. Therefore $\delta D = 0.02$ cm; and $\delta l = 0.02$ cm. If $l = 2$ cm, and $D = 2$ cm; we have,

$$\frac{dV}{V} = 2 \frac{0.02}{2} + \frac{0.02}{2}$$

dV is the error made in V , therefore the percentage error will be,

$$\begin{aligned} 100 \times \frac{dV}{V} &= \frac{2}{2} \times 0.02 \times 100 + \frac{0.02}{2} \times 100 \\ &= 2 + 1 \\ &= 3\% \end{aligned}$$

Hence the percentage error in determining the volume = 21. As is evident, the percentage error is quite large in the measurement of diameter. Therefore, more observations should be taken to measure D , and a value of smaller least count should be used.

Personal errors made in taking observation:—The accuracy of the result also depends upon the individual performing the experiment. As for example, suppose two different persons are to set the prism in the minimum deviation position. As they possess different powers of judgement, the setting may be slightly different, and the values obtained by the two persons for the angle of minimum deviation may differ. Even the two observations taken by the same person may differ. Therefore, this personal factor introduces some error. To minimise this error, observations for the same measurement are repeated a number of times. Arithmetic mean is then determined. Even this arithmetic mean is not completely free from errors. To further reduce the error, it is actually calculated. From Gaussian theory of errors we get,

$$E = 0.6745 \cdot \sqrt{\frac{\sum \delta^2}{n(n-1)}}$$

Where E is the probable error present in the mean value M , δ the departure of each observation from the mean M , and n the number of observations taken for the same quantity. Then, the corrected value of M will be, $M \pm E$.

Performance and recording of an experiment:—(1) Having learnt all about the experiment, select the apparatus of proper range and get it issued. Before you start doing the experiment, see that the following things are recorded in your practical note book.

- (a) Day and date.
- (b) Temperature and pressure. (If they are needed)
- (c) Name of the experiment.
- (d) Apparatus required.
- (e) A neat and carefully drawn self-explanatory diagram.
- (f) Necessary theory.
- (g) Method (It should be written in details, so that the revision of the experiment at some latter date may be easy.)
- (h) Observation table (Always of the page after leaving margin.)

Introduction:

- (i) Results. (Always mention the units, otherwise result will be meaning less.)
 - (j) Precautions and sources of error.
 - (k) Percentage error.
 - (l) Criticism on the result and performance of the experiment.
2. Note the least count and the range of the instruments you are working with. Keep it in mind that small quantities and that too occurring in higher powers always need greatest attention and repetition. Very large quantities may be measured only once e.g. weighing is mostly accurate and so it is done only once.
3. Note all the observations *directly* in the table. Over writing should never be done on any grounds. It is a wrong practice to note observations first in rough note book and then to record in fair note book, which give correct result. If you record a wrong set of observations and if you can explain what mistake you have made, it goes to your credit. Take as large a number of observations as possible. All quantities must be recorded with proper units.
4. As soon as you take a good number of sets of observations, start calculating the result by log tables. It is essential in the B.Sc., classes that the result must be calculated by log tables. You are already familiar with the use of log tables. All the calculations must be shown in the fair note book. It is advised to record the calculations performed by logs on the margin of the left side page. See that neatness of the copy is maintained.
5. Do not forget to mention the units of the result obtained.
6. At the end of the experiment you must discuss the result obtained, and the difficulties encountered while doing the experiment. Now calculate the percentage error, and give a fair criticism of the work you have done.
- Graphs:—(1) A graph can be drawn in any two interdependent quantities e.g. between angle of incidence and angle of deviation, or between the actual readings of an ammeter or a voltmeter and corresponding errors.
2. A graph paper is required for drawing a graph. The horizontal axis is taken as X axis, and the vertical axis as Y axis.
3. The independent variable is generally plotted on the X axis and the resultant variable on the Y axis.

4. Choose a suitable scale to represent the two variables in the full graph paper may be used.

5. The origin of the graph need not be zero.

6. Take at least five observations covering the full range.

7. The points on graph should preferably be shown as \circ .

8. When you want to connect these points by means of a curve try to do it in a smooth way. It is not necessary for your curve to pass through all the points. Draw it smoothly in a such a way that it passes through maximum number of points.

9. It is always better to anticipate from theory whether you expect a straight line, or a hyperbolic curve etc. and draw it accordingly.

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EXPERIMENT No. I

Experiment:—To determine Young's modulus of a bar (rectangular beam) by bending (flexure).

Apparatus:—A bar of rectangular cross-section, two strong knife edges placed on clamps, a scale pan or a load tanger, 6 to 8 weights of half kilo gm. each, a metre scale, a vernier-callipers, a screw gauge, a travelling microscope, a needle or a pin or a spherometer, a galvanometer, cell, key, connecting wires etc.

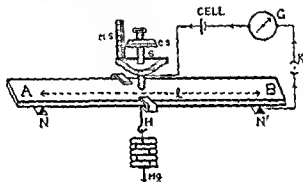


Fig. 1

Description of the apparatus:—It consists of rectangular bar AB of the material whose Young's modulus (Y) is to be determined. The bar is placed on two rigid knife edges N and N' clamped on the table. From the mid point of the bar a hanger is suspended which can carry the load as shown in fig. (1). If microscope is to be used, there is placed a frame at the centre of the bar in which is fixed a horizontal wire as shown in fig. 3. The wire serves as a reference.



Fig. 2

When a spherometer is used to find out the depression, the arrangement is as shown in fig. (1). AB is the bar placed on the knife edges N and N' . It carries a load hanger suspended from its middle point. Just above the middle point is placed, either a micrometer screw or a spherometer. The central leg of the spherometer should touch the middle point where the hanger is placed. An electric circuit is also made con-

$$e = \frac{Mgl^3}{3YI}$$

For a rectangular beam $I = \frac{bd^3}{12}$, where b and d is respectively the breadth and depth of the beam.

$$\therefore e = \frac{4Mgl^3}{Ybd^3} \dots\dots\dots (1)$$

When the beam is placed on the knife edges and loaded in the middle as is done in this experiment the reaction at each knife edge will be $Mg/2$ acting in the upward direction. As in the neighbourhood of the middle point the beam will be horizontal; it may be considered as equivalent to two inverted cantilevers fixed at the middle point and loaded at C and D as shown in fig. (6). The load $Mg/2$ acts upwards at C and D. Hence the depression can be obtained by formula (1) by substituting $Mg/2$ in place of Mg and $l/2$ in place of l . Here l is length of the bar between the two knife edges C and D.

$$\begin{aligned} \therefore e &= \frac{4 \frac{Mg}{2} (l/2)^3}{Ybd^3} \\ &= \frac{Mgl^3}{4Ybd^3} \dots\dots\dots (2) \\ \text{or } Y &= \frac{Mgl^3}{4bd^3e} \dots\dots\dots (3) \end{aligned}$$

Method —1. Place the rectangular bar on the two knife edges symmetrically. The two end portions of the bar which remain projecting beyond the knife edges should be equal. Place the bar in such a way that the depth remains vertical and its length is perpendicular to the two knife edges.

Determination of depression (e) a by microscope—

2. Mark the middle point of the bar and put a frame there. The frame has a horizontal wire fixed at its centre. The wire is used to determine depression. A pin can also be fixed in place of the wire.

3. Suspend the load hanger from the middle point of the bar. Find V. C. of the microscope. Focus it (so that its scale remains vertical) on the wire or the tip of the vertical pin. Take the reading on the microscope scale. It constitutes the initial reading. In this case the horizontal cross wire should coincide with the image of the wire

4. Place gently half kilo-gm. weight on the hanger. The wire will be slightly depressed. Lower the microscope and again focus it on the wire. Again read the microscope scale. It forms the second reading.

5. Go on increasing the weights in steps of half kilo gm. Each time after focussing the microscope in a similar way note the reading on its scale. The weights can be put up to 3 to 4 kilo-gm. [If you put more weights the elastic limit may be crossed and the beam may not return to its original condition. The depression produced should not exceed two-thirds of the maximum permissible depression, within the elastic limit. The depression should be so small that the ends at the edges may be regarded as horizontal].

6. Now decrease the load again in steps of half kilo-gm. Each time focus the microscope and take the corresponding reading, till the weight in the hanger is again zero.

7. Find the mean reading corresponding to each load.

Determination of depression by a spherometer:—

8. In this case first of all determine the least count of the spherometer and put it on the bar in such a way, that its central screw just touches the middle point of the bar where the hanger is placed,

9. Make the electric circuit as shown in fig. (1). The galvanometer will give deflection (or the bulb will be lighted up) only when the circuit is completed i. e. when the central leg just touches the bar. Therefore, move the screw till you just get deflection. Use of voltmeter is recommended in place of galvanometer. Galvanometer is to be used with heavy resistance in series.

10. Take the reading of the spherometer in this position when there is no weight in the hanger. It will constitute first reading.

11. Now put half kilo-gm. weight in the hanger as before, the bar will be depressed. Contact between the central leg and the bar will be broken. Consequently the current will stop. Move the central leg till it just touches the bar which will be indicated by the deflection in the galvanometer. Take the reading of the spherometer. This will be the second reading.

12. As done in the previous case go on increasing the weights in steps of half kilo-gm. Each time move the central leg till it just touches the bar as before. Take corresponding readings of the spherometer.

13. Similarly decrease the load again in steps of half kilo-gm. as before, and take the corresponding necessary reading till the weight in the hanger is again reduced to zero.

14. Similarly determine the mean reading corresponding to each load.

15. For both the cases discussed above, determine depression for two kilo-gm. This can be done by subtracting second reading from the sixth, or 3rd from 7th and so on. Determine mean depression for two kilo-gm.

16. Measure the distance between the two knife edges C and D. It gives l .

17. Measure breadth (b) of the bar with the help of a vernier callipers. Do it at two to three places and then find out mean (b).

18. Determine the thickness (d) of the bar with the help of a screw gauge. d should be determined at least at eight different places on the bar. Determine mean thickness d .

19. Knowing all the necessary things calculate Y by formule (3).

*Note:—*Some times the depression is determined by a optical lever. It is an extremely accurate method for the determination of depression. Please see for this method in Appendix.

Observations:—

[1] For l ; b ; and d

(i) Distance between the two knife edges (l) =cm.

(ii) Breadth of the bar (b);

V. C. =

(1) = ...cm; (2) = ...cm; (3) =cm

Mean (b) =cm.

(iii) Thickness of the bar (d)

L. C. of the screw gauge =cm.

(1) = ...cm. (2) = ...cm. (3) = ...cm.

(4) = .. cm. (5) = ...cm. (6) = ...cm.

(7) = .. cm. (8) = ...cm.

Mean d = ...cm.

{2} Table for the depression (e)

L. C. of the microscope or spherometer = . cm.

Load put in the pan in k. gm. (b)	Microscope Reading		Mean Microscope Reading $\frac{c+d}{2}$	Depression (e) for 2 k. gm.	Mean depression for 2 k. gm.
	Load increasing (c)	Load decreasing (d)			
0	—	—	— (f)		
1	—	—	— (g)		
1	—	—	— (h)		
1½	—	—	— (i)	$(j-f) =$	
2	—	—	— (j)	$(k-g) =$	
2½	—	—	— (k)	$(l-h) =$	
3	—	—	— (l)	$(m-i) =$	
3½	—	—	— (m)	$(n-j) =$	
4	—	—	— (n)		

Calculations—After substituting the values of l, b, d, g, w 0 gm; and e in the formula $Y = \frac{w l^3}{48 b^3 e}$, calculate Y

Result— $Y = \dots$ dynes/cm².

Sources of error and precautions — 1. Add or remove the weights slowly as possible.

2. Form the spherometer only when the wire or the pulley comes and take the readings on the microscope with care. The wire should not be shifted while taking various readings. It should be moved in the vertical direction. If spherometer screw is used, it be moved only in one direction to avoid back-lash error.

3. Through out the experiment the bar should not move on the fulcrum otherwise the fulcrum point will change.

4. As the thickness (l) of the bar enters as the third power in the formula, it should be determined very accurately by taking a number of plates. A small error in its determination will represent a large error in the determination of Y .

As Hooke's law fails when elongation is more than 25% of the length of the bar, the wire used as fulcrum should not be deformed too far.

The knife edge supporting the fulcrum should be parallel to the fulcrum wire and the wire is placed

Modifications -1 Draw a graph between load and depression and calculate the value of Y

2. Prove that the depression produced by loading a bar at its mid-point is inversely proportional to the cube of its thickness.

Criticism and percentage accuracy —

By means of a microscope the depression can be determined accurately up to 0.0002 cm. only. If more accuracy is desired micrometer screw of pitch $\frac{1}{2}$ mm. and L. C. = 0.0105 cm. should be employed. As there exists friction between the bar and the knife edges, the result is affected. Though we assume that one end is horizontal, it is not very correct. The beam should be very light and no saggings should take place due to its weight, but this is not always zero. So while increasing the length of the beam this point should always be borne in mind.

Oral Questions—1. Define Y , neutral axis, and axis of bending, elastic limit, elastic fatigue, breaking stress and strain. 2. How depression is produced? 3. What is a cantilever? 4. In how many ways can you measure the depression produced and which is the best way? 5. Why do you take a bar of longer length and smaller thickness? 6. Why you measure (d) so accurately? 7. What is elastic limit and how will you find this in a particular case? 8. How will you know that screw is just touching the bar? 9. How does Y depend upon temperature? 10. Why the girders are so made that their middle portions are of much smaller width than the upper and the lower faces?

“Always find out

EXPERIMENT No. 2

Experiment:—To determine Young's modulus (Y), modulus of rigidity (η), and Poisson's ratio (σ) of a material of a wire by Searle's apparatus.

Apparatus:—A thin wire of about 25 cm. length and 1 mm. diameter of the material whose Y , η and σ are to be determined, two inertia bars of rectangular or circular cross-section fitted with clamps and screws, a stop watch, a vernier callipers, thread, metre scale, weight box etc.

Description of the apparatus—A B and CD are two identical inertia bars of either circular or rectangular cross-section. The experimental wire whose elastic constants are to be determined is rigidly connected to their centres E and F by clamps. The bars are suspended by two torsionless vertical threads from a rigid support as shown in fig. (1). The bars remain parallel to each other and perpendicular to the axis of the wire.

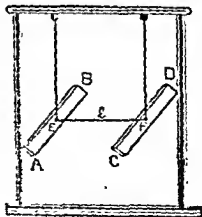


Fig. 1

Theory: If the ends A and C of the two bars are slightly pulled together through equal distances, the wire is bent in to the form of a

circular arc as shown in fig. 2. If the bars are released they start vibrating in a horizontal plane on account of a couple exerted on them by the wire and vice-versa.

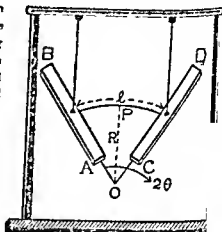


Fig. 2

$$M = \frac{YK}{R} \dots \dots \dots (i)$$

$$\text{and } R = \frac{l}{2\theta} \dots \dots \dots (ii) \text{ where } l$$

the length of the wire and θ is the angle through which each bar deflected from its mean position.

From eqns. (i) & (ii) we get.

$$M = \frac{YK 2\theta}{l}$$

$$\text{but } K = \frac{\pi r^4}{4} \text{ (where } r \text{ is the radius of the wire)}$$

$$\therefore M = \frac{Y\pi r^4}{2l} \theta$$

It produces an angular acceleration $\frac{d^2\theta}{dt^2}$ in each bar, and therefore, if I is the moment of inertia of any bar about a vertical axis passing through its centre of gravity, we have.

$$I \frac{d^2\theta}{dt^2} = \frac{Y\pi r^4}{2l} \theta$$

$$\text{or } \frac{d^2\theta}{dt^2} \propto \theta$$

Hence, as acceleration is \propto to displacement, motion is simple harmonic. If, T , is the periodic time of each bar it will be given by,

$$T_1 = 2\pi \sqrt{\frac{2Il}{Y\pi r^4}}$$

$$\text{or } Y = \frac{8\pi Il}{T_1^2 r^4} \dots \dots \dots (1)$$

If the bar is of rectangular cross-section,

$$I = M \left[\frac{a^3 + b^3}{12} \right] \dots (2) \quad \begin{array}{l} \text{[Where } M \text{ is the mass of the bar,} \\ a \text{ is the length of the bar,} \\ b \text{ is the breadth of the bar].} \end{array}$$

If the bar is of circular cross-section,

$$I = M \left[\frac{R^4}{12} + \frac{R^4}{4} \right] \dots (3) \quad \begin{array}{l} \text{[Where } M \text{ is the mass of the} \\ \text{bar } l \text{ is the length of the bar,} \\ R \text{ is the radius of the bar]} \end{array}$$

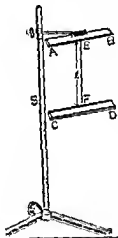


Fig 3

Now the suspension threads are removed and one of the bars is clamped horizontally to a rigid support, so that the other one is suspended vertically below it at the other end of the wire. The suspended bar is if turned in the horizontal plane twists the wire, on releasing, the bar executes simple harmonic torsional vibrations.

If T_2 is the periodic time of these oscillations, we have,

$$T_2 = 2\pi \sqrt{\frac{I}{C}}$$

Where C is the couple per unit twist set up in the wire. It is

$$C = \frac{\eta \pi r^4}{2l}, \text{ Where } \eta \text{ is the modulus of rigidity.}$$

$$\therefore \eta = \frac{8\pi Il}{T_2^2 r^4} \dots \dots \dots (4)$$

From eqns. 4 and 1 we get,

$$\frac{Y}{\eta} = \frac{T_1^2}{T_2^2}$$

$$\text{But Poisson's ratio } (\sigma) = \frac{Y}{\eta} - 1$$

$$\therefore \sigma = \frac{T_2^2}{2T_1^2} - 1$$

$$= \frac{T_2^2 - 2T_1^2}{2T_1^2} \dots\dots\dots(5)$$

Method.— To determine Y:

1. Take the experimental wire. Fix its one end to the middle point of one of the bars, and the other end to the middle point of another bar. By the help of two vertical threads suspend these bars from a rigid support as shown in fig. 1. The bars must remain horizontal.

2. By the help of a stand put a horizontal pointer in front of one of the bars. To attain better accuracy make a mark on the bar and put the pointer across the mark.

3. Bring slightly the two bars together as shown in fig. 2 and slip a loop of cotton thread over them so that they remain in the deflected position. The curvature of the wire should be very small otherwise the theory will fail.

4. Burn the thread. The bars will begin to oscillate. When the mark crosses the pointer start the stop watch. Determine time for 20, 25, and 30 oscillations. Determine time for the same number of oscillations at least twice. Then determine mean periodic time T_1 .

5. Determine I. C. of screw gauge, and find out the diameter of the wire at least at 8 different places with its help. Find mean diameter and thence the mean radius r .

6. By the help of a metre scale determine the length of the wire l .

7. Determine the length, breadth or thickness of each bar by the help of a scale and a vernier callipers. Weigh them separately in a balance, and calculate the moment of inertia of each bar by either formula (2) or (3). Hence calculate mean moment of inertia I .

8. Knowing T_1 , I , r and l calculate the value of Y by eqn. (1).

To determine η :

9. Clamp one of the bars horizontally to the rigid support as shown in fig. 3 so that the other bar remains suspended at the other end of the wire.

10. Put a mark on the suspended bar, and put a pointer across the mark.

11. Bring the suspended bar to rest at 3 o'clock position, and when left, the bar executes simple harmonic oscillation.

12. Start the stop watch when the mark is crossing the pointer, and determine time for 20, 25 and 30 oscillations. Determine time for the same number of oscillations at least twice. Then determine mean periodic time T_1 .

13. Find r , l , and I as discussed before.

14. Knowing T_1 , r , l , and I , calculate the value of η by formula (4).

To determine σ

15. Knowing the values of Y and η determine σ by formula (5).

Observations —

(1) Length of the wire \approx cm.

(2) Table for the diameter of the wire

L. C. = ... cm.

S.N.	Diameter along one direction (x)	Diameter along perpendicular direction (y)	Mean diameter $\left(\frac{x+y}{2}\right)$
1			
2			
3			
4			

Mean diameter \approx ... cm

„ radius (r) \approx ... cm.

(3) For Moment of inertia of the bar (I)

(i) Mass of the inertia bar (M) \approx ... gm.

(ii) Length of „ „ „ (l) \approx ... cm.

(iii) Breadth of „ „ „ (b) \approx ... cm.

(iv) Thickness of the „ (if it is circular) (D) \approx ... cm.

(4) Table for T_1 and T_2

Number of oscillations	Time taken				Time taken				Mean T_1	Mean T_2
	1	2	Mean	T_1	1	2	3	Mean	T_2	T_3
20										
25										
30										

Calculations —

First determine the moment of inertia of the bar I by the eqns.,

$$I = M \frac{(a^2 + b^2)}{12} \quad \text{[If rectangular cross section]}$$

$$= M \left(\frac{l^2}{12} + \frac{R^2}{4} \right) \quad \text{[If circular cross-section]}$$

2. Substitute the values of I , r , J , and T_1 in the equation;

$$Y = \frac{8 \pi I J}{T_1^2 \cdot 4} ; \text{ and determine } Y$$

3. Substitute the values of I , J , T_2 , and r in the equation,

$$\eta = \frac{8 \pi I J}{T_2^2 \cdot 4} ; \text{ and determine } \eta$$

4. Substitute the values of T_1 and T_2 in equation,

$$\sigma = \frac{T_1^2 - 2T_2^2}{2T_1^2} ; \text{ and determine } \sigma.$$

Result :—

$$Y = \dots \text{ dynes/cm}^2$$

$$\eta = \dots \text{ dynes/cm}^2$$

$$\sigma = \dots \dots$$

Precautions and sources of error.—

1. The radius of the wire should be very carefully determined as it occurs in the fourth power.

2. The amplitudes of oscillations while determining T_1 should be very small otherwise the formula will change and the wire will be strained beyond the elastic limit.

3. The bars should not toss up and down, their motion must be in the horizontal plane.

4. As the time periods occur in the second power they should be very carefully determined.

Criticism:—Generally for determining extension for the determination of Y long wire is needed, but in this case, we get good results even with a short length of the wire. This is an extremely fine method for determining σ because it does not entail the determination of Y and η . By simply determining T_1 and T_2 , σ can be independently determined. T_1 and T_2 can be determined very accurately whereas there remains always an appreciable error in the determination of the radius of the wire.

Oral questions:—

1. Define Y , η , and σ the elastic constants of a material. 2. What are their units and how are they related to each other? 3. What are the other

methods of determining them, and which are the best 4. What do you understand by elastic limit, stress and strain ? 5. Why the amplitude of the vibration of the rods should be kept small 6. Why the diameter of the wire should be measured so accurately ? 7. What are the forces acting on the rods when they are oscillating ? 8. Why the bars should not move up and down ? 9. Are the moments of inertia of the two bars equal, if not how the error is to be corrected ?

"Before you measure any quantity you must know the accuracy upto which it must be measured and hence choose the measuring instrument accordingly."

EXPERIMENT No. 3

Experiment:—To determine the moment of inertia (I) of a given body by the help of an inertia table using an auxiliary body of known moment of inertia.

Apparatus:—M. I. Table, an auxiliary body (a rectangle or a right cylinder), the given body whose moment of inertia is to be determined, stop watch, spirit level, a vernier callipers, weight box etc.

Description of the apparatus:—

It consists of an aluminium circular table T , carrying two vertical rods A and B of equal length. A cross-rod R along with the table is suspended by means of a long wire C , another end of which is fixed to another cross-rod D by means of a chuck. The rod D is fixed to the top of two vertical rods E and F standing on a heavy iron base G . The base rests on three levelling screws. There is a concentric groove cut on the table in which three levelling weights are placed. A mark is also made on the table to indicate its mean position. The table is so adjusted that the axis of suspension passes through its C. G. Some times a plumb line is provided at the bottom of also the table.

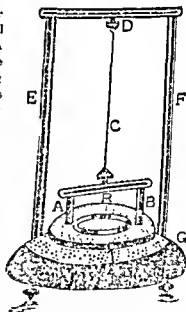


Fig 1

Theory:—When the table is given a slight rotation, it oscillates about the wire as an axis.

If T be the periodic time of torsional vibrations, I the moment of inertia of the table and C the couple per unit radian twist of the wire, then we have.

$$T = 2\pi \sqrt{\frac{I}{C}} \dots \dots \dots (1)$$

If T_1 is the time period when a body of known moment of inertia is placed on the table,

$$T_1 = 2\pi \sqrt{\frac{I + I_1}{C}} \dots \dots \dots (ii)$$

If T_2 is the time period when the given body of unknown moment of inertia I_2 is placed on the table,

$$T_2 = 2\pi \sqrt{\frac{I + I_2}{C}} \dots \dots \dots (iii)$$

From (i), (ii) and (iii) we get,

$$I_2 = \frac{T_2^2 - T_1^2}{T_1^2 - T_1^2} \times I_1 \dots \dots \dots (iv)$$

Where $I_1 = \frac{ML^2}{12} (L^2 + B^2)$ [If the body of known moment of inertia is a rectangle of sides L and B and mass M .]

$= \frac{Mr^2}{2}$ [If it is right cylinder of mass M and radius r .]

$= \frac{2}{5} Mr^2$ [If it is a sphere of mass M and radius r .]

Method :—1. Level the base with the help of a spirit level and levelling screws. The table should not touch the rods E or F. Put two spirit levels at right angles to each other on the table and level it. It should become perfectly horizontal. Done by adjusting the position of the levelling weights put in the table. The levelling can be tested by means of a plumb line also. The levelled axis of the wire will pass through the centre of the table.

See that the reference mark made on the table is in front of the vertical pin fixed in another stand in front of the mark so that it can be the reference point indicating mean position.

Slowly twist the table through a small angle in the horizontal plane. It begins to oscillate simple harmonically. When it has few oscillations and the mark is to cross the mean position, stop watch and find out the time for 20, 30, and 40 oscillations. The number of oscillations determine time at least twice. Calculate the mean periodic time T .

Now place the body of known moment of inertia (right cylinder) on the table and again level it. It should be placed so that the axis of the cylinder or the vertical line passing

Mean $T = \dots\dots\dots$ Sec. $T_1 = \dots\dots\dots$ Sec. $T_2 = \dots\dots\dots$ Sec.

Calculations:—

1. First of all determine the moment of inertia I_1 of the auxiliary body by the relations.

$$I_1 = \frac{MI^2}{12} (L^2 + B^2) \text{ [If rectangle]}$$

$$= \frac{MR^2}{2} \quad \text{[If cylinder]}$$

$$= \frac{2}{5} MR^2 \quad \text{[If solid sphere]}$$

$$\therefore I_1 = \dots\dots\dots \text{gm} \times \text{cm}^2$$

2. Substituting the values of I_1 , T , T_1 and T_2 in equation (iv) determine the value of I_2 .

Result:—

$$I_2 = \dots\dots\dots \text{gm} \times \text{cm}^2.$$

Precautions and sources of error:—

1. Before starting the experiment all the kinks present in the wire should be completely removed.

2. It is extremely important that the table should always remain perfectly horizontal so that it always oscillates about the axis of the wire and its moment of inertia may remain constant. Consequently once the balancing weights are adjusted their position should not in any case be altered.

3. Through out the performance of the experiment the C. G. of the system in all the three cases should lie on the axis of the wire about which the moment of inertia is to be determined.

4. The wire should not be twisted beyond the elastic limit.

5. The table should move in the horizontal plane only without tossing up or down.

6. The body whose moment of inertia is to be calculated must be of uniform density.

Criticism:—For increasing the accuracy in the determination of the periodic time, and decreasing percentage error, the wire should be of greater length and smaller radius. It will increase T , decreasing the percentage error. But smaller is the radius of the wire more will be the kinks present. Therefore, a compromise is made and generally a wire of 50 cm. length and 0.1 cm. radius is taken. As the load is increased or

decreased, the radius and the length of the wire varies, and therefore, the couple varies. It impairs the accuracy obtained. To obtain better results chronometers should be employed in place of stop-watches and oscillations should be watched through a telescope. The bodies taken of known and unknown moments of inertia should have moment of inertia comparable with that of the table, so that we might get appreciable difference between T , T_1 and T_2 . It is assumed that the oscillations are free and that air resistance is negligible. However, if possible, the table part should be enclosed in a box and be prevented from direct drift of wind.

Oral questions:—1. Explain moment of inertia of a body giving its physical significance. 2. Give the theorems regarding the moment of inertia. 3. Describe the moment of inertia table and explain why it is so called? 4. What type of oscillations the table performs? 5. What is the function of the balancing weights? 6. Why should not they be disturbed once adjusted? 7. What is the function of the concentric circles made on the table? 8. Why do you not take a very long wire of a very thin radius?

"Always remember it is not the result which you achieve is important; but the method which you employ. So always try to follow only the correct procedure".

EXPERIMENT No. 4

Experiment : To determine the modulus of rigidity (η) of a material in the form of a wire by dynamical method.

Apparatus :— A heavy cylindrical rod or a disc, a long wire of the material whose η is to be determined, an auxiliary body of known moment of inertia, a stop-watch, a screw gauge, a vernier callipers, a spirit level, a weight box, a meter scale etc.

Description of the apparatus:— In this case the experimental wire is taken, and its upper end is rigidly fixed. The lower end supports a heavy cylindrical rod or a disc (the wire is attached to the centre of the cylindrical body).

Theory :— If a rod or a wire is clamped at one end and twisted at the other by applying a couple about its axis and perpendicular to its length, it is said to be under tension. On account of the elasticity of the material, a restoring couple is generated in it. This restoring couple (C) is equal and opposite to the twisting couple. Let the length of the wire be l , its radius r , and coefficient of rigidity (η). If it is twisted through an angle of θ radians at the free end, the twisting couple C is given by the relation,

$$C = \frac{\eta \pi r^4}{2l} \theta, \dots \dots \dots (i)$$

$$\text{If } \theta = \text{unity, } C = \frac{\eta \pi r^4}{2l}, \dots \dots \dots (ii)$$

When the cylindrical rod is twisted in its own plane and released, it begins to execute simple harmonic torsional vibrations about the wire as an axis. If T_1 is the periodic time, it is given by the relation,

$$T_1 = 2\pi \sqrt{\frac{I_1}{C}} \dots \dots \dots (iii)$$

Where I_1 is the moment of inertia of the cylindrical body, and C is restoring couple per unit radian twist.

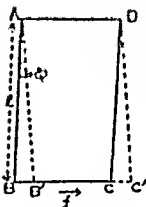
If now the auxiliary body is placed on the cylindrical rod, the new periodic time T_2 is given by the relation,

$$T_2 = 2\pi \sqrt{\frac{I_1 + I_2}{C}} \dots \dots \dots (iv)$$



Fig. 1

We use I_0 as the moment of inertia of P as a rotating body.



From fig. 2 (i) we get,

$$T_2^2 - T_1^2 = 4\pi^2 \frac{I_0}{g} \dots\dots\dots (i)$$

Substituting the value of C from (ii) in (i) we get

$$\begin{aligned} T_2^2 - T_1^2 &= 4\pi^2 \frac{I_0}{g \pi r^2 l} \\ &= \frac{4\pi^2 \cdot I_0 \cdot l}{g \pi r^2} = \frac{4\pi \cdot I_0 \cdot l}{g r^2} \end{aligned}$$

$$\text{or } g = \frac{4\pi \cdot I_0 \cdot l}{(T_2^2 - T_1^2) r^2} \dots\dots\dots (v)$$

Fig 2

Where $I_0 = \frac{MR^2}{2} \dots\dots\dots (vii)$ [If it is a solid cylindrical body of mass M and radius R].

$= MI \left(\frac{R_1^2 + R_2^2}{2} \right) \dots\dots\dots (viii)$ [If it is hollow cylindrical ring of mass M and external and internal radii R_1 and R_2].

Method :—To determine T_1 :—1. Take a long experimental wire. Clamp its upper end and suspend a heavy cylindrical body from its lower end as shown in fig. 3. The body suspended should remain perfectly horizontal which can be obtained by the help of a spirit level. The wire should pass through the centre of the body.

2. Mark a vertical line on the body which will serve as reference line. Put a pin in front of the line by a wooden stand.

3. Gently twist the cylindrical body and leave it so that it begins to oscillate simple harmonically in the horizontal plane. It should not toss up and down.

4. After the body has made a few oscillations and the reference mark is crossing the pin start the stop watch. Count the number of oscillations. Find time for 15 oscillations twice or thrice, and then determine time for one oscillation.

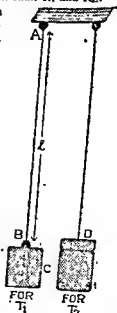


Fig 3.

5. Again find time for 10 oscillations twice or thrice and divide time for one oscillation. The mean of (4) & (5) is mean T_1 .

To determine T_2 :-

6. Put the auxiliary body on the cylindrical disc in such a way that again the axis of the wire passes through its centre. Oscillate system in the same way and determine time for 15 and 10 oscillations twice or thrice. Find mean periodic time. This gives T_2 .

7. Determine the length of the wire between its two ends with the help of a meter scale. It gives L .

8. Find L. C. of the screw gauge and determine the diameter of the wire at least at seven different places. Find mean diameter, thence the radius of the wire r .

9. Find the mass of the auxiliary body (ring) by the help of a balance. Determine its internal and external radii R_1 and R_2 with the help of vernier callipers.

Observations:-

[1] Length of the wire (l) cm.

[2] Table for radius of the wire.

L. C. = ... cm.

S. N.	Diameter along one direction	Diameter in mutually perpendicular direction	mean diameter (d)
1			
2			
3			
4			

Mean $r = \frac{d}{2} = \dots \text{cm.}$

[3] For moment of inertia of the auxiliary body:-

(i) Mass of the ring (M) = gm.

(ii) Internal radius (R_1) = cm.

(iii) External radius (R_2) = cm.

(iv) Radius (R) = ... cm.

(if it is a solid cylinder)

[4] Observation table for T_1 and T_2 .

S.N.	Number of oscillations	With only cylindrical body				T_1	With the auxiliary ring placed on the body				T_2
		1	2	3	Mean		1	2	3	Mean	
1	15										
2	20										

Mean $T_1 = \dots$ Sec.Mean $T_2 = \dots$ Sec.

Calculations :—

1. Calculate the moment of inertia of the ring (I_2) by the formulae (vii) or (viii).

2. Substitute the value of T_1 , T_2 , l , r , and I_2 in formula (vi) and calculate η by using log tables.

Result :—Modulus of rigidity of the material (η) = dynes/cm².

Precautions and sources of error :—

1. There should not be any kinks in the wire, and it should be quite long and thin.

2. The axis of the wire must always pass through the C. G. of the cylindrical body.

3. The body should simply rotate in the horizontal plane and should not move up and down.

4. The wire should not be twisted beyond the elastic limit otherwise the restoring couple C will not remain \propto to the angle of twist.

5. The time periods T_1 and T_2 should be measured very accurately as they occur in second power.

6. As the radius is to be raised to the fourth power, a very small error in its determination will make an appreciable error in the result. Hence, it should be measured very accurately and at number of different places.

7. The density of the auxiliary body should be uniform throughout, otherwise there will be an error in the determination of I_2 .

8. It is assumed here that (C) the restoring couple per unit twist remains constant throughout the experiment, but it is not rigorously true, because when the load is changed the radius of the wire changes, altering the couple C . It causes some error.

9. The moment of inertia of the auxiliary body is calculated from its geometrical dimensions on the assumption that the density is uniform through out, which is not true in most of the cases. These errors can be removed by employing Maxwell's needles.

Criticism :--See expt. "M. I. Table".

Oral questions :--

1. Explain rigidity, and describe a torsional pendulum. 2. Explain the principle of this experiment. 3. What are the factors upon which the periodic time depends? 4. If the length is doubled how will the periodic time change? 5. Will you prefer a thick wire or a thin wire? 6. Which is the most important quantity to be determined in this experiment? 7. Does the value of η calculated by statical method agree with the result obtained by this method? 8. See, experiment on moment of inertia.

EXPERIMENT No 5

Experiment —To determine the modulus of rigidity (η) of a metal in the form of a rod by statical method (using a horizontal type twist apparatus).

Apparatus —Horizontal type apparatus, half kilo-grm. weights (new 12 to 14), a meter scale, a vernier callipers and a screw gauge.

Description of the apparatus:—

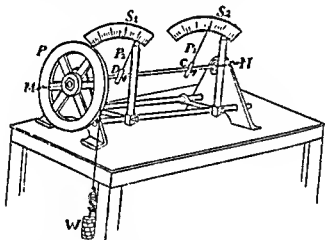


Fig. 1

One end N of the experimental rod is firmly clamped in a block fixed in a frame. The other end is attached to a steel axle of a large pulley P as shown in the figure. A cord is wound round the rim of the pulley. The free end of the cord carries a hanger in which weights can be put. By putting the weights load is applied resulting in a couple on the rod. The rod gets twisted. P_1 and P_2 are two pointers fixed at two adjustable points C and D on the rod. The pointers move over two graduated scales S_1 and S_2 fixed in the frame. The scales are calibrated in degrees. The pointers directly give the twist produced at these two points.

Theory :—If R is the radius of the pulley, M the mass suspended, and g the acceleration due to gravity, the couple acting on the rod is given by,

$$\text{Couple} = MgR \dots\dots\dots (i)$$

This couple is balanced by the couple due to torsional reaction in the rod, which is given by,

$$\frac{\eta \pi r^4}{2l} (\theta_2 - \theta_1) \dots\dots\dots (ii)$$

Where r is the radius of the rod, l is the length between C and D where the pointers are situated. θ_2 and θ_1 are the twists produced in radians at the points D and C.

Equating (i) and (ii) we get

$$\frac{\eta \pi r^4}{2l} (\theta_2 - \theta_1) = MgR$$

$$\text{or } \eta = \frac{2 M g R l}{\pi r^4 (\theta_2 - \theta_1)}$$

If the angles are measured in degrees the relation will become,

$$\eta = \frac{360 M g R l}{\pi^2 r^4 (\theta_2 - \theta_1)} \dots\dots\dots (iii)$$

Note :—In some types of apparatus pointers are not provided, only there is one vernier fixed to the pulley. In such cases l is the length of the rod fixed between the pulley and the block. Instead of $(\theta_2 - \theta_1)$, only one angle of twist θ is to be determined by the vernier fixed on the pulley and the relation becomes,

$$\eta = \frac{360 M g R l}{\pi^2 r^4 \theta} \dots\dots\dots (iv)$$

Method :—1. Firmly clamp the end N of the rod in the block attached to the frame. During the experiment this end of the rod should not move in the clamp.

2. Wind a thread round the pulley and suspend a pan at its free end. The thread must remain tangential to the pulley.

3. Fix the two pointers at two points, say C and D along the length of the rod. Adjust the positions of the pointers on the circular scales such that they read zero. Note down the positions of these two pointers P_1 and P_2 on the circular scales. This gives zero reading.

8. Find the value of θ_1 for a load of 2 kg. from the graph. (Note: The value of θ_1 is the angle of twist for a load of 2 kg. from the graph. The value of θ_1 is the angle of twist for a load of 2 kg. from the graph.)

9. Find the value of θ_2 for a load of 2 kg. from the graph. (Note: The value of θ_2 is the angle of twist for a load of 2 kg. from the graph. The value of θ_2 is the angle of twist for a load of 2 kg. from the graph.)

10. Find the value of θ_1 for a load of 2 kg. from the graph. (Note: The value of θ_1 is the angle of twist for a load of 2 kg. from the graph. The value of θ_1 is the angle of twist for a load of 2 kg. from the graph.)

11. Find the value of θ_2 for a load of 2 kg. from the graph. (Note: The value of θ_2 is the angle of twist for a load of 2 kg. from the graph. The value of θ_2 is the angle of twist for a load of 2 kg. from the graph.)

12. Find the value of θ_1 for a load of 2 kg. from the graph. (Note: The value of θ_1 is the angle of twist for a load of 2 kg. from the graph. The value of θ_1 is the angle of twist for a load of 2 kg. from the graph.)

13. Find the value of θ_2 for a load of 2 kg. from the graph. (Note: The value of θ_2 is the angle of twist for a load of 2 kg. from the graph. The value of θ_2 is the angle of twist for a load of 2 kg. from the graph.)

14. Find the value of θ_1 for a load of 2 kg. from the graph. (Note: The value of θ_1 is the angle of twist for a load of 2 kg. from the graph. The value of θ_1 is the angle of twist for a load of 2 kg. from the graph.)

15. Find the value of θ_2 for a load of 2 kg. from the graph. (Note: The value of θ_2 is the angle of twist for a load of 2 kg. from the graph. The value of θ_2 is the angle of twist for a load of 2 kg. from the graph.)

16. Find the value of θ_1 for a load of 2 kg. from the graph. (Note: The value of θ_1 is the angle of twist for a load of 2 kg. from the graph. The value of θ_1 is the angle of twist for a load of 2 kg. from the graph.)

17. Find the value of θ_2 for a load of 2 kg. from the graph. (Note: The value of θ_2 is the angle of twist for a load of 2 kg. from the graph. The value of θ_2 is the angle of twist for a load of 2 kg. from the graph.)

Note—As described in theory where there is only one pointer, measure length from the fixed end to the position of this pointer. This will give l the length of the rod. Determine the angle of twist θ_1 in the same way. Instead of $\theta_1 - \theta_2$, we shall get only θ_1 . Determine θ_1 for a load of 2 kgm. in a similar way.

Observations—

(1) For the diameter of the rod:—

L. C. of the screw gauge = cm.

S. N.	Diameter in one direction.	Diameter in perpendicular direction.	Mean diameter d
1			
2			
3			
4			

Mean diameter (d) = cm.Mean Radius $r = d/2 =$ cm.

(2) V. C. of the callipers = cm.

Length of the rod between the two pointers = cm.

or between the fixed end and the pulley (l) = .. cm.

(3) For the diameter of the pulley

(i) cm., (ii) cm.

(iii) cm., (iv) cm.

Mean diameter (D) = cm.„ Radius (R) = cm.(4) Observation table for ($\theta_2 - \theta_1$) in degrees

Load in kilogram. placed on the pan	Reading of pointer P_1 in degree (θ_1)			Reading of pointer P_2 in degree (θ_2)			$\theta_2 - \theta_1$	θ_2, θ_1 for 2 k. gm.	Mean $\theta_2 - \theta_1$ for 2k.gm.
	Load	Load	Mean	Load	Load	Mean			
	increasing	decreasing		increasing	decreasing				
0	—	—	—	—	—	—	—		
$\frac{1}{4}$	—	—	—	—	—	—	—		
1	—	—	—	—	—	—	—		
$1\frac{1}{4}$	—	—	—	—	—	—	—	(5.1)	
2	—	—	—	—	—	—	—	\approx	
$2\frac{1}{4}$	—	—	—	—	—	—	—	(6.2)	
3	—	—	—	—	—	—	—	\approx	
$3\frac{1}{4}$	—	—	—	—	—	—	—	(7.3)	
4	—	—	—	—	—	—	—	\approx	
$4\frac{1}{4}$	—	—	—	—	—	—	—	(8.7)	
5	—	—	—	—	—	—	—	\approx	

 \therefore Mean ($\theta_2 - \theta_1$) for 2 k. gm. degrees.

$$\therefore \frac{\Delta l}{\theta_2 - \theta_1} =$$

Calculations:—

Knowing $(\theta_2 - \theta_1)$, l , R , r , g , and M calculate η by the formula.

$$\eta = \frac{360 Mg R l}{\pi^2 r^4 (\theta_2 - \theta_1)}$$

Result:—

$$\eta = \dots\dots \text{dynes/cm}^2.$$

Precautions and Sources of error:—

1. The vertical portion of the string should always be tangential to the pulley.
2. The shear should not exceed the elastic limits otherwise Hooke's law will not hold good.
3. The rod should be firmly clamped in the block fixed in the frame.
4. As the radius of the rod occurs in the fourth power it should be determined very accurately.
5. The weights should be placed and removed gently.
6. If the axle is not mounted exactly at the centre of the pulley, an error may be introduced. This is eliminated by twisting the rod in both the directions of the pulley.
7. If the thread or the string possesses an appreciable diameter, its radius should be added to the radius of the pulley to get the exact value of R .
8. Always there is present a great error in the determination of the angle of twist and radius of the specimen wire. In order to eliminate it a graph should be drawn between load and θ i. e. $(\theta_2 - \theta_1)$, and then mean value of $\frac{M}{\theta}$ should be found from the graph. This will very much reduce the percentage error in the determination of θ .

modifications:—1. To prove that the angle of twist of a given length of a cylindrical rod is directly proportional to the applied couple.

Hint—1. If this is to be true M should be directly proportional to θ the angle of twist for the same length of the rod.

2. Therefore, plot a graph between the load M and the twist θ (i. e. $\theta = \theta_1 - \theta_2$, in this case) when l is kept constant.

3. It comes out to be a straight line proving the contention stated above. It is as shown in fig (2).

4. The slope of this curve will give mean $\frac{\theta}{M}$ which when substituted in the formula (iii) or (iv) will give η .

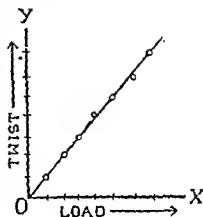


Fig. 2

Modification 2. The angle of twist due to a given couple is proportional to the length of the rod twisted.

Hint:— 1. Take different lengths of the rod, and determine corresponding values of θ and M . Plot graphs for each length. They will be straight lines passing through the origin.

2. Determine $\frac{\theta}{m}$ for each length from the graph.

3. Now plot a new graph between the corresponding values of $\frac{\theta}{m}$ and l . It will come out to be a straight line as shown in fig. 3.

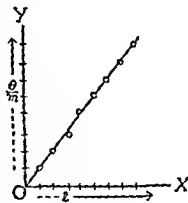


Fig. 3

Criticism:— The graph obtained in this case is almost a straight line. The minor irregularities noticed are (i) due to the non uniformity of the material of the bar, (ii) due to the slight eccentricity of the axis of the rod with respect to the centre of the circular scale.

If longer length of the rod is taken nonuniformity will increase. On the other hand if length employed is smaller the lower will be the value of twist produced. Therefore a compromise is sought and a

of nearly 31 cm. length is used. Similarly the error in the pulley is the same for every turn, but the error due to eccentricity increases. The pulley in the pulley block is the error due to eccentricity. Hence also therefore a large mass is required.

To eliminate the error due to eccentricity double pulley points on both sides of the circular wire may be employed. In that case the circular wire should be a complete circle. The mass of the pulley on the two sides will eliminate the error.

As there is only one pulley only a single force is applied to the end of the rod. This produces a side pull on the rod, resulting in friction between the rod and the bearings. Hence it greatly impedes the free twisting of the rod.

Oral questions—

1. Explain method of rigidity ? 2. How is the rod twisted and the couple applied ? 3. Why one end of the rod is fixed ? 4. Why the thread or the spring should remain tangential to the pulley ? 5. Explain the error due to eccentricity of the axis of rod and show how it is removed ? 6. Why the weights should be placed and removed gently ? 7. What is the maximum load that you can apply ? 8. Why the readings should be taken by winding the string on both the sides of the pulley ? 9. Why the rod in this method should not be very thin ? 10. Why do you not take an extremely long or extremely short length of the wire ?

EXPERIMENT No. 6

Experiment :—To determine η of a rod by statical method (using a vertical type twisting apparatus).

Apparatus :— Vertical type Barton's apparatus, See the previous experiment,

Description of the apparatus :—One end O of the experimental wire OD whose coefficient of rigidity is to be determined, is rigidly clamped to a rigid support as shown in fig. 1. The other end of the wire carries a heavy metallic cylinder C attached to it.

Two cords are wound round the cylinder C moving in the opposite direction² passing over the two pulleys KK'. The pulleys carry pans in which the weights can be put. The pulleys are identical and of the same weight. A long pointer with two ends is attached to the wire which moves over a circular scale calibrated in degrees. The whole system rests on a heavy frame supported on levelling screws.

Theory :—When equal weights are placed on the pulleys, they constitute a couple and rotate the cylinder C. Therefore, the wire is twisted, which can be read on the circular scale.

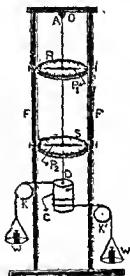


Fig 1

If D is the diameter of the cylinder, M the mass put on the pan, and g the acceleration due to gravity, the moment of the couple acting on the cylinder and the wire is given by.

$$\text{Couple} = M g D.$$

This is balanced by the couple due to torsional reaction in the wire which is given by.

$$\frac{\pi D r^4}{32} \theta.$$

Where r is the radius of the wire, l is the length of the wire from the point it is suspended, to the point at which it is clamped to the cylinder, and θ is the angle of twist in radians.

EXPERIMENT No 7

Experiment:—To determine the surface tension of water by Jaeger's method.

Apparatus:—Jaeger's apparatus, a thin glass tube drawn at its one end in the form of a fine capillary, a scale, a thermometer, a microscope etc.

Description of the apparatus:—It consists of a long thin glass tube with its lower end drawn into a fine capillary of about 0.2 to 0.5 mm diameter. The tip of the capillary is perfectly smooth and cut off square. The surface should be perpendicular to the axis of the tube. Even when seen through the microscope the edges of the tube should not indicate any trace of roughness or raggedness. The tube is fixed

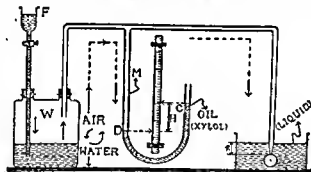


Fig. 1

vertically so that it dips in water (whose surface tension is to be determined) contained in a beaker. About 4 to 5 cm. of its length is kept in side water. This tube is then connected to a manometer M and also to a Woulff's bottle W. The bottle carries a dropping funnel with a stop cock or a burette tube. The funnel and part of the bottle are filled with pure water. Xylol (a liquid hydrocarbon) is used as a liquid in the manometer instead of water, as it has smaller density.

Theory:—When the capillary is dipped in water some water rises in it due to capillary action. The shape of its meniscus is nearly hemispherical. When water is dropped from the funnel in the bottle, the air in the bottle is displaced into the capillary tube. This displaced air is forced into the capillary tube and the surface of the

liquid in the capillary tube is pressed downwards. The level of liquid goes on sinking lower and lower as the pressure is increased. Finally the liquid level reaches the end and a bubble of air is produced into the liquid. As the pressure increases the radius of the bubble decreases until it acquires a minimum value. At this stage the bubble acquires more or less hemispherical shape with a radius equal to that of the aperture at the end. Let it be r . Now the bubble becomes unstable because any further growth of the bubble increases its radius decreasing the internal pressure. As the external pressure is constant, equilibrium is destroyed and the bubble breaks away. Hence just before the bubble gets detached, the pressure inside is maximum and is registered by the manometer M .

When the bubble breaks away the pressure inside it is equal to $P + H\ell g$, where P is the atmospheric pressure, H is the maximum difference of level of manometer liquid in two limbs, ℓ is the density of the manometer liquid and g is the acceleration due to gravity. The pressure outside the bubble $= P + h d g$, where h is the depth of the tube from the surface of water in the beaker and d is the density of water.

Thus, the excess pressure inside the bubble

$$\begin{aligned} &= (P + H\ell g) - (P + h d g) \\ &= g(H\ell - h d). \end{aligned}$$

But from the theory of surface tension, the excess pressure $= 2T/r$, where T is the surface tension of water.

$$\therefore \frac{2T}{r} = g(H\ell - h d)$$

$$\text{or } T = \frac{r g}{2} (H\ell - h d) \dots \dots \dots (1)$$

Knowing all these things T can be determined.

Method:—1. Take the tube clean it and clamp it in a vertical position as shown in the figure. The capillary should remain dipping in water upto a depth of nearly 3 to 4 cm. A scratch is then made on the capillary and the level of water in the beaker is so adjusted that the scratch coincides with the level.

2. Connect the tube to the manometer M and Woulff's bottle W with the help of rubber tubing. Make the joints air tight by putting wax etc.

3. Fill part of the bottle and the funnel with water and xylol in the manometer limbs.

4. By opening the stop cock of the funnel blow air inside the tube so that the bubble is formed. The flow of water should be adjusted that bubble is formed after every ten seconds (i. e. at the rate of 6 per minute). When the bubble breaks away, the pressure becomes maximum and then suddenly falls.

5. Note down the maximum pressure when the bubble is just detached with the help of the manometer M. Read the levels of liquid at C and D in the manometer at that time. Difference between C and D will give the maximum difference H . Repeat this process a number of times to get various readings of H . Then determine mean H .

6. Now by pouring or taking out liquid from the beaker change the depth (h) of the tip of the capillary from the surface of the liquid (another scratch is to be made). Repeat the same procedure to determine H . Take at least three different sets with different depths.

7. The levels C and D in the manometer are to be determined with microscope if more accuracy is required. First focus the microscope at C and then at D. The difference will give the value of H .

8. Remove the capillary and clamp it in a horizontal position. Focus a microscope on its orifice. Coincide its crosswires with one of the inner edges and then on the inner edge of the other side. The difference will give the diameter of the tube. Rotate the tube at right angles to the previous position and again determine the diameter. Take a number of such readings, and then determine mean diameter d . Half of it will be the radius (r).

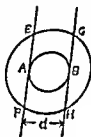


Fig. 2

9. Measure the distance between the tip of the capillary and the corresponding scratches by the help of a scale. It will give the value of h . At least three different sets should be taken after changing h .

10. Calculate surface tension (T) for each set of observation and then determine the mean value of T .

11. With the help of a good thermometer note down the temperature of the liquid.

Observations :—

[1] Table for the measurement of h and H .

S. N.	Value of h in cm. (a)	Reading of the manometer		Mean H in cm.
		upper level (b)	lower level (c) H (b-c)	
1				
2				
3				

[2] Table for the diameter of the capillary

Least count of the microscope = . . . cm.

S. N.	Diameter in one direction		Diameter in mutually perpendicular directions		Mean diameter d
	Reading on outside	Reading on other side Diameter	Reading on one side Diameter	Reading on other side Diameter	
1					
2					
3					

Mean Diameter = cm.

Mean radius (r) = $\frac{d}{2}$ = cm.

[3] (i) Temperature of water = °C.

(ii) density of manometric liquid (ρ) = gm/cm³

(iii) density of water (d) = 1 (in this case).

Calculations —

Calculate surface tension for each observation by the formula.

$$\gamma = \frac{r \rho}{2} (H_1^2 - H_2^2)$$

Calculation table

S. No.	h	H	He	hd	He—	g	$T = \frac{rg}{2} (H^2 - h^2)$
1							
2							
3							

Mean $T =$ Result:—Surface tension of water,
(T) = dynes per cm. at °C.

Precautions and sources of error:—1. The capillary tube should be perfectly clean, i. e. it should not have any traces of grease etc., otherwise it will contaminate water altering the surface tension.

2. There should be no leakage in the apparatus otherwise theory will not rigidly apply. Therefore, the apparatus should be in one piece and rubber joints should be avoided as far as possible.

3. The open end of the manometer should be drawn in the form of a capillary to damp the oscillations of the liquid in it.

4. The bore of the capillary taken should be small i. e. about 2 to 3 mm. If the bore is not smaller, the bubble will not be hemispherical when it is detached from the orifice of the capillary.

5. As the diameter is quite small, it should be very accurately measured after taking several readings for it.

6. The bubbles should be formed slowly, and singly i. e. two bubbles should not emerge together. Some time must elapse before the other bubble is formed. If it is not so, the maximum pressure will not remain independent of the rate of bubble formation. These conditions are satisfied if the air space in the bottle is reduced, and flow of water from the funnel is properly regulated.

7. It is very important to note the temperature of water, because surface tension changes with temperature.

Modification.—To Determine surface tension of water at various temperatures

Hint:—A beaker with a thermometer is placed in the tank, and is determined at various temperatures as described above. A graph is then drawn between surface tension and temperature. Surface tension increases with temperature.

Criticism of the apparatus :—This is quite a good method determining surface tension of liquids. It is specially suitable for studying the variation of surface tension with temperature. As the bubble is formed within the liquid surface the temperature can be easily controlled. When a graph is drawn between surface tension and temperature, the slope of it can be used to study the molecular aggregation of the liquid (i.e. the number of atoms in a molecule).

The danger of contamination of the liquid surface is minimised in this case. As the capillary is thin, it can be easily cleaned reducing the possibility of contamination. It increases percentage accuracy.

This method can be employed for determining the surface tension of molten metals.

It is also suitable for studying the variation of surface tension of a solution, with different concentrations of the solute.

As we have to measure the diameter of the capillary only at the orifice, the non-uniformity of the bore does not cause any error.

Despite all these advantages discussed above, there is no certainty about the radius of the bubble when it breaks away. It may not be hemispherical and the same as that of the orifice. The bubble is hemispherical only when very narrow capillaries are used. However, the radius of the bubble has been found to be a function of the radius of the aperture. Therefore, for greater accuracy the following formula is used.

$$T = \frac{rR}{2} \left[H \rho - d \left(k + \frac{2r}{3} \right) \right]$$

Oral Questions :—1. Explain the principle underlying this method. 2. Explain whether the excess pressure inside the bubble depends upon the depth of the orifice below the surface of the liquid. 3. What liquid is used in a manometer and why? 4. When the bubble breaks is its radius exactly equal to the radius of the orifice? If not, what corrections should be made? 5. Why maximum pressure is noted? 6. What should be the convenient rate of formation of bubbles? 7. Is this method superior to that of capillary rise? If what are the merits? 8. How does surface tension change with temperature?

EXPERIMENT No. 8

Experiment :—To determine the surface tension of water by capillary tube.

Apparatus :—Glass tube for drawing capillary tubes, or ready-made capillary tubes of uniform bore, a glass plate, a pin, wax, microscope, beaker, stand etc.

Theory:—If a capillary tube of small radius is dipped in liquid, liquid rises in it on account of surface tension. The meniscus of the liquid is concave upwards as at P. The meniscus is in contact with a tube of length $2\pi r$, if r is the radius of the tube at P. If T is the surface tension of the liquid, the force exerted by the meniscus on the tube is equal to $2\pi rT$ in the direction of the arrow, where θ is the angle of contact. As action is equal to reaction the tube will exert force on the liquid, and the liquid will rise up. The horizontal components of this force will cancel out and the vertical components will be equal to $2\pi r T \cos \theta$.

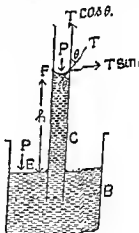


Fig. 1

If h is the height to which the water rises, the volume of water in the tube up to the meniscus

$$\begin{aligned} &= \pi r^2 h + \text{volume of meniscus} = \pi r^2 h + \pi r^3 - \frac{2}{3} \pi r^3 \\ &= \pi r^2 h + \frac{\pi r^3}{3} = \pi r^2 \left(h + \frac{r}{3} \right) \end{aligned}$$

Weight of this liquid column will be,

$$\pi r^2 \left(h + \frac{r}{3} \right) dg, \text{ where}$$

d is the density of liquid (for water $d = 1 \text{ gm/cc.}$)

The water will rise till the upward force due to tension is balanced by the downward force of gravity.

$$\therefore 2\pi rT \cos \theta = \pi r^2 \left(h + \frac{r}{3} \right) \rho g \quad \dots (b)$$

$$\text{or } T = \frac{r \left(h + \frac{r}{3} \right) \rho g}{2 \cos \theta}$$

For water $\theta = 0$ and $\cos \theta = 1$

$$\therefore T = \frac{r \left(h + \frac{r}{3} \right) \rho g}{2} \quad \dots (n)$$

$= \frac{r h \rho g}{2} \dots (iii)$ where $\frac{r^2}{6}$ may be neglected as r is extremely small.

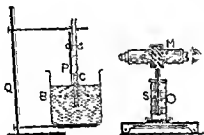


Fig. 2

Method-1. Take two or three glass tubes. Clean them first by soda and then by sulphuric acid and nitric acid. Rinse

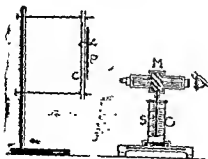


Fig. 3

with tap water and dry. Heat one of them in a Bunsen flame,

and draw three or four capillary tubes of uniform bore (r = from 0.1 to 0.2 mm.). If prepared capillary tubes are provided, wash them as explained above.

To determine h :—2. Take a thin clean glass plate. Fix one of the capillary tubes along the length of the plate by wax or by rubber bands. Also attach a pin P at the bottom of the plate so that it remains parallel to the capillary tube as shown in the figure.

3. By the help of a stand, put the plate just above a beaker filled with uncontaminated tap water, in such a way that the capillary tube dips in water, and the pin head is just above the level of water in the beaker. Care should be taken to see that the capillary tube is perfectly vertical. The pin head will give the level of water in the beaker. Due to surface tension water will rise up in the tube.

4. Take a microscope and determine its L. C. Put it in such way that its scale is vertical while its tube is horizontal. Focus its eye piece on the crosswires. Now put its objective in front of the pin head, and see the inverted image of the pin head. Adjust it in such a way that its horizontal crosswire just touches the pin head. Take the reading on the microscope scale. It corresponds to the level of water in the beaker.

5. Raise the microscope tube along the scale without bodily displacing it and now focus it on the meniscus of water in the capillary tube. An inverted image of the meniscus will be seen. Adjust it in such a way that the horizontal crosswire is tangential to the lowest portion of the meniscus. Take the reading on the microscope scale.

6. Difference between the two readings (4) and (5) will give the height through which water has risen in the tube. Repeat this process at least twice and then determine mean height h .

7. If the capillary drawn is of such a small bore that the capillary rise is greater than 5 cm., it is not necessary to determine it with the help of a microscope. Instead, the capillary tube may be fixed against a glass scale graduated in to half millimeters. The capillary rise can be directly measured on the scale.

To determine r :—8. Make a mark at the meniscus of water in the tube. Remove the capillary tube. By means of a strip fix the plate at the mark. Hold the beaker to the tube and in a sharp stroke draw the capillary tube out from it. The capillary tube will be longer by the rise which has taken place when it is in contact with water.

of the tube is to be determined at the place of the water meniscus. See fig. 3.

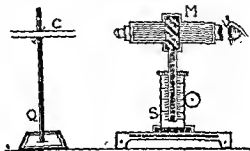


Fig. 3

9. To find out the internal diameter of the capillary tube, adjust the microscope so that its vertical crosswire is tangential to the hand side of the inner circumference of the capillary tube. Take the reading of the position of the microscope tube, on the scale which it is travelling. Move the tube horizontally so that now the vertical crosswire is tangential to the right hand side of the inner circumference. Again take reading on the microscope scale. The difference between these two readings will give the internal diameter of tube. Turn the tube in its position by a right angle, and again determine the diameter similarly. The mean of these two readings will give the internal diameter. For accuracy one or two more sets of observations may be taken. Calculate radius from this reading.

10. Replace this capillary tube by another one of a different bore. Similarly determine the height of water risen, and the radius of the tube. The process should be repeated at least with three or four capillary tubes of different bores.

11. Knowing h and r for every tube, find the product $h \cdot r$ for each observation, and determine mean of $h \cdot r$. Then with the formula (ii) calculate surface tension T .

12. Determine the temperature of water in the beaker with thermometer reading up to $\frac{1}{2}^{\circ}\text{C}$ and note it. (It is because surface tension varies with temperature).

Observations :—

Temperature of water = $^{\circ}\text{C}$.

[1] Table for capillary rise (h)

No. of tube	Reading of Microscope		Difference ($b-a$) h
	At Level of water (a)	At the upper meniscus (b)	
1			
2			
3			

[2] Table for radius of the capillary.

S.N.	Diameter in one direction			Diameter in mutually perpendicular direction			Mean Diameter
	Reading on L.H.S.	Reading on R.H.S.	Diameter	Reading on L.H.S.	Reading on R.H.S.	Diameter	
1							
2							

Mean diameter $d = \dots$ cm." Radius $r = d/2 = \dots$ cm.

Calculations :—

S.N.	r in cm.	h in cm.	rh	Mean rh	$T = \frac{hr\gamma}{2}$
1					
2					
3					
4					

result :— $T = \dots$ dyns per cm. at $^{\circ}\text{C}$.

Precautions & Sources of error :—

1. The capillary tube should be kept perfectly vertical, otherwise there will be an error in the measurement of h .

2. The water, beaker, and the capillary tube must be clean. They should not be contaminated with grease or oil. If they are contaminated, surface tension will change and the liquid will not rise to the proper height. As this mistake is mostly committed, accuracy is the aim, this point should be clearly born in mind while doing the experiment. Do not use distilled water as it is likely to contain grease. If the water is not contaminated, water will drop in beaker when the tube is removed.

3. The top of the tube should be kept open. It should not get blocked by wax etc.

4. Mind it that the radius of the tube is to be determined at the place where the level of water stood in the tube. That is why it is broken from that place. The bore should be uniform, otherwise if the radius is determined some what above or below that point, it will cause an error in the determination of r . The uniformity of the bore can be ascertained by introducing a pellet of mercury inside the tube. Measure the length of the thread at different places. If the length comes out to be the same, the bore is uniform.

5. Determine the diameter of the tube at least in two perpendicular directions. While determining it try to avoid the back lash error.

6. Do not forget to note down the temperature of water otherwise the result will be meaning less.

7. The bore of the capillary should be fine otherwise h will be smaller.

8. To make the angle of contact zero, it is better to wet the tube a little above also.

Criticism :—This method gives fairly good results. It is only applicable in the cases where the angle of contact is zero. Otherwise, the value of T will be unreliable because the angle of contact is always uncertain. If the liquid is contaminated the angle of contact will change altering the value of surface tension.

If the capillary taken is of uniform bore the radius can be accurately determined by introducing a pellet of mercury inside the tube, and measuring its length and mass. If l is the length, m is the mass and r is the internal diameter of the tube, the volume of mercury thread will be $=\pi r^2 l$, if d is its density, $m = \pi r^2 l d$.

$$\text{or } r = \sqrt{\frac{m}{\pi l d}}$$

But it is extremely difficult to obtain a tube of perfectly uniform bore. Thus, the radius of the tube at the meniscus cannot be determined with a high degree of accuracy. Furthermore, often the contamination of water takes place and the students fail to obtain correct values.

If it is possible to cut the bore at the end up to which water rises, then uniformity of the tube is not important. As such, students

As capillary rise is very large, it is not necessary to measure it correctly up to third place of decimal with a microscope, though usually it is measured with a microscope.

Contamination of water surface with any metallic contact should be avoided. Instead of a metallic pin it is better we use a glass style.

Or 1 Questions :—

What do you understand by surface tension, and how does it arise ? Give its units. 2. How does surface tension differ from elastic forces ? what is the difference between a stretched rubber sheet and a liquid surface ? 3. Why the liquid rises in a tube. 4. Define the angle of contact ? When is the meniscus concave or convex and why ? What is the value of angle of contact in case of (a) water and glass (b) mercury and glass. 5. Why the capillary tubes of fine bores are taken ? What is the difference in pressure just on two sides of the meniscus ? 7. Will height h change if more of the tube is pushed in the liquid ? How does T varies with temperature ? 8. Why are globules of mercury spherical ? 10. Why is it difficult to introduce mercury in a fine thermometrical capillary tube ? 11. Why does oil spread over the surface of a liquid ? 12. Do you know any other methods of determining surface tension ? Which is the best ?

EXPERIMENT No. 9

Experiment:—To determine the coefficient of viscosity (η) of π , determining the rate of flow through a capillary tube by Poiseur method, at room temperature.

Apparatus:—A capillary tube, viscosity apparatus, two constant baths, a graduated cylinder, stop-watch, a thermometer, weight etc.

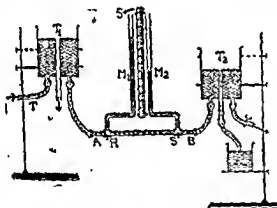


Fig. 1

Description of the apparatus:—T, is a constant level bath carried on a stand. It can be raised up or lowered down. Its inlet tube is connected to the tap, while the central constant level tube is connected to a sink. The outlet tube is connected to a long capillary tube AB above through a glass T with the help of rubber tubing. The end B of the capillary tube is also connected through a T piece to a constant level bath T₂ as shown in the figure. The outlet of T₂ is closed by wax, and water is collected in a beaker from the constant level tube. M₁ and M₂ are the two limbs of a manometer. The limbs of the manometer are arranged over two fine holes in the capillary tube through T pieces. A scale S is provided between the two limbs of the manometer to read the levels of water.

in them. The difference in the levels of water in the two limbs directly gives the difference of pressure between the two ends of the capillary tube AB. The tube AB remains perfectly horizontal.

At some places a simpler apparatus as shown in Fig. 2 is used.

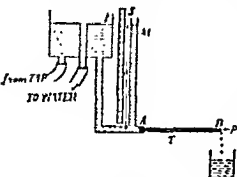


Fig. 2

coincides with the axis of the tube AB. The end B is open, and below it is placed a beaker, in which water can be collected.

Theory:—When a liquid is allowed to flow through a narrow tube it opposes the relative motion between its different layers on account of viscosity. Therefore, to maintain steady flow of the liquid some pressure is needed. If V is the volume of water in c.c. flowing per sec., then by Poiseuille's equation it is given by,

$$V = \frac{P\pi a^4}{8\eta l} \dots\dots\dots (i)$$

Where P is the pressure difference between the ends of the capillary tube AB in dynes, a the radius of the tube in cm., l the length of the capillary tube in cm., and η the coefficient of viscosity of water.

$$\therefore \eta = \frac{P\pi a^4}{8Vl} \dots\dots\dots (ii)$$

If h is the difference between the levels of water in the two manometric limbs (or the difference between the level of water in the tank denoted by M and the horizontal plane carrying the axis of the tube), d the density of water, and g the acceleration due to gravity, then we have,

$$P = h d g = h g \text{ [as } d \text{ for water} = 1]$$

$$\therefore \eta = \frac{h g \pi a^4}{8 V t} \dots \dots \dots \text{in)} \\ = \frac{\pi a^4 g}{8 l} \cdot \frac{h}{V} \dots \dots \dots \text{(iv)}$$

Note:—poiseuille's formula holds good only when the velocity of flow of the liquid is below the critical velocity. The critical velocity depends upon the bore of the tube and viscosity of the liquid.

Method:—1. Take a thick walled capillary tube of nearly 0.5 mm. in diameter and 40 cm. in length. Clean it by HNO_3 , H_2SO_4 and NaOH . Rinse it then by tap water. Place it horizontally on the table. Connect one of its ends A to the constant level bath T_1 through a T piece with rubber tubing. The other end B is also connected to the second constant level bath T_2 . Close the out let tube of the constant level bath T_2 . Beaker is placed below the constant level tube of T_2 to collect water.

2. Through T pieces arrange the two limbs of the manometer over the holes at R and S as shown in the figure. The two limbs should remain perfectly vertical. The holes R and S where the manometric limbs are connected to the tube AB should be at least 10 cm. away from the capillary tube. In the apparatus of the second type connect the end A to the manometer M.

3. Open the tap so that water comes in T_1 . By raising or lowering it and also adjusting T_2 , fix the baths in such positions that the water begins to come out of the constant level tube of T_2 in a steady trickle. The discharge of water should not be too large. In second type of apparatus water comes out at the end B. Generally 10 to 30 drops per minute are sufficient.

4. Take a completely dried and cleaned graduated cylinder and put it below the constant level tube of T_2 or the end B as the case may be. The water will begin to collect in it. As soon as you start collecting water start the stop watch.

5. When sufficient water has been collected say about 100 c.c. stop the stop watch and remove the cylinder. Determine the volume of water collected from the graduated cylinder and time t from the stop watch. From this observation calculate the volume V of water flowing per second.

6. Read the level of water in the two limbs M_1 and M_2 and then determine the difference of level between the two limbs. It will give h . In another type determine h from the manometer M.

7. Now change the positions of the two baths by lowering or raising them along the stands. Consequently the pressure will change changing the rate of flow of water. As described above determine the corresponding values for V and h . In this way change the pressure at least for three to four times. Each time determine the value of V and h .

8. From each observation, determine the value $\frac{h}{V}$ and then calculate mean $\frac{h}{V}$.

To determine radius :—

9. Remove the capillary tube and put it horizontally on a clamp stand. Take a travelling microscope and determine its L. C. Probably it should be 0.001 cm. Focus it on one of the ends of the tube and determine its internal diameter in this position as described in the expt. on surface tension. Move the tube by a right angle and again determine the internal diameter. Now repeat the same procedure putting another end in front of the microscope. The mean of three or four readings will give the diameter of the tube from which the radius of the tube a is calculated,

Note:—A better method of determining radius is as follows:—Introduce a pellet of mercury in the capillary tube. Find its length at a few places in the tube and then determine the mean length. Let it be x . Now by taking the mercury in a previously weighed watch glass find the mass (m) of mercury pellet of length x . If a is the radius of the tube, volume of this much of mercury will be $=\pi a^2 x$. If d is the density of mercury,

$$m = \pi a^2 x \cdot d$$

$$\text{or } a = \sqrt{\frac{m}{\pi x d}}$$

10. Find the length of the capillary tube with the help of meter scale.

11. Find the temperature of water in the level bath by the help of thermometer.

12. Calculate η , the coefficient of viscosity by the formula, (iv)

Observations—(1) Temperature of water =°C.

(2) Length of the capillary tube =cm,

[1] Observation table for h and V :-

S.N.	Reading of the level of water in M_1 in cm (h_1)	Reading of the level of water in M_2 in cm (h_2)	$h = h_1 - h_2$	Volume of water flowing in c. c. V'	Time in sec	Volume V for one sec.	$\frac{h}{V}$	Mean $\frac{h}{V}$
1								
2								
3								
4								

[2] Observation table for the internal diameter of the tube:-

L.C. of the microscope = ... cm.

S.N.	One end of the tube			Another end of the tube			Mean Diameter (d)
	Diameter in one direction			Diameter in Perpendicular direction			
	Reading L.H.S.	Reading R.H.S.	Diameter	Reading L.H.S.	Reading R.H.S.	Diameter	
1							
2							

Mean diameter $d = \dots$ cm.Mean radius $a = d/2 = \dots$ cm.

or

(i) Length of the mercury pellet at various places =

(1) ... cm (2) ... cm. (3) ... cm.

Mean = ... cm.

(ii) Mass of the watch glass = ... gm.

(iii) Mass of watch glass + mercury = ... gm.

(iv) Mass of mercury (m) = (3 - 2) = ... gm.

(v) Density of mercury (ρ) = 13.6 gm/cc.

$$a = \sqrt{\frac{m}{2 \rho L}}$$

Calculations:- Mean $a = \dots$ cm.

$$\frac{h}{V} = \dots$$

EXPERIMENT No. 10

Experiment:—To determine the mechanical equivalent of heat by mechanical method (Searle's friction cone method).

Apparatus:—Searle's apparatus, a weight box, a thermometer balance etc.

Description of the apparatus:—A and B are two truncated cones of gun metal, fitting closely in to one another. The inner cone remains projecting over the outer one. The outer cone is fixed to an ebonite disc by pins. The ebonite disc is fixed to a vertical spindle S which can be driven by hand or by electric motor. C is a counter which gives the number of revolutions which the spindle makes i. e. it gives the number of revolutions made by the outer cone.

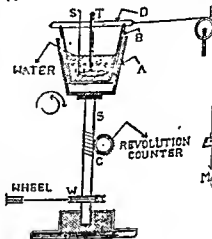


Fig. 1

The inner cone B is rigidly fixed to a wooden disc D. A groove cut in the edge of the wooden disc around which passes a string. The string passes over a pulley P and carries a mass M at the other end. A thermometer is placed in the inner cone, which is filled with water.

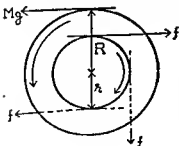


Fig. 2

Theory:—When the outer cone is rotated the inner cone tries to rotate with it on account of friction between them. But the string is so wound that the weight tries to move the cone in the opposite direction. The weight is adjusted that when the outer cone is moving the inner cone remains stationary. In equilibrium, the moment due to the force Mg about

the axis of the spindle must be equal to the moment due to the frictional force. Hence we have,

$$MgR = Fr \dots \dots \dots (i)$$

Where M is the mass suspended, g is the acceleration due to gravity, R is the radius of the disc, F is the mean value of the frictional force between the two cones and r is the mean radius of the surface of contact of the two cones.

If the outer cone makes n revolutions, the work done W by the force of friction is given by,

$$W = 2\pi n r F \dots \dots \dots (ii)$$

From (i) and (ii) we get,

$$W = 2\pi n M g R \dots \dots \dots (iii)$$

When so much amount of work is done, it will produce heat which will increase the temperature of the cones and water. The heat produced is given by,

$$H = (m_1 S + m_2) (t - t_1) \dots \dots (iv)$$

Where m_1 is the mass of the two cones including stirrer,

S is the sp. heat of the material of the cones,

t is the final corrected temperature of water and cones,

t_1 is the initial temperature of water and cones,

m_2 is the mass of water in the inner cone.

But according to joule's law

$$J = \frac{W}{H}, \text{ therefore, from (iii) and (iv) we get,}$$

$$J = \frac{2\pi n M g R}{(m_1 S + m_2) (t - t_1)} \dots \dots (v)$$

Method—1. Take the two cones and clean them. Place one on to another and see whether the outer one can rotate about the inner one or not. If the friction is too large, reduce it by lubricating the surfaces of the cones by oil. See that very little oil is used.

2. Determine the mass of the two cones including the stirrer by balance. Let it be m , gms. Remember that usually the cones are very heavy and so you need not use a sensitive balance.

3. Fill the inner cone up to nearly two thirds with water and again weigh the two cones. The difference between this reading and the former one gives the mass of water filled in the cone. Let it be m_1 gm.

4. Fix the outer cone on the abrasive disc, and place the wooden disc above the inner cone. Fix one end of the string on the groove of the disc and suspend a pan carrying a mass M by its another end. It is very important to see that the string while passing over the pulley remains perfectly tangential to the disc D . Now rotate the spindle S by hand or by electrically driven motor.

5. Put the thermometer T in the inner cone passing through the disc through a cork.

6. Adjust by trial and error the mass in the pan in such a way that while the outer cone is moving the inner one remains stationary. (Though students encounter great difficulty in doing this in the beginning, after some practice it will become very easy). When this adjustment has been done note the initial temperature of water and the cones by the thermometer T . Also note the reading of the counter.

7. Now start the stop watch and go on moving the outer cone by driving the wheel. It is again very important that the wheel should be driven at a constant speed, otherwise the inner cone will not remain stationary. Stir the water constantly so that the temperature remains uniform.

8. When the temperature of water in the cone rises by about 5° to 10°C , stop rotating the spindle and the watch. Read the final temperature of water (t_2) by the thermometer. Determine the time T by the stop watch for which the wheel has been rotated.

Again read the position of the counter and determine the number of rotations (n) performed by the outer cone.

To determine Radiation correction:—9. To obtain the radiation correction, find the fall in temperature for the same time for which the experiment was done. Let it be t_3 $^\circ\text{C}$, then the radiation correction will be $\frac{t_1}{2}$ $^\circ\text{C}$. Add this value to t_2 to get the final corrected temperature.

10. To determine the circumference of the disc $2\pi R$, take a thread and pass it round the disc completely, and then measure it on a meter scale. To get more accurate value, two or three turns of the thread are taken, and the length of the string is determined for these

turns. Dividing it by the number of turns, the length for one turn can be obtained.

11. Calculate the value of J by substituting the corresponding values in formula (v).

12. If there is time left, vary the speed of rotation, and the mass M suspended by the thread. Repeat the procedure in the same way, to get the new values, and calculate for J .

13. If you have taken few sets of observations, determine each set, and then calculate the mean value of J .

Observations:—

1. Mass of the two cones with stirrer (m_1) = gm.
2. Mass of the two cones + water in the inner cone (m_2) = gm.
3. Initial temperature of water (t_1) = °C.
4. Final " of " (t_2) = °C.
5. Initial reading of the counter (c_1) =
6. Final " of " (c_2) =
7. Mass of the load suspended from the string (M) = gm.
8. Fall in temperature of water after cooling through the same time for which the expt. is done..... = °C.
9. Circumference of the disc D ($2\pi R$) = cm.
10. Sp. heat S of the material of cones =

Calculations:—

1. Mass of water (m_2) = ob. 2 - ob. 1 = ... gm.
2. Rise in temp. ($t_2 - t_1$) = " 4 - " 3 = ... °C.
3. No. of rotations made by the cone = (n) = $C_2 - C_1$ = ob. 6 - 5 = ...
4. Final corrected temp. $t = \left(t_2 + \frac{t_2 - t_1}{2} \right)$ °C
5. Radius of the disc R = ... cm.

Substituting the proper values in the formula.

$$J = \frac{2\pi n M R}{(m_1 S + m_2) \left(t_2 + \frac{t_2 - t_1}{2} - t_1 \right)}, \text{ calculate } J.$$

Result:—The mechanical equivalent of heat = ergs/calorie.

Precautions and sources of error:—

1. The string carrying the mass should remain tangential to the disc.

2. The disc must remain stationary i. e. the mass suspended must remain at the same level. This can be achieved by adjusting the rotation of the wheel. As the temperature rises, to keep the disc stationary the wheel will have to be rotated with more speed.

3. Before starting expt. the cones should be properly lubricated, otherwise friction will be extremely large, and it will be very difficult to perform the experiment.

4. The pulley P should have minimum friction, otherwise it will tend to change the value of Mg in the formula.

5. The water should be constantly stirred.

6. The radiation correction should always be applied.

7. The water in the inner cone should not be so much that it may spill out.

8. A thermometer reading upto $\frac{1}{2}^{\circ}\text{C}$ or $\frac{1}{3}^{\circ}\text{C}$ should be used to note the temperatures.

Criticism —The value of J found by this method is not very accurate due to the following reasons.

(1) The rise of temperature is very small, and therefore it cannot be determined very accurately.

(2) The temperatures are determined by mercury thermometers and not by standard thermometers.

(3) Though the radiation correction is applied, radiation losses are still there, and the amount of heat calculated is less than the heat generated. Therefore, the value of J obtained by this method is slightly higher.

(4) The assumption that the total work done with no over-ruled heat is wholly taken up by the cones is wrong. Hence, the result is not very accurate.

Oral questions—

1. What is Joule's law ? 2. Define J and give its units ?
3. How is heat generated in this experiment ? 4. Is this process reversible or irreversible ? 5. Why is it necessary to adjust the speed of rotation so that the suspended weight remains at the same level ? Is it necessary to rotate the spindle at a constant speed ? 6. If you increase the weight suspended, why the heat generated increases ? 7. Why the string should remain tangential to the disc ? 8. Which of the two cones rotate ? 9. What is radiation correction and how is it applied ? 10. Why the results obtained by this method are high ?

EXPERIMENT No. 11

Experiment :—To determine the thermal conductivity of copper in the form of cylindrical rod by Searle's apparatus.

Apparatus :—Searle's apparatus, two thermometers reading up to $\frac{1}{2}^{\circ}\text{C}$, and two thermometers reading up to $\frac{1}{8}^{\circ}\text{C}$, a constant level bath, a boiler with a burner to prepare steam, measuring flask, vernier callipers, meter scale, weight box, rubber tube etc.

Description of the apparatus :—AB is a thick cylindrical bar of copper. The end A is placed in the steam chest C, in which steam

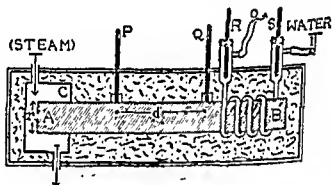


Fig. 1

can be admitted from the boiler. The steam after heating the end A passes out from the other out let. A copper spiral tube is welded around the other end B of the bar as shown in the figure. The ends of the spiral tube carries cups in which thermometers can be placed. Cold water is circulated in the spiral tube. Cold water is allowed to enter the spiral tube from a constant level bath (not shown) to ensure steady flow. After circulating, the water comes out from the other end after taking heat from the bar, which can be collected in a cylinder. The two thermometers S and R give respectively the temperatures of in flowing and out flowing water. Two holes are drilled at a convenient distance along the bar, and two thermometers P and Q are placed in them. To secure better contact, mercury is placed in

these holes. The whole apparatus is surrounded by felt or cotton wool to prevent the heat from going out, and is packed in a wooden case.

Theory :—In the steady state the heat flowing through the bar per sec. is absorbed by the circulating water at the other end. Let M be the mass of water flowing in t sec., and θ_1 and θ_2 be the temperatures of in flowing and out flowing water; then heat taken up by water per sec. will be.

$$= \frac{M}{t} (\theta_1 - \theta_2) \dots\dots\dots (i)$$

But the heat Q flowing per sec. through the bar is given by,

$$Q = K A \frac{\theta_1 - \theta_2}{d} \dots\dots\dots (ii)$$

Where K is the coefficient of thermal conductivity of the material of the bar.

A is the area of cross-section of the bar,

θ_1 and θ_2 are the steady temperatures recorded by P and Q and,

d is the distance between these two thermometers.

Equating (i) and (ii) we get,

$$K A \frac{\theta_1 - \theta_2}{d} = \frac{M}{t} (\theta_1 - \theta_2)$$

$$\text{or } K = \frac{M (\theta_1 - \theta_2) d}{t A (\theta_1 - \theta_2)} \dots\dots\dots (iii)$$

If the radius of the bar = r ; $A = \pi r^2$

$$\text{or } K = \frac{M (\theta_1 - \theta_2) d}{t \pi r^2 (\theta_1 - \theta_2)} \dots\dots\dots (iv)$$

Method :—1. By means of rubber tube connect the steam chest to the boiler. Pass steam through it so that the end A is heated and the steam passes through the bar. Put two thermometers P and Q in the

2. Connect the farther end of the spiral tube to a constant level and allow the water to circulate in the spiral. For this connections with the bath are to be made as explained for viscosity. The water should come out only in the form of a trickle otherwise the temperature difference between the in flowing and out flowing water will be very small. Insert two thermometers R and S in the cups at the two ends of the spiral. These thermometers should be able to read up to $1/5^\circ\text{C}$. The flow should be regulated such that the difference of temperature between the two thermometers be more than 5°C .

3. Now wait till the bar attains steady state. It should be clearly noted that the rate of flow of water in the spiral must remain constant throughout. When steady state is reached, the temperatures indicated by the four thermometers will attain a steady value. (Note it that in the steady state the four thermometers do not show the same temperatures). Whether the bar has attained the steady state or not can be determined by noting the temperatures in the four thermometers after every five minutes. If there is no change in the respective values of temperatures denoted by them, the bar is said to have attained the steady state. It takes about 30 to 40 minutes to obtain this condition.

4. When the bar has attained the steady state, read the four thermometers. Let the temperatures denoted by them be θ_1 , θ_2 , θ_3 and θ_4 , respectively.

5. To determine the mass of water flowing per sec. in the spiral tube, take a clean and perfectly dry measuring cylinder. Start the stop watch and collect water in this cylinder for a certain interval of time say, t seconds. Determine the volume of water from the cylinder. As the density of water is unity the volume will be equal to the mass. Knowing mass (M) discharged in time t , determine the rate of flow, i.e. mass flowing per second. The mass collected can also be determined by taking a weighed beaker, and then collecting water in it. Again weigh the beaker after the water has been collected. The difference between the two masses will be the mass of water which has been collected in t seconds.

6. Now repeat the whole process again after changing the rate of flow of water. It can be done by altering the position of the constant level bath. Once the rate of flow is varied, you have again to wait till the steady state is reached. Again determine θ_1 , θ_2 , θ_3 , θ_4 and M in the same way. It takes nearly half an hour to reach the steady state. Hence it is advisable not to change the rate of flow, but for the same rate of flow, collect water for different timings.

7. Measure the distance d between the two hole with the help of vernier callipers.

8. Measure the diameter of the bar also with the help of vernier callipers. Determine the diameter at three or four different places on the bar. And then calculate mean diameter.

9. Calculate the value of K by each set of observation and then determine the mean value of K .

Observations:—

Length of the bar between the holes =cm.

[1] Determination of the radius of the bar—

L. C. of vernier callipers =cm.

S. No.	Diameter in any position	Diameter in perpendicular position	Diameter	Mean Diameter
1	—	—	—	
2	—	—	—	

$$r = \frac{\text{Diameter}}{2} = \text{.....cm.}$$

[2] To know whether steady state is reached or not:—

S. No.	Time	θ_1	θ_2	θ_3	θ_4
	5 min.	—	—	—	—
	10 "	—	—	—	—
	15 "	—	—	—	—
	20 "	—	—	—	—
	25 "	—	—	—	—

Conclusion:—Temperatures are steady.

[3] Observation table for θ_1 , θ_2 , θ_3 , θ_4 , M and t :—

S.No.	θ_1 °C	θ_2 °C	θ_3 °C	θ_4 °C	Mass of water collected (M) in gm.	Time taken t in sec.	Rate of flow $m = \frac{M}{t}$	Mean
1								
2								
3								

Calculations:—From each set of observation calculate K and then determine mean value of K .

Result:—The coefficient of thermal conductivity of copper
=calories/sec/sq. cm/unit temp. gradient.

Precautions and sources of error:—1. The bar should be covered with cotton wool or felt otherwise radiation losses will become appreciable.

2. While taking one set, the rate of flow of water through the spiral must be maintained steady. It can be secured only when constant level bath is used. If the water is admitted direct from the tap, the rate of flow will not remain constant.

3. The rate of flow should be as small as possible so that the difference between t_2 and t_1 may be quite large. But mind it, the flow should always remain continuous.

4. To have better accuracy for the same set, determine the rate of flow for a number of times, and substitute the mean value in the formula.

5. The temperatures should be noted and water collected only when the bar has attained the steady state, otherwise the heat flowing through each section of the bar will not be the same and the formula will not apply.

6. The thermometers P and Q ; and R and S should be interchanged. This will eliminate the error due to the defects if any present in thermometers.

Criticism:—The apparatus gives fairly good results. It is suitable only for good conductors of heat which can be available in the form of cylinders.

For more accurate results, the bar should be heated by platinum resistance wire wrapped round the end A . The temperatures should be measured by platinum resistance thermometers. As the radiation losses are not totally eliminated, they cause some error.

Oral questions—

1. Define coefficient of conductivity of a substance and give its units. 2. What do you understand by the steady state of the

bar ? Is it essential to obtain it in this case ? 3. If the rate of flow of water is altered, will the steady state be disturbed ? If yes why ? 4. Why do you take thick bars and cover them with felt or cotton wool ? 5. What do you understand by temperature gradient ? 6. How is the rate of flow of water maintained constant ? 7. Why the rate of flow of water is kept small ? 8. Is this method suitable for determining K for poor conductors ? 9. What is the difference between good conductors and bad conductors ?

EXPERIMENT No. 12

Experiment :—To determine the value of γ the ratio of two specific heats of a gas, one at constant pressure and the other at constant volume by Clement and Desormes's method.

Apparatus :—A large flask connected with a liquid manometer, a bicycle pump etc.

Description of the apparatus :— F is a flask of glass capacity (nearly of 5 litres). It is surrounded on all sides by non-

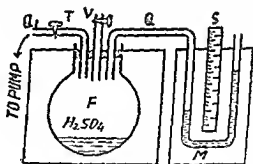


Fig. 1

conducting material like cotton wool. The flask has either a metallic mouth or a cork is tightly fitted in its mouth. Two side tubes Q , and Q are fitted in the mouth of the flask. One of the side tubes is connected to a bicycle pump through a stop cock T . The other tube Q is connected to a manometer M . S is a vertical scale fitted to the manometer board. Generally Xylene is used as a manometric liquid. M gives the pressure of the air enclosed in the flask. V is a valve fitted in the mouth of the flask which when opened puts the inside air in communication with the outside atmosphere.

Theory :— V is closed and air is compressed inside the flask by the pump. Then T is closed. Due to sudden compression the temperature of the air increases. But after some time the air gets cooled to the

stationary, indicating the excess of pressure of the compressed air over that of the surroundings. If P is the atmospheric pressure, P_1 the pressure of the enclosed gas, h_1 the difference between the levels of the manometric liquid in the two limbs, ρ the density of the liquid, and g the acceleration due to gravity, then we have,

$$P_1 = P + h_1 \rho \dots \dots \dots (i)$$

Now if the valve V is suddenly opened and closed, the enclosed air in the flask will experience an adiabatic expansion. Momentarily the air inside will attain the same pressure as outside. But due to sudden expansion the temperature of the air falls. But the temperature of the enclosed air will tend to increase and finally attain the atmospheric value. Consequently the pressure inside the flask will increase and after some time the manometric levels will again become stationary. Let this difference between the two levels in the stationary state be h_2 . If P_2 now is the pressure of the enclosed gas, we have,

$$P_2 = P + h_2 \rho \dots \dots \dots (ii)$$

By considering adiabatic and isothermal changes, and simplifying, from (i) and (ii) we get,

$$\left(\frac{P_1}{P_2} \right)^Y = \frac{P_2}{P} \dots \dots \dots (iii)$$

Where $Y = \frac{C_p}{C_v}$, C_p is the specific heat at constant pressure, and C_v is the specific heat at constant volume.

By taking logs we get,

$$Y (\log P_1 - \log P_2) = \log P_2 - \log P$$

$$\text{or } Y = \frac{\log P_2 - \log P}{\log P_1 - \log P_2} \dots \dots (iv)$$

Substituting the values of P_1 and P_2 from (i) and (ii) in (iv) we get,

$$Y = \frac{\log (P + h_1 \rho g) - \log P}{\log (P + h_1 \rho g) - \log (P + h_2 \rho g)}$$

$$Y = \frac{\log \left(1 + \frac{h_1 \rho g}{P} \right)}{\log \left(1 + \frac{h_1 \rho g}{P} \right) - \log \left(1 + \frac{h_2 \rho g}{P} \right)}$$

As h_1 and h_2 are much smaller than P these log series can be expanded. As the higher powers of h are very small, retaining only the first power of h_1 and h_2 we get,

$$Y = \frac{h_1}{h_1 - h_2} \dots \dots \dots (v)$$

Method:—1. To get rid of the moisture present in the air introduce a few drops of concentrated sulphuric acid in the flask. (These are usually put there and you need not worry about it. But you must check).

2. Connect the manometer M to the flask with the help of the side tube Q.

3. Close the valve V and connect the side tube Q, to a compression pump, and compress air inside the flask. Go on compressing air till the difference between the levels of the two tubes of the manometer is nearly 5 to 10 cm. Now close the stop cock T, and wait for some time till the enclosed gas attains the atmospheric temperature. Now the two levels in the manometer will become stationary. Note down the levels of the two limbs and determine the difference h , between the two levels.

4. Next open the valve V and close it suddenly. The air will expand adiabatically. Its temperature will suddenly fall, and momentarily the air inside will attain the same pressure as outside. This will be indicated by no level difference in the two manometric tubes. Wait for some time till the air again attains the atmospheric temperature. The pressure will increase and ultimately it will become steady. The two levels in the manometer will again become stationary. Read the two levels and determine their difference h_1 .

5. Repeat the same procedure at least for four times. Every time note the value of h , and h_1 .

6. Calculate γ by formula (v) by h 's set, and then find the mean value of γ .

Now as we have the diatomic gas it is represented by an exhaust pump. The principle, however remains the same. Here, instead of air coming out it rushes in when the valve is opened. However, the same method of determining γ is valid for the reason that we are not here in the vicinity of the critical point.

Observations:—

S. N.	After compressing the air			After adiabatic expansion but when temperature attains initial value			$\gamma = \frac{h_1}{h_1 - h_2}$
	Level in L. H. S. limb in cm. (a)	Level in R. H. S. limb in cm. (b)	Pressure difference $h_1 = (b - a)$ (c)	Level in L. H. S. limb in cm. (d)	Level in R. H. S. limb in cm. (e)	Pressure difference $h_2 = (e - d)$	
10							

Calculations:—Calculate γ from formula,

$\gamma = \frac{h_1}{h_1 - h_2}$ by each set and then determine the mean value of γ .

Result:— $\gamma = \dots\dots$ (no units).

Precautions and sources of error:—1. It is very important in this experiment that the flask should be perfectly air tight. If it is not so the level will not remain stationary. In that case wax should be used and the flask should be made air tight.

2. The enclosed gas should be completely dry. CaCl_2 is therefore, placed inside the flask to absorb the moisture.

3. The manometric liquid must possess low density and low vapour pressure, so that the difference between the two levels in the manometer tubes for the same difference of pressure may be large. That is why water is never used. Xylene is normally preferred. If xylene is also not easily available some low grade Mobil oil may be used.

4. For the applicability of formula (3), L , and h_1 should not be very large.

5. The levels in the manometers should be noted only after the enclosed air has attained the steady atmospheric temperature.

As h_1 and h_2 are much smaller than P these log series can be expanded. As the higher powers of h are very small, retaining only the first power of h_1 and h_2 we get,

$$Y = \frac{h_1}{h_1 - h_2} \dots \dots \dots (v)$$

Method.—1. To get rid of the moisture present in the air introduce a few drops of concentrated sulphuric acid in the flask. (These are usually put there and you need not worry about it. But you must check).

2. Connect the manometer M to the flask with the help of the side tube Q.

3. Close the valve V and connect the side tube Q, to a compression pump, and compress air inside the flask. Go on compressing air till the difference between the levels of the two tubes of the manometer is nearly 5 to 10 cm. Now close the stop cock T, and wait for some time till the enclosed gas attains the atmospheric temperature. Now the two levels in the manometer will become stationary. Note down the levels of the two limbs and determine the difference h_1 between the two levels.

4. Next open the valve V and close it suddenly. The air will expand adiabatically. Its temperature will suddenly fall, and momentarily the air inside will attain the same pressure as outside. This will be indicated by no level difference in the two manometric tubes. Wait for some time till the air again attains the atmospheric temperature. The pressure will increase and ultimately it will become steady. The two levels in the manometer will again become stationary. Read the two levels and determine their difference h_2 .

5. Repeat the same procedure and at the same time note the value of h_1 and h_2 .

6. Calculate Y by formula (v) and find the value of Y .

Note:—At many places, the pump. The procedure of air rushing out it this procedure is are not sure of

EXPERIMENT No. 13

Experiment:—To determine the height of a distant tower or a building with the help of a sextant.

Apparatus:—A sextant, a measuring tap (50' or 100'), a plane mirror etc.

Description of the apparatus:—Sextant consists of a graduated arc AB connected to two fixed radial arms BC and AC. The arc subtends an angle of 60° at the centre. (But on the scale 120° are marked). Each degree on the scale is marked double to make the instrument direct reading. If the mirror rotates through 5° , the scale reads 10° . CD is the third arm which is movable, and carries at one end C a plane mirror M_1 , called the index glass. At the other end it carries a vernier V

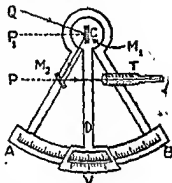


Fig. 1

which moves over the arc AB. The plane of the mirror M_1 is perpendicular to the plane of the arc, and parallel to the length of the arm CD. There are screws fixed at the back of these mirrors to set their plane perpendicular to the plane of the arc. A half silvered glass plate M_2 is fixed to the arm AC which is called the horizon glass. Its upper half is transparent while the lower half is silvered. The plane of the mirror M_2 is also perpendicular to the plane of the arc, and parallel to the arm BC. A telescope T is mounted on the arm BC which is directed towards M_1 . The axis of the telescope passes through the centre of of M_1 . Sometimes in place of a telescope a hollow tube with a small hole is also provided. This is of particular use when the object to be observed is not very distant. A tangent screw is also provided to make fine adjustments.

Theory:—When the arm CD occupies the position CB, the planes of M_1 and M_2 are parallel to each other. Therefore BC marks

the zero position of the circular scale AB. A wooden handle is provided with the sextant to hold it in hand. Sometimes a stand is also provided on which the sextant can be fixed. In this position, if the telescope is pointed towards a distant object, two images will be seen of that object coinciding with each other. One is seen through the transparent portion,

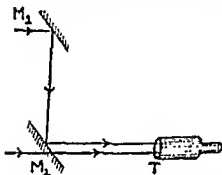


Fig. 2

while the other is due to the rays which have been doubly reflected once at M_1 and then at M_2 . If the mirrors are parallel the rays will be parallel and consequently the two images will coincide as shown in fig. 2. If it is not so the instrument possesses zero error.

Sextant is employed for determining the angular separation between two distant points or the angular elevation of a tower or a building. Angular separation then gives the height between the two points under consideration. Suppose the height of a tower is to be determined. Then, a reference mark is made at the bottom of the tower in level with the eye.

If the telescope T is directed towards this mark its image will be seen through the transparent portion of the plate M_1 . Now the arm CD is moved so that M_1 moves and receives the rays coming from the top of the tower. These rays will be first reflected at M_1 and then after getting reflected at M_2 enter the telescope and forms the image of the top. The arm CD is so adjusted that the image of the mark and the reflected image of the top coincide, the angular separation of the reference mark from top will be the $\angle QCP$. But when the mirror turns through an angle, the reflected ray turns through twice that angle. The angle θ through

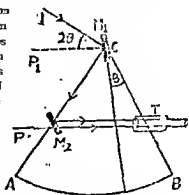


Fig. 12

which the mirror is turned is measured on the scale. Naturally 2θ will be the angular separation.

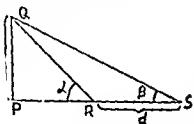


Fig. 4

$$h \cot \beta = PR + d \dots\dots\dots (i)$$

$$h \cot \alpha = PR \dots\dots\dots (ii)$$

Subtracting (ii) from (i) and solving we get,

$$h = \frac{d}{\cot \beta - \cot \alpha} \dots\dots\dots (iii)$$

α and β are determined with the help of a sextant.
And —

To adjust the sextant — 1. Bring the arm CD near the 0° of the scale, and keeping your eye near the index glass in it for the first part of the scale. If the image is in same plane as the scale, the plane of the index glass was perpendicular to the plane of the arc. If it is not so, use the screws provided at the back of the mirror, and make adjustment.

2. Observe any object through the telescope and adjust it in such way that its two images coincide at the centre of the field of view. Now tilt the sextant so that these images lie near the edge of the field of view and note if they still coincide. Tilt in the opposite direction so that the images lie near the other edge. If the coincidence persists, the axis of the eye is parallel to the scale. If it is not so, adjust the eye by means of the screws provided.

3. Point the sextant towards a distant object. You will see two images, direct and the other reflected one. Adjust the telescope so that the direct image and the reflected image lie. The image which moves by moving the movable

arm is the reflected image. If the coincidence is perfect the horizon glass is parallel to the index glass and perpendicular to the plane of the circular scale. If these two are not parallel one image will lie side ways with respect to the other. To remove this defect move the screws provided at the back of M_1 , so that M_1 and M_2 are set parallel to each other, and the two images coincide.

To determine vernier constant:—4. (a) Determine the number of divisions marked on the circular scale. Usually they are sixty, and therefore V. C. of this scale will be one minute. (b) Now determine the number of divisions on the vernier scale, they are usually four in number, therefore vernier constant of the instrument will be 15 seconds.

To determine zero reading:—5. As described in theory, make a reference mark on the building in level with your eye.

Move away from the building by a considerable distance and select some place on the ground. Mark the position of this place. Let it be S (fig. 4). Now standing there, point the telescope towards that reference mark. Direct image of the mark will be visible through the transparent portion. Move the arm CD and get the reflected image of the same reference mark. Coincide these two images. Read the vernier and the main scale. It gives zero reading at that place. [Some times to determine the zero reading, the movable arm is so adjusted that the zero of the vernier coincides with the zero of the circular scale. After making this adjustment, the screws provided at the back of the mirrors are adjusted to bring about coincidence between the direct image and the reflected image of the reference mark at the centre of the field of view.]

6. Next point the telescope towards the reference mark so that its image is clearly visible through the transparent portion. Now rotate the arm CD so that the rays from the top falls upon the mirror M_1 , and in this way obtain the image of the top in the telescope. In this position you will see two images, (a) the direct image of the reference mark, and (b) the doubly reflected image of the top. Clamp the arm CD, and by tangent screw adjust CD so that these two images completely coincide on the cross-wires. Read the vernier and the main scale and add. This gives the angular elevation of the top with respect to the reference mark. Add or subtract from it the zero reading (as the case may be). It gives the angle θ .

∴ Height of the building from the reference mark (c) = ...metres.

∴ Height of the building = (c) + (d) = ...metres

Result — The height of the building = ...metres.

Note — The height can be obtained in ft. also.

Precautions and sources of error:—1. It is important to note that zero error or the zero reading changes from place to place; therefore, it should be freshly determined at the place of observation.

2. The two mirrors M_1 and M_2 must be parallel to each other and perpendicular to the plane of the arc.

3. The axis of rotation of the mirror M_1 should lie at the centre of the graduated arc.

4. The foot of the building and the two places of observation should lie in the same straight line.

5. The axis of the telescope should be parallel to the plane of the circular scale and must pass through the centre of the horizon glass.

Criticism:—If all the errors are eliminated, sextant gives fairly good results. To increase the accuracy in the determination of the height h , d should be large—nearly one-fourth of the height to be determined. The angles α and β should also be determined near the building and not very far off.

Modifications:—1. To determine the elevation of the sun, with the help of a sextant using an artificial horizon.

Hints:—1. Artificial horizon is a horizontal reflecting surface. It can be either a surface of mercury in a trough or a carefully levelled plane mirror.

2. Place the plane mirror P on a well levelled table and look through it for the image of the sun.

3. Direct the telescope towards this mirror to look for S , the image of the sun. The image S_1 will be seen directly through the transparent portion.

4. Move the index glass so that the reflected image of the sun is also seen through the telescope. Measure this angle subtended by the

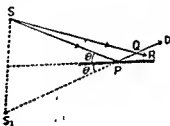


Fig. 5

two images on the circular scale by keeping the plane of the sextant vertical. As the instrument is held above the artificial horizon, at the point of observation Q, sextant measures the angle DQR and not $\angle SPS_1$, but since the object is quite distant, these two angles are almost equal and so $\angle SPS_1 = \angle DQR$. [*It is therefore always better to hold the sextant as near to the horizon mirror as possible.*]

4. As is clear from fig. (5) the elevation of the sun will be half of the angle $\angle SPS_1$.

2. To determine the height of a building with the help of a sextant using an artificial horizon.

Hints:—As described above, determine the angles of elevations α and β at two places distant d apart and then calculate the required height as described in the experiment. As the observed angle differs from the angle of elevation, observations should be made from a place fairly distant from the building.

3. To determine the horizontal distance between two points at a height in level with the eye marked on the wall.

Hints:—(see Fig. 6).

1. P and Q are the two points distant l apart. Here, l is to be measured.

2. Take two points R and S in such a way, so that they are collinear with P and the line PRS may be perpendicular to AB.

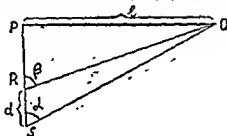


Fig. 6

4. Determine the angular separations α and β between these points at R and S respectively as described in the experiment.

5. Measure the distance between R and S. Let it be d .

6. Determine l by the formula,

$$l = \frac{d}{\cot \alpha - \cot \beta}$$

7. In this case the sextant is to be held horizontally for determining α and β .

4. To measure height between two spots (both not in level of the eye) either both above eye level or one below and other above eye level.

Hints:—(1) Suppose both the spots are above the eye level. Determine the height h_1 of one of the spots from the eye level by sextant. Similarly determine h_2 the height of the other spot from eye level. The difference between these two heights h_1 and h_2 gives the height between the two spots.

(2) Suppose one is above the eye level, and the other is below eye level. First determine the height between the eye level and the spot which is above. Let it be h_1 . Then determine the height between the eye level and the spot which is below. Let it be h_2 . $h_1 + h_2$ gives the required height.

Oral questions:—

1. Explain the principle upon which sextant is based. 2. What are the adjustments of the sextant, are they necessary? 3. What are the functions of the two mirrors? 4. How is the instrument made direct reading? 5. Why coloured glasses are provided with the instrument? 6. Explain artificial horizon. 7. Can you measure the altitude of the sun with the help of this instrument? 8. Explain zero error, does it depend upon the distance of the object from the point of observation? If so what is the relation? 9. What do you understand by the terms angular elevation or angular separation?

EXPERIMENT No. 14

Experiment:—To determine the refractive index μ of glass in the form of a prism, for a given wave length of light (sodium light, $\lambda = 5893 \times 10^{-8}$ cm.) with the help of a spectrometer.

Apparatus:—A spectrometer, a sodium lamp, (or any monochromatic source of light), a prism, a reading lens, a lamp, a spirit level etc.

Description of the apparatus:—Spectrometer mainly consists of the following parts —

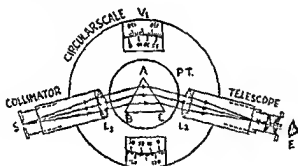


Fig. 1

(1) **Collimator:** It is a metal tube at one end of which is an achromatic lens system L_1 directed towards the prism table P. T. At the other end is fitted a draw tube carrying an adjustable vertical slit at its end. The draw tube can be moved in or out with the help of a rack and pinion arrangement. S is the source of light which is placed in front of the slit. The width of the slit can be adjusted by a screw. The draw tube is so adjusted that the slit lies at the focal plane of the lens L_1 .

Consequently the rays emerging from the collimator are parallel. Thus, it can, turn the rays. It is rightly called the base of the instrument.

(2) A circular metallic scale graduated from 0° to 360° is attached horizontally to the base of the instrument. The circular scale can rotate about a vertical axis passing through the centre of the base. A telescope is attached to the circular scale. It is capable of rotating about the vertical axis passing through the centre of the circular scale. It rotates along with the circular scale.

Telescope is a metal tube, at one end of which it carries an achromatic lens system L_1 called the objective glass. At the other end a draw tube is fitted carrying the cross-wires and the Ramsden's eye piece. Ramsden's eye piece consists of two plano-convex lenses of equal focal lengths kept apart by a distance equal to $\frac{2}{3}$ of the focal length of any of the two lenses. Cross wire is fixed beyond these two lenses. Out of these two lenses the lens nearer the objective is called the field lens while the other is called the eye lens. The draw tube can also be moved in or out by a rack and pinion arrangement. By adjusting the draw tube telescope can be focussed to receive parallel beam of light, and form a well defined image of any object at its cross wires. The axes of the telescope and collimator are horizontal and are perpendicular to the axis of the spectrometer, and the three meet at the same point. Two screws are provided at the base of the instrument, one to clamp the telescope, and the other to give it a fine movement after clamping. The latter is called the tangent screw.

(3) At the centre, over the circular scale is mounted a base table carrying two verniers V_1 and V_2 which moves with the table over the circular scale. At the centre of the base table is placed the prism table resting on a vertical rod. In fact the base table is the part of the prism table. The prism table can be adjusted and fixed at any desired height with the help of a screw. Prism table along with the verniers is capable of rotation about a vertical axis passing through the centre of the instrument. Independently of the telescope. The prism table consists of two circular plates connected by means of three leveling screws P_1, P_2, P_3 form the three vertices

: an equilateral triangle. On the upper surface of the table parallel lines are drawn as shown in fig. 2. One set of parallel lines are parallel to the line joining the two screws. As in the case of a telescope, the prism table is also provided with two screws at the base, one to clamp it, and the other to give it a fine movement after clamping.

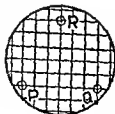


Fig. 2

Prism is placed on the prism table.

Description of Sodium lamp:—It is an evacuated discharge tube generally U shaped in A.C. lamps filled with neon gas at a pressure of about 10mm. of mercury. A few specks of sodium are placed on its walls. Two electrodes in the form of cylinders containing tungsten spirals coated with barium oxide are sealed at its two ends. When a voltage of 400 volts is applied between its two electrodes (by a step up transformer) discharge passes through the neon gas giving out its characteristic red light. Due to the heat of discharge sodium evaporates and sodium vapours are produced. The colour of light changes from red to yellow in a few minutes. As the ionisation potential of sodium is lower than that of neon, discharge is almost maintained by the sodium vapours (at a pressure of about 0.1 mm. of mercury) which give out their characteristic yellow light. To maintain the temperature of the tube at about 600°C. it is surrounded by a vacuum jacket.

Theory:—ABC is the prism. PQ and RS are respectively the incident and the emergent rays of sodium light. The $\angle NMS$ formed between these two rays is called the angle of deviation. (See fig. 3).

In the minimum deviation position, let this angle of deviation be δm , which is called the angle of minimum deviation. If μ be the refractive

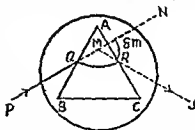


fig. 3

index of the material of the prism for this wave length of light used, and A be the angle of the prism (angle between the two refracting faces AB and AC), then μ is given by the relation,

$$\frac{1}{f} = \frac{1}{u} + \frac{1}{v}$$

It is found that the image is inverted and real.

Method - To adjust the spectrometer -

To test whether the axes of the collimator and telescope are parallel and are perpendicular to the vertical axis about which the table can rotate.

1. This adjustment is normally done by the manufacturer. However, to test for it, insert a pin at the centre of the pin table, and look through the wide slit of the collimator. The image of this pin formed by the collimator lens. If the axis of the collimator is properly adjusted the image will be formed at the centre of the field of view. If not so, slightly rotate the collimator tube about its vertical axis, so that the image of the pin is adjusted at the centre of the field.

Remove the eye piece from the telescope and repeat the above procedure. If need be, rotate the telescope about a vertical axis by the screws, to bring the image of the pin formed by the objective glass in the centre of the field. The adjustment should be done at least at three different positions.

and directly see the wall by the other eye. Adjust the distance between the eye piece and crosswires so that when one eye clearly observes the crosswires, the other simultaneously sees the wall. Thus, the eye piece is focussed on the cross wires.

To adjust the telescope for receiving parallel rays :—4. It can be done in two ways. Put the instrument in a open window and point the telescope objective towards a well defined narrow object e. g. telegraph wires, electric cables etc. at a long distance away. By moving the eye piece with the help of rack and pinion screw so adjust, that a well defined image of the object is formed at the cross-wires without any parallax. As the rays coming from a distant object are parallel, the telescope has been adjusted for receiving parallel rays.

However, this method is not recommended as you are required to remove the spectrometer (which is a delicate and a costly instrument) from the dark room and hence there is a danger of damage to it.

To adjust both telescope and collimator without removing it from the dark room by Schuster's method:—

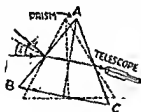


Fig. 4

5. (i) Put the sodium lamp on in the socket. You will find that the lamp starts glowing with reddish neon light. Wait till it starts glowing with intense yellow sodium light. (ii). Mount the prism on the table. (iii). Illuminate the collimator with sodium light (iv). Look for the refracted image of the slit through the telescope. (v). Rotate the

prism so that it is set in the minimum deviation position (see step...10) shown by the dotted lines in figs. 4 and 5. The image of the slit should be quite distinct. (vi). Now slightly turn the refracting edge A of the prism towards the side of the telescope as shown in fig. 4, and look for the image of the slit in the telescope. It will be blurred, because the rays entering the telescope are oblique. (vii). Adjust the

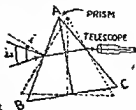


Fig. 5

by moving the

Then move the prism table to the right a little, (iii). Then slightly turn the prism table to the right so that the refracting surface AC is perpendicular to the axis of the collimator. (iv). Again when seen through the telescope the image will appear to be indistinct. That is, do not disturb the telescope, but adjust the distance of the slit from the collimating lens, to again obtain a clear and well defined image. (v). Focus the telescope again in the first position, and the collimator in the second position. A few alternate adjustments will focus both the telescope for receiving parallel rays, and collimator for giving parallel rays. Remember, when the refracting edge is moved towards the side of the telescope it is the lens which is to be adjusted, while if the edge is moved towards the side of the collimator it is the collimator which is to be adjusted. If a mistake is made and the adjustments are done other way round, the image will be rendered more indistinct.

To adjust the collimator for giving parallel rays (when Schuster's method is not followed):—

6. After adjusting the telescope, illuminate the slit and look for its image directly through the telescope. As the collimator is not adjusted for parallel rays, the image formed in the telescope will lack sharpness and definition. By adjusting the distance between the slit and the collimating lens with the help of screw d provided, make the image observed in the telescope clear and well defined. The width of the slit should be kept as small as possible. It is possible only when the slit is situated at the focal plane of the collimating lens. Thus, the collimator is adjusted for giving parallel rays.

To adjust the prism table:—

7. (i). To start with, level the prism table with the help of a spirit level. (ii). Then, place the prism ABC so that its centre coincides with that of the table, and one of its refracting surface, say AC (fig. 6), remains perpendicular to the line joining the two levelling screws P and Q . (iii). Now illuminate the slit with sodium light (iv). Rotate the prism in such a way that light falls on the edge A illuminating both the refracting surfaces AB and AC . (v). Now fix the table. (vi). Move the telescope to see the image of the slit formed by the rays reflected from the surface AC . If

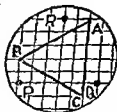


Fig. 6

slit does not lie in the middle of the field of view, or if it is much above or below the intersection of the cross-wires, adjust the two levelling screws P and Q to make it symmetrical with respect to the cross-wires.

(vii) Now turn the telescope on the other side to view the image of the slit formed by the rays reflected from the surface AB. In this case adjust the symmetry of the image with respect to cross-wires by *only* adjusting the *third screw R*. The table is now perfectly horizontal, and its edge A is vertical and parallel to the axis of rotation of the instrument.

To measure the angle of the prism (A):—8. After finishing all these adjustments, determine the least count of the verniers attached to the spectrometer. (i). Determine the smallest main scale division of the metallic circular scale. Usually it is $\frac{1^\circ}{2}$. (ii) Count the number of divisions marked on the vernier. Usually they are 30. Hence the least count will be $\frac{1}{2} \times \frac{1}{30} = \frac{1}{60}$ degree or 1 minute.

9. (i). Illuminate the slit with the sodium light and put the prism

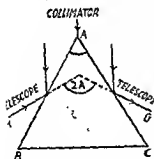


Fig. 7

on the prism table. The prism is so placed, that its edge A is kept turned towards the collimator, so that half of the light from the collimator falls on the face AB, and half on AC (ii). Now turn your eye in the horizontal plane and locate the image of the slit reflected from the face AC. This helps in determining the approximate position of the image (iii). Move the telescope in that position and look for the image of the

(iv). Clamp it in this position and by the tangent screw adjust its position to obtain a sharp image of the slit on its cross-wires. Let this position of the telescope be G (Fig. 7). (v). Note down this position the circular scale with the help of the two verniers V_1 and V_2 with a reading lens. (The difference between the readings of the two verniers will be nearly 150°) (vi). Unclamp the telescope. (vii). Now turn the telescope towards the other side of the prism facing the face B. (viii). As described above again focus it on the image of the slit

formed by the rays reflected from the surface AB. Let this position of the telescope be H. Similarly determine this new position by reading the two verniers V_1 and V_2 . (ix). The difference between the two readings of the same vernier taken at the positions G and H, will give the angle through which the telescope has been rotated. Let it be $2A$. As is clear from the fig. (7) half of this angle will be the angle of the prism A. To be more accurate take more than one set of readings for the two positions G and H.

Note:—Sometimes it appears difficult to obtain the reflected image of the slit simultaneously on both the sides of the prism. It happens only when (i) More light falls on one face than the other. Therefore, arrange so that light falls equally on both the surfaces. (ii), when the levelling of prism table or of telescope is not proper. So check this also.

To determine the angle of minimum deviation δ_m —

10. (i). Put the prism on the table in such a way that one of its refracting surfaces AB lies normal to the rays falling from the collimator. (ii). Now rotate the prism through a very small angle, so that the incident rays make a small angle at the face AB. (iii). Now look from the side of AC, and locate the approximate position of the refracted image of the slit by your eye. (iv). Move the telescope in that position, and obtain the image of the slit on its cross-wires.

Note:—Sometimes students encounter great difficulty in getting the refracted image of the slit. It is because the angle of incidence of rays falling on the face AB is very small. Therefore, to obviate this difficulty, rotate the prism in the same direction to increase the angle of incidence.

(v). Rotate the prism in the same direction and follow the image of the slit through the telescope. Due to the rotation of the prism, angle of incidence increases, decreasing the angle of deviation. Consequently to again see the image of the slit, telescope shall have to move away from the base of the prism. (vi). Slowly go on rotating the prism, the angle of deviation will go on diminishing. (vii) A stage will come when the angle of deviation will become minimum, and the slit will not move in the same direction, but becomes stationary for some position of the prism. (viii). Any further rotation of the prism will increase the angle of deviation and therefore, the image of the slit shall start turning back and shall move in the opposite



Fig. 4

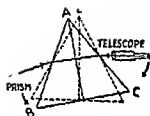


Fig. 9

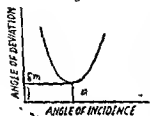


Fig 10

direction). In this position if the prism is rotated either clockwise or anticlockwise, the angle of deviation always increases, as shown in fig. (10). Consequently the image of the slit will move in the same direction, even when the table is turned in the either direction. (ix). Clamp the telescope where the image just turns back. (x). Now use the tangent screw and so adjust, that by turning the prism (in either direction), the image of the slit just reaches the intersection of the cross-wires and then turns back. (xi). This gives the position of minimum deviation. Note down this position of the telescope on the circular scale with the help of the two verniers V_1 and V_2 . Let this position of the telescope be denoted by x .

11. Remove the prism, and rotate the telescope so that it directly faces the collimator. Clamp the telescope, and by adjusting the tangent screw bring the image of the slit on its cross-wires. This direct reading gives the direction of the incident rays. Determine this position of the telescope by again reading the two verniers V_1 and V_2 . Let this be denoted by y .

12. Now to get the angle of minimum deviation determine the difference between the two readings of the same vernier for the two positions of the telescope, i. e. $\delta m = (x - y)$.

13. Rotate the prism so that now the light falls on the surface AC. In this case look from the side of AB. Repeat the whole procedure described above and determine δm .

14. Determine mean δm and then calculate μ .

Observations:—

[1] For the least count of the circular scale:—

(i) Value of one circular scale division (a) =°

(ii) Number of divisions on the vernier (n) =

(iii) Least count = $\frac{a}{n}$ = minute.

[2] Table for the determination of A :—

S. N.	Vernier	When reflection takes place at the face AC			When reflection takes place at the face AB			Difference between the two readings of the same vernier $2A = (a - b)$	Mean $2A$
		Main scale Reading	Vernier scale Reading	Total (a)	Main scale Reading	Vernier scale Reading	Total (b)		
1	V_1	1 2 3							
2	V_2	1 2 3							

[3] Table for the determination of δm :—

S. N.	Vernier	Reading for minimum deviation position			Reading for direct light			Difference between the two readings of the same Vernier $\delta m = a - b$	Mean δm
		Main scale	Vernier scale	Total (a)	Main scale	Vernier scale	Total (b)		
1	V_1	1 2 3							
2	V_2	1 2 3							

[4] Similar table can be drawn when refraction takes place from the other face of the prism.

Calculations :—

$$\angle 2A = \dots\dots\dots^\circ$$

$$\therefore A = \dots\dots\dots^\circ$$

Mean of $\delta m = \dots\dots\dots^\circ$ Now calculate μ by the relation,

$$\mu = \frac{\sin A + \delta m}{2} / \sin \frac{A}{2}$$

Result: $\mu =$ (no units). (For $\lambda = 5893 \times 10^{-8}$ cm.).

Precautions and sources of error:—1 All the adjustments described in the method should be properly done, otherwise the angle determined will not be accurate. Moreover, if the adjustments are faulty, it will be pretty difficult to obtain the images properly, and entails great wastage of time.

2. While reading the verniers, clamp the table and the telescope otherwise a slight movement of the two will spoil the whole adjustment.

3. Keep the width of the slit as narrow as possible, so that the image may be very sharp.

4. If the axis of rotation of the telescope and the table do not pass through the circular scale it will cause an error. To eliminate the error read both the verniers.

5. The voltage needed for sodium lamp is 440 volts. So be careful.

6. Once the lamp is illuminated it should be saved from all kinds of jerks and movements.

7. Sometimes due to faulty polishing or some such reasons you might get two images of the slit. Choose the brighter of the two and proceed if you are not able to investigate its cause and eliminate it.

Criticism:—The results obtained are quite satisfactory. The accurate measurement of the angles A and δ_m will depend upon the good adjustments of spectrometer, and proper placing of the prism on the table.

Modification 1. To determine the dispersive power of the material of the prism with the help of a spectrometer.

Hints:—1. In this experiment replace sodium lamp by a mercury lamp. It gives almost full spectrum.

2. Adjust the spectrometer as described in the main experiment and determine the angle of the prism A .

3. Place the prism properly on the table and obtain the spectrum of mercury light. Determine angles of minimum deviations for the two extreme colours and the mean colour. To get the angle of minimum deviation for a particular colour fix the telescope in such a position, that the image of the slit through it for that colour, turns back for the

anti-clockwise and clockwise movements of the prism (It has been described in detail in the main experiment). Then, take the direct reading of the telescope. The difference between these two readings gives the angle of minimum deviation for that colour.

4. Similarly determine angles of minimum deviation for other wave lengths. (Determine δ_m for red, violet and yellow colours). The direct reading should be taken a fresh for all colours. While obtaining minimum deviation position the prism is to be rotated, and hence the verniers may get disturbed.

5. Knowing A and the angle of minimum deviation, calculate refractive indices for each colour. As violet light is more refrangible than red, the angle of minimum deviation will be more for violet light than that of red light. Let μ_v , μ_r and μ be respectively the refractive indices for violet, red and mean yellow colour. As explained above μ_v will be greater than μ_r .

6. Knowing μ_v , μ_r and μ , calculate dispersive power by the following relation,

$$\text{or } w = \frac{\mu_v - \mu_r}{\mu - 1}.$$

Where w is the dispersive power.

Oral Questions :—

1. What do you understand by the refractive index of a material?
2. What are the factors upon which it depends?
3. What is monochromatic light?
4. What do you understand by the angle of minimum deviation?
5. How is it obtained in this case?
6. What are the main adjustments of the spectrometer and how are they done?
7. Explain the various parts of the spectrometer.
8. What type of eye piece is used in the telescope and why?
9. What do you understand by achromatic combination of lenses?
10. Why the upper surface of the prism table is ruled?
11. Why tangent screws are provided?
12. What do you understand by the dispersive power of the prism?
13. What type of spectrum you get by a mercury lamp?
14. Though sodium light gives two wave lengths we see only one line in this experiment, why?
15. Why the glow is reddish in the beginning in a sodium lamp?
16. Why neon is used and why is it excited earlier to sodium when its ionisation potential is higher?

EXPERIMENT No. 15

Experiment:—To determine the magnifying power of a telescope.

Apparatus:—The telescope whose magnifying power is to be determined, a scale with well defined graduations quite wide apart (preferably 4 cm. apart), measuring tap etc.

Description of the apparatus:—For the description of telescope, see experiment no. 14.

Theory:—Let PQ be the object and $P'Q'$ be its image formed by the objective of the telescope. Let the eye piece form the final

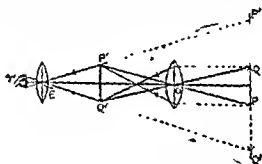


Fig. 1

image $P'Q'$ at the same place where the object PQ lies. As the length of the tube is quite negligible in comparison to the distance of the object from the eye, the angle subtended by the object at the objective may be taken to be equal to the angle subtended by the object at the eye. Let m be the magnifying power of the telescope, then, we have,

$$\begin{aligned}
 m &= \frac{\angle P'EQ'}{\angle POQ} = \frac{P'Q' / d}{PQ / d} \\
 &= \frac{P'Q'}{PQ} \dots\dots\dots (1)
 \end{aligned}$$

Where d is the distance of the object and the image from the telescope.

Suppose the object is a graduated scale placed in the position of the object PQ. If N divisions of the scale (i. e. divisions in the length PQ) as viewed directly by one of the eyes coincides with n divisions of the scale (i. e. divisions in the length PQ) as seen through the telescope with the other eye, we have,

$$m = \frac{P'Q''}{PQ} = \frac{N}{n} \dots\dots\dots (ii)$$

Method :—1. Place the given scale vertically at a distance of nearly 20' from the telescope. The distance selected should be such that the divisions marked on the scale may be distinctly visible through the naked eye.

2. Directly see the scale with one eye, and with the other eye, look for the image of the scale through the telescope. Adjust the distance of the objective from the eye piece in such a way, that the final image $P'Q''$ (fig. 1) is formed at the same distance as the scale, i. e. the image of the scale lies by its side, and there is absolutely no parallax between the directly observed scale and its image seen through the telescope.

3. Now concentrate your attention on a convenient portion of the scale, say, PQ as seen through the telescope. Count the number of the divisions on the scale in this portion i. e. between P and Q. It gives n .

4. Now look through the naked eye, for that portion of the scale which coincides with the portion PQ as seen through the telescope. Let it be $P'Q''$. Consequently P'' and Q'' will respectively coincide with Q and P. Determine the number of divisions on the scale in the portion $P'Q''$, as seen through the naked eye. This gives N .

5. Find the distance of the scale from the telescope.

6. Repeat the above procedure, and take readings for N and n

two or three times.

EXPERIMENT No. 16

Experiment:—To determine the value of horizontal component of earth's magnetic intensity at a place, using deflection and vibration magnetometers.

Apparatus:—A vibration magnetometer, a deflection magnetometer, a bar magnet, a stop-watch, a brass rod, a compass needle, a spirit level, a meter scale etc.

Description of the apparatus:—You are already very well familiar with these two types of magnetometers. The vibration magnetometer is shown in fig. 1, while the deflection magnetometer is shown in fig. 4

Theory —(a) If a magnet of magnetic moment M is freely suspended in the earth's horizontal field H and allowed to vibrate, it oscillates simple harmonically. It is due to the restoring couple $MH \sin \theta$ as shown in fig. (2). $H T$ is the periodic time of the magnet. It is given by,

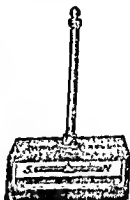


Fig. 1

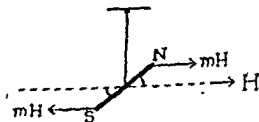


Fig. 2

$$T = 2\pi \sqrt{\frac{K}{MH}}$$

Where K is the moment of inertia of the magnet about an axis passing through its centre of gravity.

(b) If the same magnet is placed on the arm of a deflection magnetometer set in $\tan A$ position, the former will produce a magnetic field at the centre of the compass box. Let this field be F . Under the influence of the two fields F and H acting at right angles to each other,

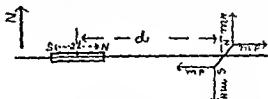


Fig. 3

the compass needle placed at the centre of the box will be deflected. In equilibrium, let the needle make an angle θ with the direction of H , then we have,

$$F = H \tan \theta$$

$$\text{But } F \text{ in } \tan A \text{ position} = \frac{2M}{(d^2 - l^2)}$$

$$\therefore \frac{2M}{(d^2 - l^2)} = H \tan \theta$$

$$\text{or} \quad \frac{M}{H} = \frac{(d^2 - l^2)}{2} \tan \theta \dots \dots (i)$$

Where l is half the effective length of the magnet, and d is the distance of the middle point of the magnet from the pivot of the compass needle. Dividing (i) by (ii) we get,

$$H = \sqrt{\frac{2MH}{d^2 - l^2}} = \sqrt{\frac{2M}{d^2 - l^2}} \dots \dots (ii)$$

$$\text{and} \quad K = \frac{M^2 L^2}{12} \dots \dots (iii)$$

Where M , L and H are respectively the mass, length and field of the magnet.

Method — To adjust the vibration magnetometer :— 1. Level the instrument by levelling screws. When it is in level the equilibrium thread will pass through the centre of the hole, without touching the sides.

2. Put the magnetometer in the magnetic meridian; usually a line is marked on the horizontal mirror of the magnetometer or a thread is stretched. Keep a compass needle on it and rotate the box till the needle is parallel to the linear thread. Draw the boundary line round the box. If no line or thread is provided, draw the magnetic meridian with the help of a compass needle, and place the longitudinal edge of the magnetometer along it.

3. There should be no twist in the suspension when a magnet is put in the stirrup. The stirrup should remain pointing in north south direction. To achieve this, put a brass rod in the stirrup and see that brass rod comes to rest in the magnetic meridian. If it does not, rotate the upper screw head till the rod is in the magnetic meridian. The brass rod may take a long time to come to rest and therefore, for this adjustment see that the brass rod equally deflects on both sides of the meridian. Always keep your eye vertically above the box.

To determine T :— 4. Remove the brass rod, and gently put the given bar magnet on the stirrup. Bring the magnet to rest by stopping any kind of motion by hand. Close the box.

5. Bring one end of any other magnet from outside near one of the ends of the suspended magnet, till the latter is slightly rotated from its position. Remove the second magnet, and allow the suspended magnet, to oscillate about its centre of gravity.

6. Start the stop watch when the magnet crosses the mean position say from left to right. When it again crosses the mean position from left to right, it is said to have completed one oscillation. Determine time for 15, 20, and 25 oscillations respectively. Find time for one oscillation from each observation, and then determine mean periodic time T .

7. Find the length (L) and breadth (B) of the magnet by a meter scale, and its mass (M) by a physical balance.

To set the deflection magnetometer in tangent A position:—

8. Rotate the compass box which is kept on the wooden board till the line joining 0-0 division of the circular scale is in line with the length of the scale (along the line marked on the scale).

9. Level the compass box with the help of a spirit level.

10. Now rotate the arms of the magnetometer (wooden board) without disturbing the compass box till the pointer comes on 0-0 reading.

this case the pointer will be parallel to the arms, and the needle will be perpendicular to the arms. H will be acting perpendicular to arms.

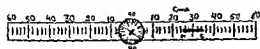


Fig. 4

for safe guard mark the position of the arms, so that any disturbance from the set position may become apparent.

To determine the deflection θ :- 11. Take the same magnet (in the vibration magnetometer) and place it length wise along the arm of the magnetometer, such that its geometrical axis produces a line through the pivot of the needle. Adjust the magnet in such a way that the deflection is near about 45° . Note this distance (x) of the point of the magnet from the pivot of the compass needle. Note deflection of both the ends of the pointer. This gives θ .

12. Reverse the face of the magnet keeping other things same and read both the ends of the pointer. This makes four readings.

13. Reverse the magnet pole to pole and keeping the distance same note both the ends of the pointer.

14. Reverse the face of the magnet and again read both ends of the pointer. This makes eight readings.

15. Place the magnet on the west arm at the same distance, as in the above procedure taking eight readings as explained above.

16. Take means of these sixteen readings. This gives θ . Take two sets of observations for θ after changing J , if there is time, otherwise one set will do.

7. Find the value of M/H by formula (i)

8. Determine the value of $\frac{M}{H}$ separately for every set and find

the value of $\frac{M}{H}$ using formula (ii).

Find the value of H by formula (iii).

Observations:—

[1] Table for vibration magnetometer.—

S. N.	Time for oscillations in sec.			Time for one oscillation in sec.			Mean T in sec.
	15	20	25	I	II	III	

(i) Length of the magnet = cm.

(ii) Breadth of the magnet = cm.

(iii) Mass of the magnet = gm.

[2] Table for deflection magnetometer.

S. No.	Distance of the magnet d in cm.	Magnet on west arm				Magnet on east arm				Mean θ	tan θ
		N-pole to- wards east		N pole to wards west		N-pole to- wards east		N-pole to wards west			
		Face	Face	Face	Face	Face	Face	Face	Face		
		A	A	A	A	A	A	A	A		
		up	down	up	down	up	down	up	down		
one end	other end	I	II	I	II	I	II	I	II	I	II
1											
2											
3											

Calculations:—

1. $MH = \dots\dots\dots$

2. $\frac{M}{H} \begin{cases} 1. = \\ 2. = \\ 3. = \end{cases} \dots\dots\dots$

$$3. \text{ Mean } \frac{M}{H} =$$

$$4. H = \dots\dots\dots \text{gauss.}$$

Precautions and source of error :—

[A] For deflection magnetometer :—

1. Reading should be taken without parallax i. e. keeping the head vertically above the pointer so that while taking the readings, the image of the pointer in the plane mirror may be exactly below the pointer.

2. All magnetic materials should be removed away from the magnetometer.

3. The magnet should be placed so that its magnetic axis when produced should pass through the pivot of the needle. If this is not so the eight readings obtained for θ in the method will be much removed from the mean value.

4. Before noting the deflection tap the compass box gently.

5. The distance should be so adjusted that the deflection of the needle is near about 45° . In the neighbourhood of 45° the percentage error made in reading the deflection is considerably reduced.

6. For greater accuracy d should be kept fairly large compared to l , so that in determining $(d^2 - l^2)$, the percentage error is reduced. Because it is very difficult to find out exactly half the effective length l of magnet.

7. The needle may not be pivoted at the centre of the circular scale. To correct for this eccentricity, both ends of the pointer are read.

8. The geometric axis and magnetic axis of the magnet may not coincide, hence, the face of the magnet is reversed pole to pole.

9. The poles of the magnet may not be symmetrically situated. To eliminate this error the magnet is reversed pole to pole.

10. Zero of the linear scale may not coincide with zero of the circular scale; that is why readings are repeated on the other arm.

[B] For vibration magnetometer :—

11. It is necessary to suspend the magnet in such a way that its centre of gravity may be exactly below the suspension, and the magnet may remain perfectly horizontal. This is done by providing a stirrup arrangement.

12. Look vertically downwards to count the number of oscillations.

13. The amplitude of the oscillations must be very small (Below 5° , so that $\sin \theta = \theta$).

14. Remember that the length and breadth of the magnet are the two sides perpendicular to the axis of suspension. Don't confuse breadth with thickness of the magnet.

15. The magnet must perform vibrations in a horizontal plane without twisting up or down.

17. For greater accuracy, the suspension fibre must be free from torsional reaction. Hence the suspension should have no initial twist. That is why horse hair is preferred.

Criticism :—The value of H obtained by this method is not completely accurate due to the following reasons.

(1) It is very difficult to determine accurately the effective length l of the magnet. If d is increased θ will not remain 45° , therefore it is difficult to satisfy these two conditions simultaneously.

(2) The friction at the pivot of the needle is not completely removed, it causes an error in the measurement of the deflection.

(3) The length of the needle is not sufficiently short, therefore, it is not perfectly justified to assume that the needle is moving in a uniform field. Thus tangent law cannot be rigorously applied.

(4) The moment of inertia of the stirrup cannot be completely neglected as is done in deriving the theory, hence error is introduced.

(5) Furthermore, the suspension fibre is neither completely free from torsional reaction, nor it is initially twistless.

Therefore, if greater accuracy is the aim, Kew magnetometer should be employed.

Modification :—To determine the magnetic moment M of a magnet.

Hints :—Find the value of $\frac{M}{H}$ and MH as shown above. Multiply the two to get the value of M^2 , and hence determine M .

Oral questions :—

1. Explain total intensity of earth's magnetic field, its horizontal

and magnetic meridian. 2. Why do you use H and not I in the experiments of deflection and vibration magnetometers? Why this method is called absolute method? 4. Is this method accurate? 5. Define magnetic moment and pole strength of a magnet. 6. Why is magnetic needle made small, while the pointer is longer? 7. Why the pointer is made of aluminium? 8. Can it be made from iron? 9. Why is the mirror provided in the box? 10. What is the necessity of taking sixteen readings? 11. What is a tangent law, and how is it made use of in this experiment? 12. How do you set a deflection magnetometer in tan A or tan B position of Gauss? 13. Which position is preferable and why? 14. Why should the deflection be adjusted in the vicinity of 45° ? 15. What is simple harmonic motion? 16. Explain moment of inertia. 17. Why stirrup is used for placing the magnet? 18. Why is it made so light, can you suspend the magnet from the suspension thread, instead of putting it in a stirrup? 19. Why is it necessary to remove the twist in the suspension? 20. What type of suspension is preferred and why? 21. Can you take a cotton thread? 22. Why should the magnet oscillate in a uniform magnetic field? 23. Why a brass rod is used to remove the twist? 24. Why the magnet should remain perfectly horizontal? 25. Why the amplitude of vibrations should be small? 26. Will the period of oscillation alter if the magnet is rotated by 90° i. e. breadth becomes depth?

ELECTRICITY

General Instructions :— Electrical experiments are easy to perform, providedly they are done in a *proper* way. To achieve efficiency and avoid difficulties, the following points must be kept in view during their performance.

1. Before the commencement of the experiment, it is very essential for you to draw a neat circuit diagram showing clearly the different connections. Keep this diagram in front of you and accordingly arrange the apparatus on the table. In no case it is advisable to depend upon memory.

2. Make sure that the various instruments which you would use in a particular experiment are of the *proper range*.

3. After putting the apparatus properly on the table, see that the connecting wires used to connect them are not too long. Their lengths should be just necessary. Make their ends naked and clean them. Connect their ends to the instruments tightly. It is extremely important to verify that the connections made are properly *tight*. If the connections remain loose, it is possible that the instruments may not give deflection.

4. Look to it that the connections may not become jumbled up at any place. Connections must be clearly distinguishable on the table. If there is more than one circuit, all the circuits should be clearly distinguishable. This precaution will very much facilitate to trace the faults, if there are any.

5. Always use a key in the circuit. Pass current in the circuit only for a short interval of time, i. e., when you are taking observations.

6. See that the instruments which you are using may not get damaged due to the flow of excessive currents through them. Take care while passing current through the circuit do not forget the range of the various instruments connected in the circuit. While using a galvanometer, always put a shield across it in the beginning. It must be noted only when the current passing through the galvanometer has become steady.

7. When it is necessary that the current flowing in the circuit should remain steady, use such batteries which possess constant e. m. f., and have large capacities (e. g. storage batteries). In circuits where steady currents are not necessary, primary cells may be employed [it is due to this reason that we employ Leclanche cell in experiments on Post-office box and Carey Foster's bridge].

8. While using a resistance box, see that the plugs in the gaps are tight.

9. To change the resistance in the circuit always use a rheostat, and not a resistance box.

10. Before starting the experiment see that the batteries or the cells which you are using possess the necessary e. m. f. or not.

Description of the apparatus:—

1. **Keys:—**The current can be stopped or started in the circuit with the help of keys. They are of two types (i) plug keys (ii) tap keys. In case of plug keys, a plug has to be inserted in the gap to start the current. There are one, two, three or four plug keys. A four plug key is used as a reversing key. Keys are generally represented in diagram by the symbol K. A tap key has to be pressed to complete the circuit.

2. **Reversing key or commutator:—**It has four terminals two fixed and two movable. The movable terminals can alternately be put in contact with the fixed terminals. It is employed to reverse the direction of the current in the circuit.

3. **Moving coil galvanometers (Suspended coil type):—**

Description:—It consists of a permanent horseshoe magnet N.S. The pole pieces of the magnet are concave having a cylindrical air gap in between them. A coil of insulated copper wire of many turns is suspended between them. The coil is either rectangular or circular in shape. It is suspended by means of a phosphor-bronze strip A fixed to the central band H forming one of the terminals of the instrument.

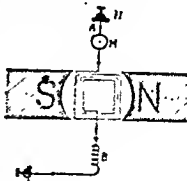


Fig. 1

Phosphor bronze is chosen because it is good conductor and its couple per unit twist is small. The current enters the coil through the strip. The other end of the coil is connected to a coiled hair spring *B*, also of phosphor bronze. The spring is connected to the other terminal of the instrument. Current leaves the galvanometer through the spring. The spring and the strip provide the controlling couple. The strip carries a mirror *M*. By lamp and scale arrangement the deflection of the mirror can be found out.

Usually a soft iron core of spherical or cylindrical shape as shown in fig. 2 is fixed at the centre of the coil. This concentrates the lines of force in the coil increasing the controlling field and making it more radial. The pole pieces are made concave or circular to make the field radial as shown in fig. 2. The coil is so suspended in the air gap that the magnetic lines of force due to the permanent magnet are parallel to its plane. As the field becomes radial, the lines of force always remain parallel to the plane of the coil, so long the coil rotates in the vertical plane. The coil may be in any position, the lines will always cut its vertical sides at right angles.



fig. 2

Adjustments:—The instrument is carefully levelled so that the coil is free to rotate in the magnetic field.

Working:—When a current is passed through the coil, equal forces act on its two sides in opposite direction. These two forces together constitute a couple which is called a *deflecting couple*. This tends to set the coil at right angles to the direction of the magnetic field (field due to the magnet). On the other hand the torsion present in the phosphor-bronze strip opposes the motion of the coil and generates another couple. This is called the *controlling couple*. Under the influence of these two couples, the coil sets in an intermediate position where the moments due to both of the couples are the same. The deflection of the coil is measured by lamp and scale arrangement.

Theory:—Let H be the field due to the permanent magnet, i the strength of the current passing through the coil, l the length of the vertical side of the coil, b the breadth of the coil and n the number

of turns of wire in the coil. When current passes through the coil each of its vertical sides experiences a force equal to Hil dynes. As there are n turns, the total force experienced is equal to $nHil$. These two forces act in opposite direction and the perpendicular distance between them is b . This is strictly true in the deflected position for a galvanometer in which the pole pieces are

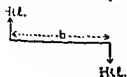


fig. 3

concave and the field is radial.

Then, the moment of the deflecting couple $= n i H l b$.

If θ is the deflection and T is the moment per unit twist generated in the suspension strip, the moment of the restoring couple is $= T\theta$. In equilibrium the two moments of the couple are equal.

$$\therefore n i H l b = T \theta$$

or
$$i = \frac{T}{n H l b} \theta \quad (\text{but } l \times b = A \text{ the area of the coil})$$

or
$$i = \frac{T}{n H A} \theta$$

or
$$i = k \theta. \quad [\text{where } k = \frac{T}{n H A}, \text{ as } T, n, H \text{ and } A \text{ are constants, and } k \text{ is a constant}]$$

This is called the constant of the galvanometer.

Hence
$$i \propto \theta$$

Thus the current passing through the coil is directly proportional to the angle of deflection. If k is known, i can be calculated.

Sensitiveness of a moving coil galvanometer :— From relation $i = \frac{T}{n H A} \theta$, we know that for the same value of i , θ is large when k is small. For k to be small, T should be small and n , H and A should be large. If A and n are very much increased, the resistance of the instrument increases too much. Hence, to increase sensitiveness T is decreased and H is increased. As phosphor bronze has more tensile strength and smaller value of T , it is extremely suited for using it in suspending the coil. In better types of galvanometers quartz suspension coated with a conducting layer is used. Such a suspension has a very low value of couple per unit twist. H is increased by taking a more powerful magnet. The strength of the

magnet is increased by special processes which are a commercial secret and by making it in laminas form. Addition of a soft iron piece at the centre of the coil helps also in increasing H .

As this form of galvanometer was first of all developed by D'Arsonval, it is also called D'Arsonval galvanometer. It is very sensitive. It can measure currents up to 10^{-9} amp.

Damping of a galvanometer:—Even when current ceases to pass, the coil does not come to rest quickly. In order to, make it dead beat, i. e., in which the coil comes to rest quickly, its oscillations are damped. It is done by winding the coil upon a light conducting frame. The induced eddy currents produced in the frame oppose the motion of the coil, and brings it quickly to rest.

4. **Moving coil galvanometer, pivoted type:**—In this case a coil of copper wire is wound upon an aluminium frame. Instead of suspending the coil, it is pivoted by means of a spindle fixed in bearings. The coil is placed between the two concave pole pieces of a permanent magnet NS as shown in fig. 5. The coil is so pivoted that its plane always remains parallel to the magnetic field. At the centre of the coil an iron core is fixed which concentrates the field within the coil. One end of the coil is connected to a hair spring placed above the coil. The other end of the hair spring is connected to one of the terminals of the instrument. Similarly, the other end of the coil is connected to the other hair spring placed below the coil. The other end of this spring is connected to the second terminal of the instrument. The two springs are coiled in opposite direction. They provide the controlling couple to balance the deflecting couple. [See Fig. 6]. A light pointer attached to the spindle of the coil, at right angles to its plane. The pointer moves over a circular scale calibrated in parts of equal length. The principle of working of this instrument is exactly the same as in the case of suspended type.



Fig. 4.

Though the pivoted type of galvanometers are a bit less sensitive than the former type, they are *portable and dead beat*. The pointer quickly

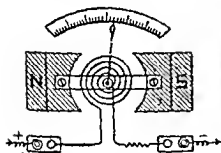


fig. 5

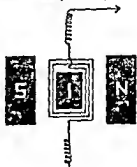


fig. 6

comes to rest. They are generally employed in all electrical experiments.

3. **Ammeter.** It is a moving coil pivoted type galvanometer with the difference that a low resistance shunt is put across the coil of a galvanometer. It is used to measure current. The shunt serves two purposes,

(1) It diverts most of the current from the galvanometer and so only a *fraction of the main current passes through the latter* (a) It reduces the equivalent resistance of the system formed by the galvanometer and the shunt. Thus, an ammeter has an *extremely low resistance. Theoretically speaking, it is zero.* The circular scale is calibrated in amp. or milli amp. by some standard current measuring instruments. The pointer rests on zero, marked on the left hand side of the scale. It moves towards right when a current is passed through it. Actually, if one amp. current is flowing in the circuit a small fraction of it enters the coil which gives deflection. This deflection is called one amp. and so on. Thus, it is calibrated.

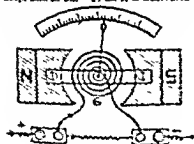


Fig. 7

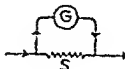


Fig. 8

resistance and low temperature coefficient. The wire for reasons already given is either of constantan or manganin. The wire is wound



Rheostat

Fig. 13

on a non-conducting cylinder, generally of china clay. Each turn is insulated from the other. A sliding contact S slides over the cylinder and makes contact with naked portion of the wire. C is a terminal

connected to the thick rod along which S moves. If A and C are connected in a circuit, and if the current enters the rheostat at A, it passes through the wire between A and S and leaves at C. It does not flow between S and B. If S is moved towards A, the current passes through lesser and lesser number of turns. Consequently, the resistance decreases and current increases. In stead of this, if S is moved towards B, more resistance is introduced in the circuit and the current decreases. Similarly, if B and S are connected in the circuit, current passes through BS. By moving S towards B, the resistance in the circuit decreases and *vice versa*. If A and B are connected in a circuit, it

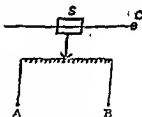


Fig. 14

behaves as a fixed resistance. On the top of the instrument is usually written something like 22 ohms, 2.5 amp. It means that the maximum current which can be passed through the rheostat is 2.5 amp. without damaging it. If current exceeds 2.5 amp., coil will be burnt off due to excessive heating. 22 ohms denote the maximum resistance it can offer when connected between A and B.

9. Hot wire ammeter :—When an electric current flows through a metallic wire, heat is produced, and consequently it expands. The elongation so produced has been utilised to measure currents in a hot wire ammeter. The current which is to be measured is allowed to flow through a fine wire (of platinum-iridium alloy of about 0.1 mm. diameter) stretched horizontally. At the middle of this wire is attached another wire of phosphor-bronz. The other end of the latter is attached to an unspun silk thread. The silk thread after passing round a pulley is fastened to a spring fixed in the instrument. The spring keeps the wire taut. The pulley is mounted over a spindle, the latter carries a pointer which moves over a circular scale.

plate. This is on account of *chemical affinity* existing between the ions and the plates. Ions are not neutral atoms but parts of atoms carrying either a positive or a negative charge. The agency which

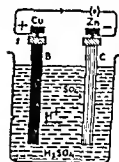


Fig. 15
the plates are the same.

does the work of moving these ions within the cell is called the *electromotive force*. This comes into existence on account of *chemical reactions*. Thus, within the cell the positive charge moves from zinc to copper plate giving rise to an electric current. As explained above, this current which flows from zinc to copper within the cell is due to the *electromotive force*. It remains constant so long as the solution and

current ultimately stops. This defect is known as polarisation. This can be explained in two ways—

(a) The layer of neutral gas formed around the positive plate offers a great resistance to the current within the cell. As the thickness of the layer increases, the resistance also increases. Ultimately it becomes so high that the current totally stops flowing within the cell.

(b) As the fresh incoming hydrogen ions carrying positive charge cannot reach the copper plate, they hand over their charges to the neutral layer. Thus, an electric field is set up between the layer of hydrogen and zinc plate. This is called *back electromotive force*. It tends to send current in the opposite direction. If it becomes quite high, it completely impedes the motion of hydrogen ions towards the copper plate. It results in the stoppage of the current within the cell.

Polarisation can be removed by preventing the formation of hydrogen layer around the plate. This can be done in two ways—
(i) *mechanical* and (ii) *chemical*. In mechanical method we have to use a mechanical device like a brush to remove the hydrogen layer. But this is not very efficient. In chemical method we oxidise hydrogen as soon as it is formed. Different oxidising agents have been employed in different cells. The chemicals which are used to remove hydrogen in these cells are called *depolarisers*.

(ii) *Local action*:—Pure zinc does not react with sulphuric acid unless a contact is established between zinc and copper. Certain impurities, e. g., carbon, arsenic, iron, lead etc. are always present in ordinary zinc used in making zinc plates. These impurities act with acid forming miniature cells consisting of impurity, acid and zinc. These miniature cells so formed cause local currents to flow in the zinc rod. This unnecessarily consumes the zinc rod because the local currents so formed do not contribute to the main current. This is a sheer wastage of zinc and is known as *local action*.

This defect can be remedied by coating the zinc rods with a mercury layer. This process is known as *amalgamation of zinc*. Zinc dissolves in mercury and comes on the surface layer, while the impurities remain inside the mercury coating. Thus, the contact between the two is broken. This stops the local action.

Cells:—Following are a few important primary cells. Each one of them has a different polariser and a different electrolyte.

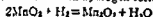
12. Leclanche Cell :—

Construction—It consists of a glass vessel containing a solution of ammonium chloride (NH_4Cl). A porous pot is placed in the middle of the vessel. A carbon rod is placed at the centre of the pot. Powdered manganese dioxide (MnO_2) mixed with pieces of carbon is packed around the rod in the porous pot. A zinc rod is immersed in the solution. Carbon and zinc respectively forms the positive and negative plate of the cell. The electrolyte is NH_4Cl .

Working—Zinc acts with ammonium chloride forming zinc chloride and positively charged ions of hydrogen



The ions penetrate through the porous put and carry the charge to the carbon rod. The potential of the carbon rod increases, MnO_2 acts as a depolariser. It acts on hydrogen forming water,



Being a solid, it is a *weak oxidising agent* and is, therefore, unable to remove hydrogen quickly. Therefore, the cell gets polarised after a little use. But, if, some rest is given to the cell, the deposited hydrogen is converted into water and the cell starts working again. Thus this type of cell is suitable only for those functions where *intermittent current is needed* e. g., in telegraphs, telephones, electric bells etc. It is quite cheap and sturdy. Its e. m. f. is 1.45 volts. The local action is eliminated by amalgamating the zinc rod.

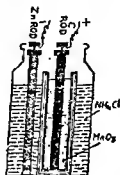


fig. 16

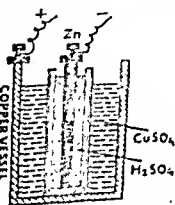


fig. 17

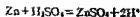
13. Daniell Cell :—

Construction :—It consists of a copper vessel filled up with concentrated solution of copper sulphate. The copper vessel acts as the positive plate. In the middle of the vessel is placed a porous pot containing dilute sulphuric acid and an amalgamated zinc rod. The zinc rod forms the negative plate.

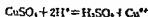
Working :—Zinc reacting with H_2SO_4 forms $ZnSO_4$ and hydrogen.

Positive ions of hydrogen are

deposited in the reaction and the potential of the zinc plate is lowered,



The hydrogen ions so produced travel towards the copper vessel reacting with CuSO_4 . Copper Sulphate Solution acts as a depolariser.



Neutral solution of sulphuric acid is formed and positively charged ions of copper are liberated. The ions travel towards the copper vessel. They give charge to the vessel, and are deposited. Thus, the potential of the copper vessel increases. The e.m.f. of this cell is 1.1 volt. The liquid depolariser used is better than the solid depolarisers. Therefore, the cell is almost free from polarisation. Local action is eliminated by amalgamating the zinc rod. This type of cell can be used where steady current is to be drawn.

14. Bunsen's Cell :—

Construction:—It consists of a porous pot filled with concentrated solution of nitric acid. A carbon rod is placed in the pot. The rod acts as the positive plate of the cell. The porous pot is placed in a larger porcelain vessel containing dilute solution of sulphuric acid. An amalgamated zinc cylinder is placed between the vessel and the porous pot. It remains immersed in H_2SO_4 and acts as the negative plate.

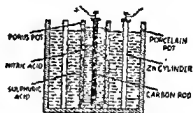


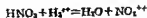
Fig. 18

An amalgamated zinc cylinder is placed between the vessel and the porous pot. It remains immersed in H_2SO_4 and acts as the negative plate.

Working:—The reactions take place in H_2SO_4 while HNO_3 acts as a depolariser.



Zinc reacts with H_2SO_4 forming ZnSO_4 and positive ions of H_2 are liberated. These ions travel through the porous pot acting with HNO_3 .



Molecules of NO_2 carry the positive charge to the carbon rod, and the potential of the rod increases. NO_2 dissolves in concentrated HNO_3 . This cell is not much in use because the fumes of NO_2 are very injurious and disagreeable. Its e.m.f. is 1.95 volts. Polarisation is also not completely removed in this cell.

15. **Grove's cell** :—It is exactly similar to that of Bunsen's, except that the carbon rod is replaced by a platinum foil. It is not in common use.

16. **Bichromate cell** :—**Construction.** It consists of a glass bottle containing dilute solution of sulphuric acid. A few crystals of potassium dichromate are placed in the acid. The crystals of potassium dichromate act as a *depolariser*. Two interconnected carbon plates *cc* are placed in the bottle as shown in fig. 19. The plates act as the positive plate. A zinc rod forming the negative plate is placed between the carbon plates

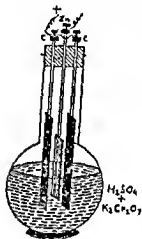
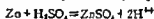


Fig. 19

Working:—Zinc reacting with H_2SO_4 forms zinc sulphate and hydrogen ions



The positive ions of hydrogen so liberated hand over their charge to the carbon plates. They are converted into water by the depolariser $K_2Cr_2O_7$. Actually it is the chromic acid formed which acts as a depolariser. Its e.m.f. is 2 volts.

As the depolarisation is not complete, the current falls off soon. It is employed only when strong currents are required for a very short duration.

17. **Standard cells** :—As the current is drawn from the cells described above, generally their e.m.f.s. decrease. Therefore, they can not be used where constant e.m.f. is required. Hence, for calibration and comparison purposes standard cells are required. Their e.m.f.s remain constant and do not change with temperature. They are used only for calibration purposes. They are mainly of two types:—

(I) **Cadmium cell** :—**Construction** :—It consists of two limbs made up of glass joined by a horizontal tube as shown in fig. 20. It forms a H shaped vessel. Pure and dry mercury is placed at the bottom of one of the limbs. It acts as the positive pole. Above the level of mercury paste of mercurous sulphate is placed which acts as the depolariser. At the bottom of the other limb an amalgam of mercury

and cadmium is placed which acts as the negative pole in the vessel, saturated solution of cadmium sulphate is filled in. The level of the solution in the vessel is kept a little above the horizontal tube. To ensure the saturation of cadmium sulphate solution, crystals of cadmium sulphate are placed as shown in

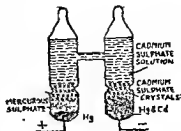


Fig. 20

fig. 20. Two platinum wires are fused at the bottom of both the limbs, its e.m.f. is 1.0183 volts at 20°C . Current is never drawn from this cell. It is mainly used for comparison purposes only.

(2) **Estimer Clarke cell** :—It is similar to cadmium cell except that cadmium is replaced by zinc through out. It is often shaped like dry cells.

18. **Dry cells** :—They are nothing but modified forms of Leclanche cells. They are extensively used in torch lights, radios, etc. Every body is quite familiar with these types of cells.

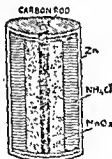


Fig. 21

Construction :—It consists of a carbon rod to which is attached a brass cap. It forms the positive pole. The rod is placed in a muslin bag containing powdered charcoal, MnO_2 and a little gum. Around the bag is placed a paste of NH_4Cl , saw dust and a little zinc chloride in a zinc container. The zinc container forms the negative plate of the cell. A non conducting diaphragm is placed at the bottom and the top of the container to insulate it from the carbon rod. To allow the ammonia gas to escape, outlets are

provided in the muslin bag. The e.m.f. of this cell is 1.4 volts.

Internal resistance of a cell :—When a current passes through a cell, it has to pass through the electrolyte constituting that cell. The electrolyte offers certain amount of resistance to the passage of the current through the cell. This resistance is called the internal resistance of the cell. It varies from cell to cell. The primary have more internal resistance than the secondary cells.

The internal resistance of a cell depends upon the following factors,

(1) **The electrolyte** :—Different electrolytes offer different resistances.

(2) **Size of the plates** :—The larger is the size of the plates the lesser is the resistance offered and *vice versa*.

(3) **The nearness of the Plates**—The nearer are the two plates in the cells, lesser is the resistance offered and *vice versa*.

(4) **Strength of current** :—As the strength of the current drawn from a cell is increased, its internal resistance, in general decreases.

19 **Secondary cells** :—The e. m. f. developed in the primary cells is due to the chemical reactions taking place in their electrolytes. These chemical reactions are *irreversible*. After the production of the current the products of the reaction are wasted and cannot be transformed into original substances. But, there are other types of cells also in which the reactions are reversible and the products are not wasted. They are called *secondary cells* or *accumulators*.

When a current is made to pass through them, electrolysis takes place. Electrical energy is converted into chemical energy and is stored up in the cell. When the cell is connected to an external circuit, i. e., when a current is drawn from it, the chemical energy is converted back into electrical energy. *The original substances are again obtained.* Thus, the difference between a primary cell and a secondary cell is that in the primary cell chemical energy is converted into electrical energy direct, while in secondary cells electrical energy is first stored up in the cell as chemical energy, and this chemical energy is then converted into electrical energy. As the current is obtained by secondary reactions, they are called secondary cells. They are also called accumulators or storage cells as charge is accumulated or stored in the form of chemical energy. The process of converting electrical energy into chemical energy is known as *charging the cell*, while the process of getting back the electrical energy from chemical energy is known as *discharging it*.

There are two types of secondary cells: (i) Acid accumulators.

(1) Acid accumulator:— It consists of a glass vessel containing dilute sulphuric acid. Two lead plates as shown in fig. 22 are dipped in the solution. The plates are constructed in the form of grids or net works as shown in fig. 23, in the interstices of which is filled litharge (PbO). PbO acts with H_2SO_4 to form $PbSO_4$. Thus, to start with both the plates contain a mixture of PbO and $PbSO_4$. The density of the acid is between 1.17 to 1.19.

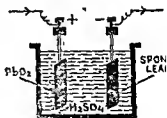
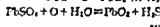


Fig. 22

Charging:—Current is passed in the cell from an external source, say, from D. C. mains or dynamo or battery charger. In

to this, hydrolysis of water takes place. Hydrogen is evolved at the cathode while oxygen travels towards anode. The reactions are as follows:—

At the positive plate:—



At the negative plate:—

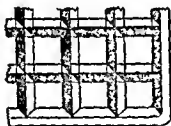
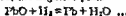
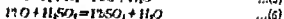


Fig. 23.

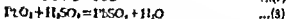
By charging, positive plate is converted into dark brown peroxide of lead, while the negative plate becomes spongy lead. According to reactions (3) and (4) the amount of sulphuric acid increases in the solution; hence its density increases because H_2SO_4 denser than water. When it is completely charged, the density is about 1.25 to 1.28. Its e. m. f. is near about 2.2 volts.

Discharging:—Current can be obtained from such a cell, when it has been charged. When current is drawn in the external circuit, it flows from anode to cathode in the outer circuit, and just in reverse direction in the cell. Again the hydrolysis takes place. But, the direction of the current has reversed, hydrogen is evolved at anode and oxygen at the cathode according to the equations:

At the positive plate :—



At the negative plate :—



The reactions are self explanatory. When the cell is discharged, the original products PbO and PbSO_4 are again obtained. Water is formed during discharge, lowering the density of sulphuric acid. It again reaches the initial value of 1.17 to 1.19. Thus, the cell regains its initial condition, and can be recharged. To know about its electrical condition the specific gravity of the acid should be occasionally measured by a hydrometer.

The e. m. f. of such a cell remains almost constant at about 2 volts. When its e. m. f. falls suddenly to 1.8 volt, it is considered as having discharged fully. Use of battery having e. m. f. less than 1.8 volts is forbidden.

Notes :—(1) It should not be charged by passing a heavy current; otherwise the plates get damaged and the material *peels off* falling upon the base.

(2) When it discharges, its e. m. f. becomes near about 1.8 volts and specific gravity equal to 1.17. No current should be taken from this cell after this stage; otherwise insoluble lead sulphates are formed greatly affecting the efficiency of the cell.

(3) The capacity of the cell is expressed in *ampere-hours*. This shows the total amount of current which can be drawn from such a cell when it is fully charged. If the capacity is 40 ampere hours, it can give a current of 40 amperes for one hour, or a current of 10 amperes for four hours etc. Greater is the size of the plates and greater is their number, greater is its capacity and rate of discharge.

(4) Its terminals should never be short circuited; otherwise heavy current passes through it damaging the plates. This is due to its internal resistance being very low.

Generally, to increase its capacity instead of two plates a number of plates are taken. The plates are arranged in parallel alternately connected to the two electrodes. By putting them in parallel their

Advantages:—The accumulator possesses the following advantages over that of a primary cell :—

(1) It has got a number of plates which possess large area, and are placed very close to each other. This arrangement extremely reduces the internal resistance of the cell which is of the order of 0.0001 to 0.001 ohm. As it has got a high e. m. f. and low internal resistance, heavy and steady currents can be obtained from such a cell. This is not possible in the case of a primary cell which has very high internal resistance.

(2) As the reactions are reversible, it can be recharged.

(3) It can be used for lighting buildings, operating cars, etc, where strong currents are needed.

Despite all these advantages, it has got a few disadvantages also. It is very heavy and therefore, cannot be transported easily. Its cost is quite appreciable in comparison to a primary cell. Apart from this, it requires very careful handling. If it is not properly charged at the proper time, it will be rendered useless.

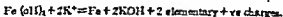
(ii) **Alkali accumulator (Edison cell):**—It consists of a steel plated container containing 20% solution of potassium hydroxide which constitutes the electrolyte. The positive plate is made up of nickel plated perforated steel tubes filled with nickel hydroxide mixed with finely divided nickel. The negative plate is also in the form of perforated iron tubes filled with iron oxide containing finely divide iron. Thus, the +ve plate is of nickel while -ve plate is that of iron, and hence it is called NI FE cell.

Charging:—Current is passed in the cell from an external source so that it passes from the nickel oxide plate to the iron oxide plate with in the cell. The reactions are as follows :—

At the positive plate :—



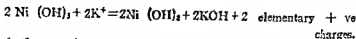
At the negative plate :—



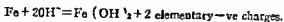
Thus, during charging positive plate is converted in to $\text{Ni}(\text{OH})_3$ while the negative plate is reduced to iron.

Discharging :—During discharge, the current flows in the cell in the reverse direction given by the following reactions :—

At the positive plate :—



At the negative plate :—



The cell can be recharged after discharge. It is clear from the reactions that the concentration of KOH remains the same during charge and discharge. When fully charged its *e. m. f.* is about 1.35 volts

Advantages :—1. It has got great mechanical strength, and is less sensitive to mechanical vibrations. As the tubes are quite strong, there is no danger of buckling of the plates. Hence it possesses longer life.

2. It can be rapidly charged or discharged, without any damage to the plates. It can even withstand short circuiting and reverse charging. Hence, it requires very little attention and care.

3. For the same capacity it is only half as heavy as the lead accumulator.

4. Even when left idle for a longer time its *e. m. f.* remains constant.

Despite all these advantages, its cost is very high. It is costlier than a lead accumulator. Its efficiency is also quite low compared to lead accumulator, and its *e. m. f.* continuously falls during discharge.

Charging of an accumulator :—(a) Where D. C. (Direct current) supply is available, connect the accumulator to be charged to D.C. mains with a variable high resistance in series. High resistance can be obtained by employing an electric bulb. The current from the mains should enter the cell from the +ve terminal. The current in the cell is adjusted to the desired strength with the help of the variable high resistance. It is very important to see that the current flowing through the cell is kept at a value specified by the manufacturer. Usually it is written on the cell itself, as to at which strength of the current it is to be charged. When a lead accumulator is fully charged the density of the acid becomes 1.25 gm. per c.c. which can be tested with the help of

a hydrometer. When the alkali accumulator is fully charged its e.m.f. becomes 1.35 volts.

(b) When the supply available at a particular place is A.C. (Alternating current) as generally is the case, first of all the potential difference at which the current is supplied is lowered with the help of a step-down transformer. The current is then rectified by a rectifier so that it becomes unidirectional i.e. D.C. This unidirectional current is then used to charge the accumulators in the same way as described above. Generally rectifiers are available in the market which supply current either at 12 volts or 6 volts potential difference. A rheostat is provided in the instrument itself to adjust the current to any desired value.

Oral questions:—Keys:—1. What is the use of keys? 2. Explain the use of a commutator.

Galvanometers:—Explain the principle of a moving coil galvanometer, 4. Is the magnet used permanent or an electro magnet? 5. Why the pole pieces are made cylindrical and an iron core is placed at the centre of the coil? 6. What is difference between a suspended coil type and pivoted coil type galvanometer? 7. Which type is more sensitive and why? 8. Why the coil is deflected when the current is passed through it? 9. Explain when the galvanometer is said to be dead beat type? how is it secured in practice, and why is it made dead beat?

Ammeters and voltmeters:—10. What do you understand by a shunt? 11. Distinguish between a galvanometer, an ammeter and a voltmeter. 12. Why an ammeter has low resistance while a voltmeter has high resistance? 13. How these two are connected in the circuit and why? 14. Why should the current enter in these instruments only from the positive terminal? 15. How can you change the range of these instruments? 16. What is a milli-ammeter and a milli-voltmeter? 17. Can you measure A.C. current or A.C. voltage with these instruments? If not, why? 18. Describe a hot wire ammeter and a hot wire voltmeter? 19. Can you measure D.C. current with a hot wire ammeter? 20. How can an A.C. instrument be distinguished from that of a D.C. instrument?

Rheostats and Resistance boxes:—21. Why the resistance wire used for their construction is usually of manganin? Can you take copper

instead of manganin, if not why ? 22. Why the wire is doubly wound ? 23. Which alloy is superior for the construction of a resistance wire and why ? 24. What do you understand by specific resistance of a material ? 25. Give the construction of a resistance box and a variable resistance (i. e. a rheostat). Which is more costly and why ? 26. How are the different resistances arranged in a resistance box ? 27. What is the use of infinity plug ? 28. Why the coils in the rheostat are insulated from one another ? 29. Explain the meaning of 20Ω , 2 amp. written on the instrument ?

Primary cells:—30. Explain the principle of primary cells, and describe Daniell cell and Leclanche cell. 31. What do you understand by the e.m.f. of a cell, and explain how is it generated ? 32. Should the cells be freshly prepared while starting the experiment ? 33. What are the defects of these cells and how are they eliminated ? 34. Describe a standard cell. 35. Can these cells be employed to obtain a constant supply of current ?

Secondary cells:—36. Explain the principle of a secondary cell ? 37. How does it differ from a primary cell ? 38. Why is it called an accumulator ? 39. What types of accumulators are generally employed in the laboratory ? 40. What is the difference between an acid accumulator and an alkali accumulator ? 41. Compare and contrast the two types of accumulators ? 42. What is internal resistance of a cell, and how has it been minimised in case of an accumulator. 43. What do you understand by the capacity of an accumulator ? 44. What do you mean by 40 amp. at two hours rate ? 45. How is their capacity increased ? 46. How are they charged again ? 47. When should they be put for recharging and why ? 48. What are their demerits ? 49. Give reactions taking place in both the types of accumulators while charging and discharging ? 50. Explain the functions of a rectifier ? 51. Why these cells are charged at a constant current ? 52. Why should not they be short circuited ?

Name of cell.	Kind of electrolyte	Positive Plate	Negative Plate	Depolariser	E.M.F. in volts	Internal Resistance	Remarks.
1. Leclanche cell	Ammonium chloride solution.	Carbon	Zinc	MnO ₂ powder	1.5	Upto 5 ohms.	MnO ₂ being solid, it is not able to oxidise H ₂ readily and hence polarisation sets in. It, therefore, does not give steady current and is used intermittently.
2. Daniell cell	Dil. H ₂ SO ₄ Soln.	Copper	Zinc	CaSO ₄ Soln.	1.1	Up to 5 ohms.	It gives very steady e.m.f. and whenever battery is not available, it can be used for steady current.
3. Dichromate cell	Dil. H ₂ SO ₄ Soln.	Carbon	Zinc	K ₂ Cr ₂ O ₇	2.2	Low.	Gives strong current due to low internal resistance.
4. Bunsen cell	Dil. H ₂ SO ₄ Soln.	Carbon	Zinc	HNO ₃	2	"	Gives fumes which are harmful. They are not very common.
5. Acid accumulator	Dil. H ₂ SO ₄ Soln.	PbO ₂	Spongy lead	—	2.2	0.1 ohm.	These are available with two or greater no. of odd plates. Greater the number and greater the area, greater is its capacity and lower is internal resistance.
6. Alkali.	Dil. KOH Soln.	NiO ₂	Fe	—	1.35	0.1 ohm	It is not advisable to draw very heavy current from 5th but this can be used for such purposes.

Note:—No. 5 and 6 are secondary cells and are also called accumulators. If their e.m.f. goes below 1.8 or 1.2 respectively, they should not be used but first recharged. They are costly and hence, their use is recommended only when steady current is needed.

EXPERIMENT No. 17

የጋራነታችንን የሚጠቅም ለሁሉም ሕዝቦች ምክር ቤቱን ማቆየት ይገባል።

1. The first part of the report is devoted to a general description of the work done during the year. It is divided into two main sections: a description of the work done in the field and a description of the work done in the laboratory.

Descriptions of the apparatus - Instruments are of various forms. The simplest type which is commonly employed in most of the laboratories is the wire type. You are already quite familiar with that generalization.

The use of as many wires makes the apparatus cumbersome. However, it is also difficult to obtain such a long wire of absolutely uniform section through out its entire length. Therefore, these difficulties have been surmounted by connecting a comparatively short wire in series with a number of resistance coils as shown in fig. 1

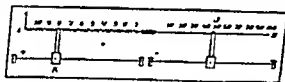


Fig. 1

The resistance of each coil is equal to the resistance of the wire. Normally ten such coils are taken, and put in series with a wire (generally of 50 cm. length), upon which slides the jockey J . J is connected to the -ve terminal of the secondary circuit. K is a contact maker, which slides over the studs of the coils. K is connected to the +ve terminal of the secondary circuit (see fig. 2). By this arrangement any number of coils can be taken in the circuit for comparison purposes, hence the length of the potentiometer wire can be altered. The slide wire is generally divided into 100 equal divisions. The length of each coil is taken to be equal to 100 divisions. (Suppose

the contact maker K is lying on coil no. 7, and J is at 23th division then the balancing length will be $= 7 \times 10 + 25 = 725$ divisions.)

Theory :—For both the cases the potentiometer wire can be regarded as a single wire as shown in fig. 2. The connections are self explanatory.

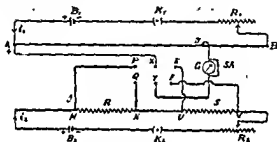


FIG. 2

Suppose R and S are the two resistances to be compared. i_1 and i_2 be the steady current flowing respectively through the potentiometer wire AB , and the two resistances R and S . Let V_1 and V_2 respectively the potential difference across R and S . Now if l_1 is balancing length of the potentiometer wire (when there is no current in the galvanometer), when the p.d. V_1 across R is balanced it, we have,

$V_1 = R i_1 = l_1 \times \dots \dots (i)$, where x is the potential gradient along the wire AB .

Similarly let l_2 be the balancing length of the potentiometer wire when p.d. V_2 across S is balanced on it, we have,

$$V_2 = S i_2 = l_2 \times \dots \dots (ii)$$

By dividing (i) by (ii) we get,

$$R/S = l_1/i_2 \dots \dots (iii)$$

Method :—1. Make neat and tight connections as shown in fig. (2). To start with, connect the +ve terminal of the battery to the end A , while the -ve terminal to the end B through a contact K and Key K_1 . This constitutes the primary circuit. Join end A to the terminal N of a four way key. Connect Y to junction

through the galvanometer G . This can be done by connecting the terminal Y in either of the terminals C or D of the strip (see Fig. 3). Short the galvanometer.



Fig. 3.

2. Connect the two resistance coils R and S and the rheostat R_3 in series with a battery B_1 through a key K_2 . This constitutes the secondary circuit.

3. Connect the higher potential terminals M and U of R and S to the terminals P and E respectively, and lower potential terminals N and V to the terminals Q and F respectively.

4. Close K_2 . Adjust R_3 so that a small potential difference is set up across R and S . Now join P to X and Q to Y . Close K_1 and bring the jockey near one end A of the wire and press. Note the direction of deflection in the galvanometer. Remove the jockey to other end and repeat the procedure. If the deflection in the galvanometer is in the opposite direction, connections are correct so far R is concerned. Determine the approximate value of the balancing length l_1 corresponding to the p.d. across R . Now disconnect P from X ; and Q from Y , and join X to E and Y to F and repeat the above procedure, if the deflection in the galvanometer becomes opposite as before, connections are correct for S also. Similarly determine the approximate value of the balancing length l_2 corresponding to the p.d. across S . If $l_1 > l_2$; $R > S$ or vice versa. If the deflection in the galvanometer is one sided in either case, the connections are wrong and test for the following.

(i) The higher potential terminals M and U of R and S should be connected to the terminals P and E of the key.

(ii) V_1 and V_2 are not individually less than the p.d. across the potentiometer wire. It is an essential condition for obtaining null point that V_1 and V_2 should be less than the p.d. across the potentiometer wire. To secure this either increase R_3 or decrease R_1 .

(iii) If still the deflection remains one sided test whether battery B_1 is fully charged or not.

5. Now connect the terminals X and Y to the two ends of the resistance R or S which ever is higher (which may be known from step

4). Adjust the rheostat R , so that the balance point is obtained near about the end B i. e. balancing length becomes large. This adjustment increases the *sensitiveness of the potentiometer*, and at the same time the *p. d. between A and B remains more than V_1 or V_2 which are to be compared.*

To determine l_1 :—6. Connect P to X and Q to Y, so that p.d. across R is balanced on the potentiometer wire. Slide the jockey and obtain a null point when there is no deflection in the galvanometer. For the final adjustment remove the shunt from the galvanometer. Measure the length of the wire from the end A to this point. This gives l_1 , the balancing length corresponding to the p.d. across R.

To determine l_2 :—7. Disconnect P from X and Q from Y, and join X to E and Y to F and repeat the above procedure (now p.d. across S is being compared). Similarly obtain the new balancing length l_2 corresponding to the p.d. V_2 across S. It is extremely important that during taking one set of readings for l_1 and l_2 , the current i_1 and i_2 should remain constant in the two circuits. This will be one set.

8. Change R_1 and R_2 (decrease R_2 or increase R_1), and again take another set. In this way take at least five or six different sets for l_1 and l_2 .

9. Determine the ratio $\frac{l_1}{l_2}$ from each set. Then determine the mean ratio $\frac{l_1}{l_2}$.

Observations:—

S. N.	Length corresponding to the p.d. across R (l_1) in cms.	Length corresponding to the p.d. across S (l_2) in cms.	$\frac{l_1}{l_2}$	Mean $\frac{l_1}{l_2}$
1				
.....				
6				

Calculations :—Calculate $\frac{l_1}{l_2}$ by each set and then determine mean $\frac{l_1}{l_2}$.

Result:—The ratio between the two resistances R and S

$$= \frac{R}{S} =$$

Precautions and sources of error:—1. The most important point to be borne in mind in this experiment is that p.d. between the two ends A and B of the potentiometer wire should always remain greater than the potential difference V_1 or V_2 across R or S . If this condition is not satisfied, deflection in the galvanometer will be only one sided.

2. R_1 should be adjusted for the maximum sensitiveness of the potentiometer.

3. Do not forget to put a shunt across the galvanometer. It should be removed only near the null point.

4. The resistances R or S should not be disturbed or mishandled during the experiment while comparing V_1 and V_2 .

5. Currents should be passed in the two circuits only when taking readings, otherwise heating will start altering the values of R and S .

6. Jockey should be pressed against the wire only for a small time. Do not slide the jockey with contact on. It causes the deformation of the wire.

7. All the higher potential terminals should be connected at one point, i. e. A and of the wire.

Criticism:—This method is quite satisfactory. The slight error present is due to the non-uniformity of the potentiometer wire, and the inconsistency of the e.m.f.s of the two batteries employed. This method is specially suited for the comparison of two nearly equal low resistances. For greater accuracy Crompton's potentiometer should be used.

Modifications:—1. To determine an unknown resistance with the help of a potentiometer.

Hint:—By the above process determine the ratio $\frac{R}{S}$. If R is known S can be determined. For this purpose R is taken in the form of a resistance box. Care should be taken to choose such a resistance from the resistance box that I_1 and I_2 are comparable. This is necessary in order to eliminate the error due to non-uniformity of the wire.

However, if the unknown resistance S is very low, the following method should be employed.

2. To determine a low resistance by potentiometer.

Hint.—1. Make neat and tight connections as shown in figure 4. R is a resistance box and S is the unknown resistance. Make primary and secondary circuits as described above.

2. Take a two way key with terminals X and Y . Connect the higher potential terminal M of R , B , to the higher potential end A of the potentiometer wire.

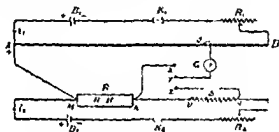


Fig. 4

The lower potential terminals B and X of R and S are respectively connected to X and Z . Connect Y to J through the galvanometer G .

3. Connect X to Y so that p.d. across R , B , is compared and determine the balancing length l_1 corresponding to the p.d. V_1 across R in R , B .

4. Disconnect X from Y and join Y to Z . Now p.d. across R and S is being compared. Similarly determine the new balancing length l_2 corresponding to the p.d. V_2 across the series combination formed by the two resistances R and S . The currents in the two circuits should be kept constant during these operations.

5. By changing the values of R in the resistance box, obtain more sets for the lengths l_1 and l_2 .

6. Calculate S by each set from the following formula.

7. If i_1 is the current flowing through the resistances R and S and s is the potential gradient along AB , we have

$$V_1 = l_1 s = i_1 R$$

$$\text{Similarly, } V_2 = l_2 s = i_2 (R + S)$$

$$\therefore \frac{R + S}{R} = \frac{l_1}{l_2}$$

or $S = \left(\frac{l_1}{l_2} - 1 \right) R$. when R is known, S can be calculated knowing l_1 and l_2 .

8. Determine the mean value of S . It will come out to be in ohms.

Oral Questions:—1. Describe a potentiometer giving its principle of working. 2. What is the use of a potentiometer? How many types of potentiometers you know, and which is the best? 3. What is potential gradient? 4. How can you increase or decrease the potential gradient? 5. Is it possible to employ primary cells in the primary and the secondary circuits, if no, why? 6. Why is it necessary that the same current should flow through both of the resistances which are being compared? 7. What should be the order of the resistances you are comparing? 8. Why should they be nearly equal? 9. Is this method suitable for comparing high resistances? 10. How will you determine low resistance by this method? 11. Why is it essential that the potential difference across the two resistances must be separately less than the potential difference across the potentiometer wire? 12. What do you understand by null point in this method? 13. Explain when there will be no current in the galvanometer? 14. When is the potentiometer most sensitive? 15. Why the wire of the potentiometer must be of uniform cross-section? 16. Can you determine the specific resistance of a wire by potentiometer, if yes, how?

EXPERIMENT No. 18

Experiment - To calibrate a voltmeter with the help of a potentiometer.

Apparatus :- A potentiometer, two accumulators, two rheostats, a galvanometer, a voltmeter, shunt, two way key, one way keys, connecting wires etc.

Description of the apparatus :- See experiment no 17.

Theory :- The connections are self explanatory (see fig. 1). In this experiment, the same potential difference is simultaneously measured with the help of a potentiometer and the given voltmeter. Hence the error in the reading of the instrument is determined. To obtain this, the potential gradient along the wire is found out with the help of a standard cell. If the standard cell is not available which is generally the case, Daniell cell can be employed in its place, and its e.m.f. may be taken as 1.07 volts.

Let l_1 be the balancing length of the potentiometer wire, when the e.m.f. E of a Daniell cell is balanced on it. Then, we have,

$E = l_1 \times x$ (where x is the potential gradient along the potentiometer wire).

$$\therefore x = \frac{E}{l_1} \dots\dots\dots (i)$$

Let l_2 be the balancing length of the wire when potential difference V_1 across the portion MW of the rheostat is balanced on it. Then, we have,

$$V_1 = x l_2 \dots\dots\dots (ii)$$

From eqns. (i) and (ii) we have,

$$V_1 = E \frac{l_2}{l_1} \dots\dots\dots (iii)$$

Let the reading in the voltmeter for the same potential difference across the portion MW of the rheostat be V_2 . Then the error in the reading of the instrument will be $= V_2 - V_1$. As the contact W is variable the voltmeter can be calibrated for its full range. A graph is then

drawn between the actual balance of the voltmeter and the corresponding errors.

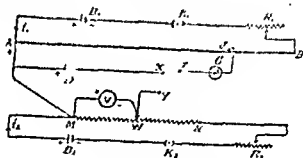


Fig. 1

Method —1. Make neat and tight connections as shown in fig. 1. Connect the end A of the potentiometer wire to the +ve terminal of the battery B_1 , and the end B to the -ve terminal of the battery through the rheostat R_1 and key K_1 . Evidently the potential of the point A is higher than that of B. It constitutes the primary circuit.

2. Connect the fixed terminal M of the rheostat to the +ve terminal of the battery B_2 , and the other fixed terminal N to the -ve terminal of the battery through a key K_2 . Evidently the potential of the terminal M is higher than that of N i.e. M is a higher potential terminal. It constitutes the secondary circuit.

3. Join the +ve pole of Daniell cell to the end A, and the -ve pole to the terminal X of a two way key.

4. Connect the higher potential terminal M of the rheostat to the end A, and the variable terminal W to the terminals Y of the key.

5. Join the middle terminal Z to the jockey J through a galvanometer G. Put a shunt across the galvanometer.

6. Connect the higher potential terminal M and variable terminal W of the rheostat respectively to the +ve and -ve terminals of the given voltmeter.

7. Close the key K_2 and by adjusting R_2 and the rheostat MN, obtain full scale deflection in the voltmeter. Now close K_1 . If the full scale deflection in the voltmeter is more than the e. m. f. of Daniell cell, connect Z to Y i. e. the sliding contact W to the jockey J through the galvanometer. If the full scale deflection is less than the e. m. f. of Daniell cell, connect X to Z i. e. -ve pole of the cell to the jockey through the galvanometer. Now try to obtain the approximate balance point as nearer to the end B as possible.

This ensures maximum sensitivity of the instrument and same time the potential difference between the two ends A and B remains more than the potential difference which is to be compared. If the deflection remains one sided and null point is not obtainable on the wire A B, follow the following procedure :

(a) Either reduce the resistance in R_1 , so that the current in primary circuit increases, increasing p. d. between the ends A and B.

(b) Or increase the number of accumulators in the primary circuit so that p. d. between the ends A and B increases.

Remember that p. d. between A and B should always remain more than the p. d. which is to be measured.

Suppose the maximum range of the given voltmeter is 3 volts. Then 1000 cm. of potentiometer wire should balance against p. d. of 3 volts. Hence for 1 volt the length of the wire should be approximately $1000/3=330$ cm. say. So while calibrating potentiometer wire with the help of a Daniell cell, see that balancing length is near about 330 cm.

To determine I_1 :—

8. Connect X and Z and adjust the jockey J, so that there is no deflection in the galvanometer. Determine this balancing length l_1 of the potentiometer wire corresponding to the e.m.f. E of Daniell cell. This gives I_1 . Thus, the potentiometer wire is calibrated. Remove the shunt while making final adjustment.

To determine I_2 :—

9. Disconnect X from Z, and join Y to Z. close K_2 by sliding the contact W, so adjust that the voltmeter reads 0.1 or 0.2 volt. Now determine the balancing length l_2 of potentiometer wire corresponding to the p. d. across the portion of the rheostat. Evidently you are balancing the potentiometer wire corresponding to the p. d. which is also being measured directly by the voltmeter.

10. Note down the reading in the voltmeter. Let it be V_1 . Calculate the true value V_2 for the same p. d. with the help of formula (iii), and determine the error, $V_1 - V_2$.

11. By sliding W change the p. d. across the terminals M and N . W should be so moved that the reading in the voltmeter may increase in steps of 0.1 or 0.2 volt. Again for each reading in the voltmeter determine the balancing length, and calculate the corresponding error. Follow this procedure till the deflection in voltmeter is full scale.

12. Draw a graph between the observed readings of the voltmeter and the corresponding errors.

Note :— Some times it is better to take a fixed resistance R in place of the rheostat MN , as shown in fig. 2. The voltmeter is put across the two terminals of the fixed resistance.

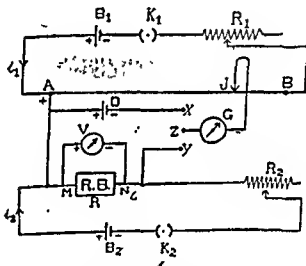


Fig. 2

In this case the p. d. across R is varied by adjusting the rheostat R_2 . The rest of the procedure is the same. This method is better because while changing p. d. the fluctuations are less, and hence null point is not disturbed.

Observations :—

Observation table for I_1 and I_2 .

S.N.	Balancing length corresponding to the e.m.f. of cell (l_1) in cm.	Balancing length corresponding to the p.d. across the portion MW of the rheostat or the resistance box (l_2) in cm.	Actual p.d. $V_2 = E \frac{l_2}{l_1}$ in volts	Observed p.d. in voltmeter V_1 in volts	Error $V_1 - V_2$ in volts
1					
2					
...					
...					
10					

Note:—The readings for the balancing length l_1 should be taken twice or thrice during the experiment to ensure, whether it remains the same or not.

Calculations—Calculate V_2 in each case from formula (iii)

$$x = \frac{E}{l_1} = \dots \dots \dots \text{volt/cm.}$$

$$V_2 = x l_2 = E \frac{l_2}{l_1} \dots \dots \dots \text{volts.}$$

Result:—The graph between the observed readings and the corresponding errors will be as shown in fig. 3. It is called the calibration curve for the voltmeter.

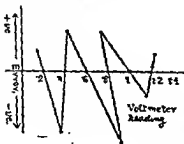


Fig. 3

precautions and sources of error:—1. All the higher potential terminals should be connected to the end A of the potentiometer wire.

2. The storage batteries used must be fully charged, and possess large capacities, so that their e.m.f. may remain constant during the performance of the experiment.

3. The potential difference across the two ends A and B of the

11. By sliding W change the p. d. across the terminals M and N . W should be so moved that the reading in the voltmeter may increase in steps of 0.1 or 0.2 volt. Again for each reading in the voltmeter determine the balancing length, and calculate the corresponding error. Follow this procedure till the deflection in voltmeter is full scale.

12. Draw a graph between the observed readings of the voltmeter and the corresponding errors.

Note :— Some times it is better to take a fixed resistance R in place of the rheostat MN , as shown in fig. 2. The voltmeter is put across the two terminals of the fixed resistance.

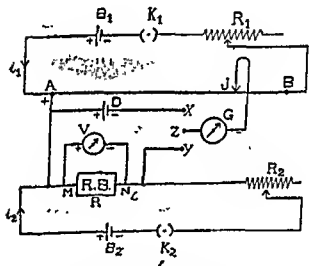


Fig. 2

In this case the p. d. across R is varied by adjusting the rheostat R_2 . The rest of the procedure is the same. This method is better because while changing p. d. the fluctuations are less, and hence null point is not disturbed.

Observations :—

[1]. E. M. F. of the Daniell cell (E) = 1.08 volts.

Observation table for I_1 and I_2 .

S.N.	Balancing length corresponding to the e.m.f. of cell (I_1) in cm.	Balancing length corresponding to the p.d. across the portion MW of the rheostat or the resistance box (I_2) in cm.	Actual p.d. $V_2 = E \frac{I_2}{I_1}$ in volts	Observed p.d. in voltmeter V_1 in volts	Error $V_1 - V_2$ in volts
1					
2					
...					
...					
10					

Note:—The readings for the balancing length I_1 should be taken twice or thrice during the experiment to ensure, whether it remains the same or not.

Calculations:—Calculate V_2 in each case from formula (iii)

$$x = \frac{E}{I_1} = \dots \dots \dots \text{vol/cm.}$$

$$V_2 = x I_2 = E \frac{I_2}{I_1} \dots \dots \dots \text{volts.}$$

Result:—The graph between the observed readings and the corresponding errors will be as shown in fig. 3. It is called the calibration curve for the voltmeter.

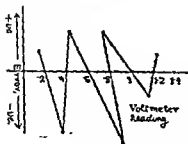


Fig. 3

Precautions and sources of error:—1. All the higher potential terminals should be connected to the end A of the potentiometer wire.

2. The storage batteries used must be fully charged, and possess large capacities, so that their e.m.f. may remain constant during the performance of the experiment.

3. The potential difference across the two ends A and B of the

11. By sliding W , change the p.d. across the terminals M and N . W should be adjusted so that the reading in the voltmeter may increase in steps of 10 or 12 volt. Again for each reading in the voltmeter determine the balancing length and calculate the corresponding error. Follow this procedure till the deflection in voltmeter is full scale.

12. Draw a graph between the observed readings of the voltmeter and the corresponding errors.

Note:—Sometimes it is better to take a fixed resistance R in place of the rheostat MN as shown in fig. 2. The voltmeter is put across the two terminals of the fixed resistance.

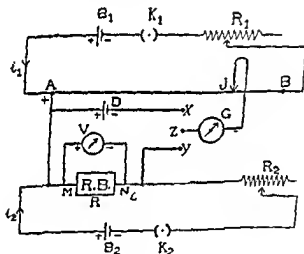


Fig. 2

In this case the p.d. across R is varied by adjusting the resist R_1 . The rest of the procedure is the same. This method is preferred because while the point is not disturbed.

Observations —

[1]. E. M. F. of the

Observation table for I_1 and I_2 .

S.N.	Balancing length corresponding to the e. m. f. of cell (E_1) in cm.	Balancing length corresponding to the p. d. across the portion MW of the rheostat or the resistance box (U_2) in cm.	Actual p.d. $V_2 = E \frac{l_2}{l_1}$ in volts	Observed p.d. in voltmeter V_1 in volts	Error $V_1 - V_2$ in volts
1					
2					
3					
4					
5					
6					
7					
8					
9					
10					

Note:—The readings for the balancing length l_2 should be taken twice or thrice during the experiment to ensure, whether it remains the same or not.

Calculations:—Calculate V_2 in each case from formula (ii)

$$x = \frac{l_2}{l_1} = \dots \dots \dots \text{volt/cm.}$$

$$V_2 = x l_2 = E \frac{l_2}{l_1} \dots \dots \dots \text{volts.}$$

Result:—The graph between the observed readings and corresponding errors will be as shown in fig. 3. It is called the calibration curve for the voltmeter.

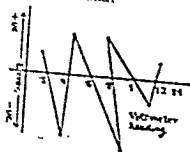


Fig. 3

precautions and source of error:—1. All the slide potential terminals should be connected to the end A of the potentiometer wire.

2. The storage batteries used must be fully charged and possess large capacity, so that their e.m.f. may remain constant during the continuance of the experiment.

3. The potential difference across the two ends A and B of the

... 2. 4. 8. 16. results. However, the percentage error in the value is upon the construction of the potential gradient. The potential gradient depends upon the uniformity of the wire as well as the constancy of the e.m.f. of the batteries used. For accurate calibration, the exact e.m.f. of the Daniell cell should be substituted. Daniell cell should be freshly prepared when starting the experiment.

Oral questions — 1. See experiment no. 17. 2. What do you understand by calibration of a voltmeter and how is it done? 3. How the wire of the potentiometer is calibrated? 4. Why a standard cell is necessary to calibrate the potentiometer wire? 5. Can a Daniell cell serve this purpose? 6. When is the potentiometer most sensitive for a given range of a voltmeter to be calibrated? 7. Can you use a resistance box instead of a rheostat in the secondary circuit?

EXPERIMENT No. 19

Experiment :—To calibrate an ammeter with the help of a potentiometer

Apparatus :—A potentiometer, two accumulators, two rheostats, galvanometer, a standard one ohm resistance coil, the ammeter which is to be calibrated, shunt, two way key, Two one way keys, connecting wires etc.

Description of the apparatus :—See experiment No. 17.

Theory :—The connections are self explanatory (see fig. 1). In this experiment the same current is simultaneously measured with the help of a potentiometer and the given ammeter. Hence the error in the given instrument is determined.

Let l_1 be the balancing length of the potentiometer wire when the E. M. F. E of a Daniell cell is balanced on it. Then we have,

$E = l_1 x$ [where x is the potential gradient along the potentiometer wire].

$$\therefore x = E/l_1 \dots \dots \dots (i)$$

Let l_2 be the balancing length of the potentiometer wire when P. D. V_2 across the two ends of a standard resistance R is balanced on it. Then we have,

$$V_2 = x l_2 \dots \dots \dots (ii)$$

From (1) and (2) we have,

$$V_2 = E \frac{l_2}{l_1} \dots \dots \dots (iii)$$

If i_2 is the current flowing in the standard resistance R and the ammeter,

$i_2 = \frac{V_2}{R} \dots \dots \dots (iv)$ If the standard resistance is a one ohm coil,

$$i_2 = V_2 \dots \dots \dots (v)$$

Substituting the value of V_2 from eqn. (3) in eqn. (5) we get,

$$i_2 = E \frac{l_2}{l_1} \dots \dots \dots (vi)$$

3. Connect the +ve pole of the Daniell cell to terminal A and the -ve pole to the terminal X of two way key.

4. Join the higher potential terminal of the one ohm coil to the end A, and the lower potential terminal to the terminal Z of the two way key.

5. Join the middle terminal Y to the jockey J through a galvanometer G. Put a shunt across the galvanometer.

6. Close K_1 and by adjusting R_2 obtain full scale deflection in the ammeter. If corresponding to this full scale deflection, the potential difference between the two ends of the one ohm coil is greater than the e.m.f. of the Daniell cell, connect Z to Y, i.e. the lower potential terminal of the one ohm coil to the jockey. On the other hand if for the full scale deflection the potential difference is less than the e.m.f. of the Daniell

cell, connect X to Y, i.e. the +ve pole of the Daniell cell to the jockey. In either case, the deflection in the galvanometer will be zero.

7. Now open K_1 and close K_2 . The current in the circuit will be $I = \frac{E}{R_2 + 1}$ where E is the e.m.f. of the Daniell cell and R_2 is the resistance of the variable resistor.

8. The potential difference between the two ends of the one ohm coil is $V = IR_2$. This is the potential difference between the two ends of the one ohm coil when the current in the circuit is I . This potential difference is equal to the e.m.f. of the Daniell cell.

9. The e.m.f. of the Daniell cell is $E = \frac{V}{R_2 + 1}$ where V is the potential difference between the two ends of the one ohm coil and R_2 is the resistance of the variable resistor.

Calculations -

Calculate i_2 from relation (1) and (2) as

$$i_2 = V_2 = I \frac{I_2}{I_1} \quad \text{amp}$$

$$\% \text{ error } (i_1 - i_2) = \quad \text{amp}$$

Result 1. i_1 and i_2 are

been observed at different times and the corresponding values are as follows. The difference between the two values is the error.

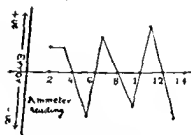


Fig. 1

Note: The error is zero at the origin and increases with the value of the ammeter reading. The error is also zero at the origin and increases with the value of the ammeter reading. The error is zero at the origin and increases with the value of the ammeter reading.

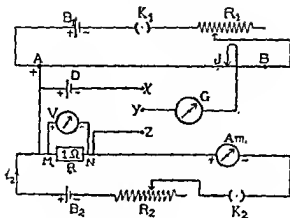


Fig. 3

Precautions and sources of error —

1. Same as in the previous experiment.

2. The ammeter should be connected in the secondary circuit in such a way that the current in it should always enter from the positive terminal.

3. All the wires connecting the higher potential terminals should be led towards the higher potential terminal of the potentiometer wire.

Criticism.—See previous experiment. The percentage accuracy as described before depends upon the following factors. (i) The constancy of the battery e.m.f. (ii) accurate knowledge of the e.m.f. of the Daniell cell (iii) uniformity of the potentiometer wire. (iv) accurate knowledge of the value of the standard resistance (v) and constancy of the potential gradient. For greater accuracy instead of an ordinary one ohm coil, standard resistance coil should be taken.

Oral questions :—

1. See experiment no. 17 and 18. 2. What do you understand by the calibration of an ammeter and how is it done? 3. Why a standard one ohm coil is preferred in the secondary circuit, can you use any value of the resistance? 4. Is the calibration of the potentiometer wire done accurately with the help of a Daniell cell? 5. Can you suggest any better cell for calibration purpose? 6. Do you know any other method of calibrating an ammeter? Which of the methods is superior and why? 7. Can you calibrate voltmeter and ammeter simultaneously? If yes, how?

Let

X and

then

the

is

or

the

is

In this particular case the two resistances P and Q are supplied by the resistances X and Y respectively connected between the taps AB and BC (see fig. 2). The jockey D divides the

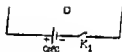


Fig. 1

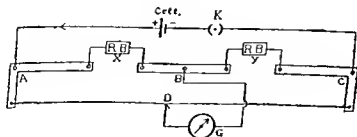


Fig. 2

bridge wire in two parts. These two parts supply the resistances R and S . Let the balance point on the bridge wire (indicated by

no current in the galvanometer) lie at a distance l_1 cm. from the end A which is connected to the resistance X. Then, the resistances R and S would be respectively proportional to the lengths l_1 and $(100-l_1)$ cm. of the bridge wire. Hence relation (i) will become.

$$\frac{X}{Y} = \frac{l_1}{(100-l_1)} \quad \dots \quad \dots \quad (ii)$$

Often the soldering of the wire with the brass strips is defective. The solder spreads at the ends forming an alloy with the bridge wire. As the specific resistance of this alloy is different from that of the bridge wire, the resistance of the wire at the two ends changes from its initial value. Furthermore, the two ends of the wire may not exactly coincide with the 0 and 100 cm. divisions of the scale i.e. the scale may be slightly disturbed. Due to this error the length of the wire as read on the scale may be slightly more or less than the actual value, depending upon the position of the zero. Moreover, the brass strips also possess some resistance. All these factors introduce *certain extra resistances at the two ends*, which are known as *end corrections*. Where accuracy is to be obtained these end corrections are not too small to be neglected.

Let these end resistances at the left and the right end be respectively equal to the resistance of α and β cm. length of the bridge wire. Then, the corrected length of the two segments of the wire would be $l_1 + \alpha$ and $100-l_1+\beta$. Therefore, equation (ii) becomes,

$$\frac{X}{Y} = \frac{l_1 + \alpha}{100-l_1+\beta} \quad \dots \quad \dots \quad (iii)$$

Let the resistances X and Y be interchanged. If the new balance point lies at a distance of l_2 cm. from the left end A which is now connected to the resistance Y, we have,

$$\frac{Y}{X} = \frac{l_2 + \alpha}{100-l_2+\beta} \quad \dots \quad \dots \quad (iv)$$

Solving (iii) and (iv) we get

$$\alpha = \frac{Yl_1 - Xl_2}{X-Y} \quad \dots \quad \dots \quad (v)$$

$$\text{and} \quad \beta = \frac{Xl_2 - Yl_1}{X-Y} \quad \dots \quad \dots \quad (vi)$$

Knowing X, Y, l_1 , and l_2 , α and β can be determined.

Let the distance from the left end of the wire to the null point be x cm.

Then

x

is the distance from the left end of the wire to the null point.

Let the distance from the right end of the wire to the null point be y cm.

Then

is the distance from the right end of the wire to the null point.

Let the distance from the left end of the wire to the null point be x cm.

To determine

1. After the circuit is set up, the balance point is found to be at a distance of x cm from the left end of the wire.

and determine the exact value of x by measuring the distance of the null point from the left end of the wire twice and then find out the exact value of x .

Note.—The null point will be at the other end of the bridge wire.

To determine I_2 —

7. Now interchange the two resistances X and Y so that in the left gap the resistance is $10\ \Omega$ while in the right gap it is $1\ \Omega$. As described above, again determine the balance point and find the distance of this new balance point again from the left end A . It gives I_2 . Similarly determine I_2 twice and then find out the exact I_2 .

Note.—In this case the null point will be at the other end of the wire.



8. Keeping the value of $X=1$ ohm, change the value of Y to 20 ohm and determine the corresponding lengths l_1 and l_2 .
 (You take atleast two to three sets for l_1 and l_2 .)

9. Calculate α and β from each set, and then determine the mean α and β .

Observations :—

N.	Resistance		Distance of the balance point from the left end A with X in the						α in cm.
	X in ohm.	Y in ohm.	Left gap (l_1) in cm.			Right gap (l_2) in cm.			
			I	II	Mean	I	II	Mean	
1									
2									
3									

Calculations:—Determine α from the formula,

$$\alpha = \frac{Yl_1 - Xl_2}{X - Y}, \text{ and}$$

$$\beta = \frac{Xl_1 - Yl_2}{X - Y} - 100 \text{ for each set.}$$

and then determine the mean for each α and β .

Result:—[1] End correction for the left end =cm

[2] End correction for the right end =cm

Note.—The end corrections are determined in terms of the length of the bridge wire. If they are to be determined in ohms the values of α and β should be multiplied by the resistance per unit length of the bridge wire.

Precautions and sources of error :—

1. Current should be passed in the circuit, only when taking observations. It will prevent unnecessary heating of the resistance coils, and hence the value of their resistances will not change.

2. To start with galvanometer must be properly zeroed, otherwise it will be damaged.

3. The jockey should not be moved with contact on, or else the uniformity of the cross-section of the wire will be destroyed.

On Equations

1. $x^2 + y^2 = z^2$ 2. $x^2 + y^2 = z^2$ 3. $x^2 + y^2 = z^2$ 4. $x^2 + y^2 = z^2$ 5. $x^2 + y^2 = z^2$ 6. $x^2 + y^2 = z^2$ 7. $x^2 + y^2 = z^2$ 8. $x^2 + y^2 = z^2$ 9. $x^2 + y^2 = z^2$ 10. $x^2 + y^2 = z^2$ 11. $x^2 + y^2 = z^2$ 12. $x^2 + y^2 = z^2$ 13. $x^2 + y^2 = z^2$ 14. $x^2 + y^2 = z^2$ 15. $x^2 + y^2 = z^2$ 16. $x^2 + y^2 = z^2$ 17. $x^2 + y^2 = z^2$ 18. $x^2 + y^2 = z^2$ 19. $x^2 + y^2 = z^2$ 20. $x^2 + y^2 = z^2$ 21. $x^2 + y^2 = z^2$ 22. $x^2 + y^2 = z^2$ 23. $x^2 + y^2 = z^2$ 24. $x^2 + y^2 = z^2$ 25. $x^2 + y^2 = z^2$ 26. $x^2 + y^2 = z^2$ 27. $x^2 + y^2 = z^2$ 28. $x^2 + y^2 = z^2$ 29. $x^2 + y^2 = z^2$ 30. $x^2 + y^2 = z^2$ 31. $x^2 + y^2 = z^2$ 32. $x^2 + y^2 = z^2$ 33. $x^2 + y^2 = z^2$ 34. $x^2 + y^2 = z^2$ 35. $x^2 + y^2 = z^2$ 36. $x^2 + y^2 = z^2$ 37. $x^2 + y^2 = z^2$ 38. $x^2 + y^2 = z^2$ 39. $x^2 + y^2 = z^2$ 40. $x^2 + y^2 = z^2$ 41. $x^2 + y^2 = z^2$ 42. $x^2 + y^2 = z^2$ 43. $x^2 + y^2 = z^2$ 44. $x^2 + y^2 = z^2$ 45. $x^2 + y^2 = z^2$ 46. $x^2 + y^2 = z^2$ 47. $x^2 + y^2 = z^2$ 48. $x^2 + y^2 = z^2$ 49. $x^2 + y^2 = z^2$ 50. $x^2 + y^2 = z^2$ 51. $x^2 + y^2 = z^2$ 52. $x^2 + y^2 = z^2$ 53. $x^2 + y^2 = z^2$ 54. $x^2 + y^2 = z^2$ 55. $x^2 + y^2 = z^2$ 56. $x^2 + y^2 = z^2$ 57. $x^2 + y^2 = z^2$ 58. $x^2 + y^2 = z^2$ 59. $x^2 + y^2 = z^2$ 60. $x^2 + y^2 = z^2$ 61. $x^2 + y^2 = z^2$ 62. $x^2 + y^2 = z^2$ 63. $x^2 + y^2 = z^2$ 64. $x^2 + y^2 = z^2$ 65. $x^2 + y^2 = z^2$ 66. $x^2 + y^2 = z^2$ 67. $x^2 + y^2 = z^2$ 68. $x^2 + y^2 = z^2$ 69. $x^2 + y^2 = z^2$ 70. $x^2 + y^2 = z^2$ 71. $x^2 + y^2 = z^2$ 72. $x^2 + y^2 = z^2$ 73. $x^2 + y^2 = z^2$ 74. $x^2 + y^2 = z^2$ 75. $x^2 + y^2 = z^2$ 76. $x^2 + y^2 = z^2$ 77. $x^2 + y^2 = z^2$ 78. $x^2 + y^2 = z^2$ 79. $x^2 + y^2 = z^2$ 80. $x^2 + y^2 = z^2$ 81. $x^2 + y^2 = z^2$ 82. $x^2 + y^2 = z^2$ 83. $x^2 + y^2 = z^2$ 84. $x^2 + y^2 = z^2$ 85. $x^2 + y^2 = z^2$ 86. $x^2 + y^2 = z^2$ 87. $x^2 + y^2 = z^2$ 88. $x^2 + y^2 = z^2$ 89. $x^2 + y^2 = z^2$ 90. $x^2 + y^2 = z^2$ 91. $x^2 + y^2 = z^2$ 92. $x^2 + y^2 = z^2$ 93. $x^2 + y^2 = z^2$ 94. $x^2 + y^2 = z^2$ 95. $x^2 + y^2 = z^2$ 96. $x^2 + y^2 = z^2$ 97. $x^2 + y^2 = z^2$ 98. $x^2 + y^2 = z^2$ 99. $x^2 + y^2 = z^2$ 100. $x^2 + y^2 = z^2$

EXPERIMENT No. 21

Experiment :—To calibrate the Careyfooster's bridge wire (i. e. to determine resistance per unit length of the wire), and then to determine difference between two nearly equal resistances.

Apparatus :—A Careyfooster's bridge, Leclanche cell, galvanometer, rheostats, two coils each of one ohm resistance, resistance box, fractional resistance box, copper strips, the two resistances which are to be compared, key, stout wire, connecting wires etc.

Description of the apparatus :—It is the modified form of a metre bridge. A Careyfooster's bridge, consists of a metre long wire of uniform cross section stretched along a wooden board. The wire is made of an alloy of high specific resistance and low temperature coefficient, (ofureka or manganin), and runs parallel to a metre scale also fixed on the board. The ends of the wire are soldered to two thick brass strips. Theoretically speaking the two ends should coincide respectively with 0 and 100 cm. divisions marked on the scale. Three brass strips running parallel to the wire are fixed on the board between

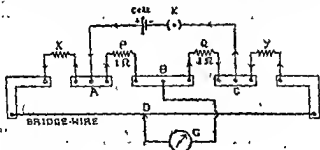


Fig. 1

the two brass strips soldered at the two ends. These five strips of brass constitute four gaps as shown in fig. 1. Terminals with binding screws are provided on all these strips. The two resistances X and Y which are to be compared are connected in the outer gaps of the bridge. They are in series with the bridge wire. Two two nearly equal resistances P and Q are put in the inner gaps AB and BC (generally they are one ohm coils)... Rest of the connections are self explanatory.

EXPERIMENT No. 21

Experiment:—To calibrate the Carey Foster's bridge wire (i. e. to determine resistance per unit length of the wire), and then to determine difference between two nearly equal resistances.

Apparatus:—A Carey Foster's bridge, E.lectrode cell, galvanometer, rheostat, two coils each of one ohm resistance, resistance box, fractional resistance box, copper strips, the two resistances which are to be compared, key, short wire, connecting wires etc.

Description of the apparatus.—It is the modified form of a wire bridge. A Carey Foster's bridge consists of a metre long wire of uniform cross section stretched along a wooden board. The wire is made of an alloy of high specific resistance and low temperature coefficient (of wire or manganin), and runs parallel to a metre scale also fixed on the board. The ends of the wire are soldered to two thick brass strips. Theoretically speaking the two ends should coincide respectively with 0 and 100 cm. divisions marked on the scale. Three brass strips running parallel to the wire are fixed on the board between

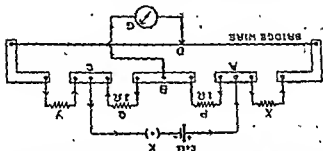


Fig. 1

the two brass wires soldered at the two ends. These five strips of brass constitute four gaps as shown in Fig. 1. Terminals with binding screws are provided on all these strips. The two resistances X and Y which are compared are connected in the outer gaps of the bridge. They constitute the bridge wire. The two nearly equal resistances are soldered gaps AB and BC (generally they are one cell explanatory).

mined. It is known as the calibration of the bridge wire. To calibrate the bridge wire a fractional resistance box is put in the left outer gap, and a thick copper strip is put across the right outer gap. Thus, Y is reduced to zero. Let the resistance in the resistance box be R (i.e. $X=R$). Now let the balance point be situated at a distance l_1' from the left end which is connected to the resistance R . After interchanging R and the copper strip let the new balancing length from the left end (which is now joined to the copper strip) be l_2' . Then, from relation (v), we get.

$$R = \rho (l_2' - l_1') \dots \dots \dots (vi)$$

$$\text{or} \quad \rho = \frac{R}{l_2' - l_1'} \dots \dots \dots (vii)$$

Method. — To determine ρ of wire to calibrate the bridge wire—

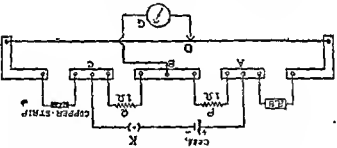


FIG. 2

1. Make neat and tight connections as shown in fig. 2. The connections should be done by thick copper wires so that the resistances in the four arms of the bridge remain the same.

2. Connect a fractional resistance box in the left outer gap. Short circuit the right outer gap by connecting a thick copper strip across its ends. In each of the inner gaps connect a standard one ohm coil (so that $P=Q=1$ ohm).

3. Connect a Leclanche cell to the terminals A and C through a key.
4. Connect one terminal of the galvanometer G to the terminal B (terminal lying on the middle strip), and the other to the jockey D. Short the galvanometer.
- To determine l_1' :—

5. Introduce a resistance = 0.1 ohm in the fractional resistance box. Put the plug in the key, and determine the approximate balance

resistances ($X - Y$) = ... ohms.

Precautions and sources of error:—1. All the connections should be tightly done. Fractional resistance box and the other resistances coils (which are generally small) should be connected in the respective gaps with thick copper wires, so that the connecting wires may not have their own extra resistances.

2. Allow the current to flow through the circuit only when taking observations, otherwise unnecessary heating of the resistances will take place altering their values.

3. Jockey should not be moved on the wire with the contact on, otherwise the wire will get disfigured, and the cross-section will not remain uniform.

4. First, allow the current to flow through the cell circuit and then through the circuit. Do the reverse of it while switching.

5. While calibrating the bridge wire, the resistance in the fractional resistance box should be adjusted to obtain the two null points as near the ends as possible. This makes $(G-H)$ very nearly equal to the entire length of the bridge wire, and the error due to the non uniformity of the wire is reduced to a minimum.

6. As described earlier, it is preferable to use a rheostat

to obtain the two ratio arms P and Q . Of course, for greater sensitivity of the bridge the sliding contact on the rheostat should be adjusted to render P and Q almost equal. It is not at all necessary to know the values of P and Q . When $P=Q$ and the wire is of uniform cross-section, the two null points obtained before and after interchanging the resistances in the outer gaps will be situated at equal distances from the centre of the wire. If P is much different from Q , it would not be possible to get the null point on the bridge, therefore, there should not be much difference between the values of P and Q . If a using a rheostat the null point can be obtained on any part of the wire. Hence, more number of sets can be taken for a given set of values for X and Y . This is not possible when fixed resistance coils are connected in the outer gaps.

7. The difference between the two resistance X and Y should not in any case be greater than the resistance of the bridge wire, otherwise it would not be possible to obtain the null point.

8. While determining the difference between X and Y , the null point should be obtained as near to the centre of the wire as possible. This reduces the error in determining the position of the null point to the minimum and hence sensitivity will be increased.

9. See experiment No. 22.

Method of solution—1. The detector is unknown resistance with the help of a Careyless's bridge.

Figure—1. Determine the resistance for each length of the wire (2) as described above.

2. If the wire resistance is R per unit length, is l cm. of X , and a resistance box in the right outer gap is placed of X_1 ohms, find out the two balancing lengths L and L_1 , and calculate X by the formula—

$$X = \frac{R(L_1 - L)}{L} + X_1$$

As Y and R are known X can be determined.

2. In determining the end corrections of the wire, the following method is used:

Figure 1 shows a wire of length l and resistance R connected to a battery of e.m.f. E and internal resistance r . The current I is given by $I = \frac{E}{R + r}$. The potential difference across the wire is $VI = IR$. The end corrections are determined by measuring the length l for which the resistance is equal to the resistance of a wire of length l_0 and resistance R_0 .

Calculations—Let us assume that the length of the wire is l and the resistance is R . The resistance of a wire of length l_0 and resistance R_0 is $R_0 = \frac{\rho l_0}{A}$, where ρ is the resistivity and A is the cross-sectional area. The resistance of the wire of length l is $R = \frac{\rho l}{A}$. The end corrections are determined by measuring the length l for which the resistance is equal to the resistance of a wire of length l_0 and resistance R_0 .

Results—The results of the experiment are shown in Table I. The end corrections are determined by measuring the length l for which the resistance is equal to the resistance of a wire of length l_0 and resistance R_0 . The end corrections are determined by measuring the length l for which the resistance is equal to the resistance of a wire of length l_0 and resistance R_0 .

Conclusions—The results of the experiment show that the end corrections are determined by measuring the length l for which the resistance is equal to the resistance of a wire of length l_0 and resistance R_0 . The end corrections are determined by measuring the length l for which the resistance is equal to the resistance of a wire of length l_0 and resistance R_0 .

Summary—An experiment on wire bridges for determining the length of the wire is described. The results of the experiment are shown in Table I. The end corrections are determined by measuring the length l for which the resistance is equal to the resistance of a wire of length l_0 and resistance R_0 .

References—The following references are given: 1. *Physics*, by R. C. Weidner and R. S. Sears, 2nd ed., McGraw-Hill, 1955. 2. *Physics*, by D. Halliday and R. Resnick, 2nd ed., Wiley, 1958. 3. *Physics*, by H. D. Young and R. A. Freedman, 2nd ed., Wiley, 1962.

Now $\frac{dX}{dx}$ is minimum when $t = \frac{Z}{L}$ therefore, the minimum value for $\frac{X}{dx}$ would be given by,

$$\frac{dX}{dx} = \frac{1}{4} \frac{X}{L}$$

For a metre bridge $l = 1$ mm, and $L = 100$ cm.

$$\therefore \frac{dX}{dx} = \frac{100}{4} \times \frac{10}{1} = \frac{100}{1}$$

Hence, the percentage accuracy is directly proportional to the length of the wire L . Therefore, to enhance the percentage accuracy

with should be increased which is actually done in Carey Foster's arrangement.

in the balanced state of the bridge, if ΔR is the small shift in the value on account of a small change dR in the known resistance R ,

$$R = \frac{L}{L - l} X$$

$$dR = -\frac{L}{L - l} dl$$

$$\frac{dR}{R} = -\frac{L}{l} \frac{dl}{L - l}$$

As l is a fraction of L , $l \ll L$, where n is less than one. Hence,

$$\frac{dR}{R} = -\frac{L}{l} dl; \text{ therefore, sensitiveness of the bridge is also}$$

proportional to the length of the wire. Thus, Carey Foster's bridge is not accurate, it is sensitive also than the other arrangements.

Questions:—

1. Explain the principle and working of a Carey Foster's bridge.
2. What do you mean by the sensitiveness and accuracy of a Carey Foster's bridge?
3. How do you find out the factors on which the two depend?
4. How do you find out the resistance per unit length of the wire?
5. Why a decimetre box is employed instead of an ordinary resistance box while calibrating the wire?
6. What type of resistances should be connected in the two inner gaps?
7. Can you connect a rheostat instead of two resistances?
8. Which is the better arrangement and why?
9. Should the two resistances in the inner gaps be exactly equal?
10. How can you compare two resistances by a Carey Foster's bridge?
11. What should be the order of these resistances?
12. What is the minimum permissible difference between the two resistances?
13. Is it possible to compare the two resistances even without calibrating the wire?
14. Why we do not consider end correction in this experiment?
15. How can you test for the uniformity of the wire?
16. Why thick wire strip is employed to short circuit the gap?
17. See the previous experiment.

employed as shown in fig. 1. In some laboratories where the current is obtained from an A. C. source, first of all a step down transformer is used to lower the potential difference of the supply to about 6 to 8 volts. This p. d. is then used to pass current through the heating coil. A rheostat is used to regulate the current in the circuit. In this

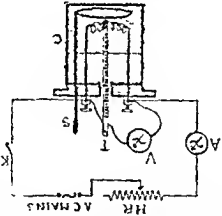


Fig. 2

case an A. C. voltmeter and an A. C. ammeter is used as shown in

in fig. 2.

Theory:—Let E be the potential difference across the two ends of the heating coil in volts and I be the current passing through it in amperes. If the current is passed for an interval of t seconds, the work done W , by the current in ergs is given by the relation,

$$W = EIt \times 10^7 \text{ (ergs)}$$

So much amount of energy will be converted in to heat which will be absorbed by the calorimeter and its contents. Then, by Joule's law we have

$$W = \frac{H}{J}$$

Where J is the mechanical equivalent of heat, and H is the amount of heat produced.

$$H = (W_1 + m) (t_1 - t_2 \times 1000)$$

Where W_1 is the water equivalent of the calorimeter and the water, m is the mass of water in the calorimeter, t_1 is the initial temperature of water, and t_2 is the final observed temperature of water.

From (i) and (iii) we get,

$$I = \frac{E H}{R h} \frac{(W' + m)(\theta_2 - \theta_1)}{10^4} \times 10^4 \quad \text{.....(iv)}$$

and $W' = m_1 S_1$ (v)

Where S_1 and m_1 are respectively the specific heat and mass of calorimeter including stirrer.

Method:—1. Take the Joule's calorimeter and clean it. Determine the mass of the calorimeter and stirrer with the help of a physical balance. It gives m_1 .

2. Fill two thirds of the calorimeter with water which may be sufficient to immerse the heating coil. Again determine its mass with the help of a physical balance. Let it be m_2 gm. Determine the difference between these two masses i. e. between m_2 and m_1 . It gives m , the mass of water contained in the calorimeter.

3. Put the heating coil in the calorimeter so that it remains fully immersed in water. Now close the lid and put the calorimeter in the wooden box.

4. Now make neat and tight connections as shown in fig. 1. Connect the resistance coil (heater), the ammeter A, the rheostat, and a key K in series with a battery of accumulators (three to four accumulators should be used in series). Current in ammeter must enter from the +ve terminal. Connect the voltmeter V across the two terminals of the heating coil. +ve of the voltmeter should be connected to that terminal of the leads, through which the current enters the heating coil. If current is to be derived from D. C. mains a high resistance should be included in the circuit. (If A. C. is to be used connections are to be made as shown in fig. 2. Feed A. C. in to a step down transformer from the mains, and connect an A. C. ammeter, a suitable rheostat and a key in series with the out put terminals of the step down transformer, which has not been shown in the diagram. In this case put an A. C. voltmeter across the two terminals of the heating coil.)

5. Put the plug in the key, and adjust the current in the calorimeter. The p. d. across the heating coil should preferably be adjusted between 6 to 8 volts with the help of a rheostat. Now determine the temperature of water with the help of the thermometer T and immerse it in the stop-water. Due to the flow of current in the coil, heat will be produced. Consequently the temperature of water will rise and the water constantly with the help of a stirrer.

6. Find out the current passing through the coil with the help of the ammeter. It gives I. Determine p. d. across the two ends of the heater with the help of the voltmeter. It gives E. If the p. d. varies during the performance of the experiment keep it constant by adjusting the rheostat.

7. When the temperature of water rises by nearly 8 to 10° C, stop the current and immediately determine the time for which the current has been passed with the help of a stop-watch. It gives t. When the current is switched off, immediately determine the temperature of water by the thermometer. Let it be θ_2 °C.

To determine radiation correction.—To obtain this correction, allow the water to cool for the same time, for which it was heated. Determine the fall in temperature of water during this time. Let it be θ_1 °C, then the radiation correction will be $\frac{\theta_1}{\theta_2}$ °C. Add this value to θ_2 to get the final corrected temperature θ_2 .

9. If possible, change the current in the calorimeter and similarly obtain another set of readings for all the quantities. If time permits, two to three such different sets should be taken.

10. Determine J from each set, and then find out the mean value of J.

[Note.—Some times a copper voltmeter is also employed to measure current in the coil.]

Observations:—

1. Mass of the calorimeter with stirrer (m) = ... gm.
 2. Mass of calorimeter with stirrer + water (m₁) = ... gm.
 3. Initial temperature of water (θ_1) = ... °C.
 4. Final temperature of water (θ_2) = ... °C.
 5. Current passing in the heating coil (I) = ... amp.
 6. Potential difference across the heating coil (R) = ... volts.
 7. Time for which the current was passed (t) = ... sec.
 8. Fall in temperature of water after cooling for the same time for which the current was passed (θ_1) = ... °C.
 9. Sp. heat of copper (S) = ...
- Calculations:—
1. Mass of water (m) = (m₁ - m) = ... gm.
 2. Final corrected temperature, (θ_2) = $\left(\theta_2 + \frac{\theta_1}{2}\right)$ = ... °C.

3. Water equivalent (W_1) = $m_1 S_1$ = ... gm.
 Substitute the values of R , I , t , m , θ_1 , θ_2 , and W_1 in equation

$$J = \frac{E I t}{(W_1 + m)(\theta_2 - \theta_1)}$$
 and calculate the value of J .

Result:—The mechanical equivalent of heat = ergs per

Precautions and sources of error:—1 It is very important

this experiment to check up the connections before starting the experiment

If the instruments are not properly connected, they may be damaged

2. The potential difference across the heating coil should not

any case exceed 6 to 8 volts, otherwise electrolysis of water is

producing serious errors.

3. The water should be stirred constantly so that the temperature

through out the calorimeter may remain uniform. It should also

be stirred while determining the radiation correction.

4. The radiation correction should always be applied.

5. The current should be kept constant through out the operation

of the experiment. It can be achieved with the help of a rheostat.

6. The final temperature of calorimeter and its contents must

not be allowed to increase by more than 10°C over that of the room

temperature, otherwise heat losses due to radiation will be quite large

7. If possible, thermometer reading up to 1°C should

be employed to register the temperature.

Criticism:—The value of J determined by this method is not

very accurate due to the following reasons.

(1) Though the radiation correction is applied, radiation losses

cannot be completely eliminated. Therefore, the amount of heat

calculated is always less than the amount of heat generated. Thus, the

value of J obtained by this method is slightly higher.

(2) As the thermometer and the heating coil also possess

thermal capacity, they also take up some heat which is erroneously

attributed to water only.

(3) Some heat is also lost due to the evaporation of water.

(4) The current flowing through the voltmeter is also not

negligible and some of the current flows through the heating

coil and some of the current flows through the voltmeter.

(v) Due to rise in temperature, the resistance of the heating coil varies, and it becomes very difficult to keep the current and the p. d. across it constant through out the experiment.

To obtain better results, the heating coil should be made of the material possessing very high specific resistance and negligible temperature coefficient. The voltmeter should possess high resistance, and liquid possessing low vapour pressure should be used instead of water. To minimise the radiation losses calorimeter must be placed in a double walled chamber in which water flows to insulate.

Oral Questions — 1. What is Joule's law? 2. Define J , and explain how is it determined in this method? 3. Explain how the work is done and heat is produced in this experiment? 4. Where is the heating coil placed in this experiment? 5. Why thick copper leads are taken? what will be the harm if the wire is directly connected to the terminals? 6. What is the material used in the construction of the resistances wire used in the heater and why? 7. What is radiation correction and how is it applied. 8. Why the p. d. across the heater should not be increased beyond 8 volts? 9. Why this method is not very accurate? 10. How much rise in temperature is permissible in this experiment? 11. Do you know any other better electrical method for determining J ?

EXPERIMENT No. 23

Experiment—To determine the value of J , the mechanical equivalent of heat by Callender's and Barne's continuous flow calorimeter.

Apparatus—A constant level bath, Callender and Barne's continuous flow calorimeter, an ammeter, a voltmeter, a rheostat, a beaker, a stop watch, battery of accumulators, two thermometers reading upto $\frac{1}{5}^{\circ}\text{C}$, measuring flask, weight box, physical balance, key and connecting wires etc.

Description of the apparatus—Callender and Barne's continuous flow calorimeter—it consists of a heating coil made of fine nichrome wire, mounted along the axis of a narrow glass tube as shown in fig. 1. The two ends of the heating coil are soldered to two terminals provided on narrow metal tubes attached to the ends of the glass tube. Two wider metal tubes are attached to these narrow metal tubes with small

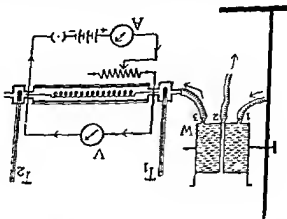


Fig. 1

pieces of rubber tubing. The wider tubes are provided with side tubes which serve as inlet and outlet for the water flowing in the calorimeter. Water enters the calorimeter from the left side and leaves by

the right side tube. The wider tubes are fitted with corks at the top. Holes are drilled in the corks, and two thermometers T_1 and T_2 are inserted in them. T_1 gives the temperature of water entering the calorimeter, while T_2 the temperature of water flowing out of the calorimeter.

W is a constant level water bath. Its outlet tube is connected to the inlet tube of the calorimeter. Most of the connections are self-explanatory. Current is passed in the heating coil either from a battery of accumulators (see fig. 1 or from an A. C. source as described in the last experiment.

Theory.—Let I_1 (in amp.) be the current flowing through the coil when E_1 (in volts) is the potential difference across its two ends. Then, the amount of work done W (in ergs) by the current in one sec. is given by the relation,

$$W = E_1 \times 10^8 \dots\dots\dots (1)$$

Due to this, heat is produced in the coil. If J is the mechanical equivalent of heat, and H the amount of heat produced per sec. in calories, we have,

$$J = \frac{W}{H} \dots\dots\dots (2)$$

Major portion of this heat is absorbed by the current of water continuously flowing through the calorimeter while a small part of it is lost to the surroundings due to radiation. In the steady state, i. e. when the temperatures of the inflowing and outflowing water attain steady values, let the amount of heat absorbed by the current of water in one second be H_1 calories, and that lost in one second due to radiation etc. be H_2 calories. Then, we have

$$H = H_1 + H_2$$

$$= m_1 S (\theta_1 - \theta_2) + H_2 \dots\dots\dots (3)$$

Where m_1 is the mass of water flowing out per sec., S the sp. heat of water, θ_1, θ_2 the temperatures of the inflowing and out flowing water respectively. From eqn. (1), (2) and (3) we get,

$$E_1 I_1 \times 10^8 = J [m_1 S (\theta_1 - \theta_2) + H_2] \dots\dots\dots (4)$$

Let the current flowing in the heater be now changed to I_2 and let E_2 be the new potential difference across its two ends. The rate of flow of water is now so adjusted that in the steady state the difference in temperature registered by the two thermometers T_1 and T_2 is again

the same i. e. $(\theta_2 - \theta_1)$. Thus, the heat lost per sec. due to radiation both the cases in the same. If now m_2 is the mass of water flowing per sec., we have,

$$R_2 I_2 \times 10^7 = J \{ m_2 (\theta_2 - \theta_1) S + H_2 \} \dots (v)$$

Eliminating H_2 from eqns. (v) and (iv), we get,

$$J = \frac{R_2 I_2 - R_1 I_1}{S (m_1 - m_2) (\theta_2 - \theta_1)} \text{ If } S \text{ is taken to be equal to } 1$$

we get,

$$J = \frac{R_2 I_2 - R_1 I_1}{(m_1 - m_2) (\theta_2 - \theta_1)} \dots (vi)$$

Method.—) Make the connections as shown in fig. 1. Connect the heating coil, the ammeter, the rheostat and the key in series with the battery of accumulators. (If A. C. current is to be used, follow the procedure described in the previous experiment i.e. the heating coil should be placed in series with the out put terminals of a stepdown transformer). Connect the voltmeter across the two ends of the heating coil. Current in both of these instruments should enter from the two terminals.

2. Connect the inlet tube of the constant level bath IV to a water tap, and its outlet tube to the inlet tube of the continuous flow calorimeter with the help of a rubber tubing. (The central tube of the constant level bath is connected to the sink). Adjust the flow of water from the tap so that the level of water in the bath remains constant (surplus water is discharged in the sink through the central tube). Adjust the height of the water bath so that a slow but steady and continuous current of water issues out of the outlet tube of the calorimeter. (The water should come out nearly at the rate of 1 to 2 c. c. per minute).

3. Now switch on the current, and with the help of the rheostat adjust its value to near about 1.5 to 2 amp. Due to the passage of current heat will be produced in the coil. The heat so produced will be taken up continuously, by the stream of water flowing in the glass tube. Consequently the temperature of the out flowing water will gradually rise indicated by the thermometer T_2 .

4. By adjusting the height of the water bath, adjust the rate of flow of water, so that a temperature difference of about 4 to 5°C is set up between the two thermometers T_1 and T_2 . Now wait till the temperature of water in the two thermometers attain steady values. To know whether they have attained steady values or not, read the thermometer

eters after every five minutes. If there is no change in the respective values of temperature denoted by them for nearly three consecutive readings the temperatures may be considered to be steady.

5. After obtaining the steady conditions and noting that the rise in temperature is near about 4 to 5°C , read the two thermometers T_1 and T_2 . They will respectively give θ_1 and θ_2 .

6. To determine the mass of water flowing out per sec, take a clean and perfectly dry measuring cylinder. Put the cylinder below the outlet tube of the calorimeter and simultaneously start the stopwatch. Collect water for a certain interval of time say, for t_1 seconds. (Generally the water is collected for 10 to 15 minutes). After t_1 seconds, immediately remove the cylinder and stop the stopwatch. Determine the volume of water collected in t_1 sec. from the measuring cylinder. As the density of water is unity, numerically the volume will be equal to the mass of water collected in t_1 sec. Let it be M_1 gm. From this observation, determine the mass of water m_1 flowing out per sec. Note:—It can also be found out by taking a weighed beaker and collecting water in it for t_1 sec. The beaker is again weighed. The difference between two masses gives the water collected in t_1 sec.

7. Determine the value of the current i , flowing through the coil with the help of ammeter A .

8. Measure the potential difference (E_1) across the two ends of the conductor with the help of voltmeter V . It constitutes one set of observations.

9. Now slightly alter the value of the heating current. By lowering or raising the constant level bath, adjust the flow of water in such a way that again in steady conditions, same temperature difference ($\theta_2 - \theta_1$) is established between the two thermometers. It is very important to see that the rise in temperature ($\theta_2 - \theta_1$) is exactly the same in both the sets of observations.

10. Find out the value of the current (i_2) flowing in the coil by the ammeter and $P. d. (H_2)$ across it by the voltmeter.

11. As described in step 6, determine the changed rate of flow of water (m_2) i.e. volume of water flowing out per sec. Again take two to three different observations for the determination of m_2 . It constitutes second set of observations.

12. If there is time, more sets of readings should be taken by altering current and adjusting rate of flow of water (keeping the rise in temperature same).

13. Note carefully the current and the voltage of the voltmeter for the standard lamp.

14. Write down by table in 12 observations and then the observations (if you have taken more than two sets) and then the mean value of I .

Observations:—

- (1). Temperature of the flowing water (θ_1) = ... °C.
 (2). Temperature of the outflowing water (θ_2) = ... °C.

[3]. Table for the first set of observations.

S.N.	P.D. in Volts (E_1)	Current in amp. (I_1)	Mass of water collected in gm. (M_1)	Time taken in sec. (t_1)	Mass of water flowing out per sec. in gm. $m_1 = \frac{M_1}{t_1}$
1					
2					
3					

[4]. Table for the second set:—

S.N.	P.D. in Volts (E_1)	Current in amp. (I_1)	Mass of water collected in gm. (M_1)	Time taken in sec. (t_1)	Mass of water flowing out per sec. in gm. $m_1 = \frac{M_1}{t_1}$
1					
2					
3					

[5]. Prepare similar tables, if you take more than two sets.

Calculations:—Knowing all the values required, calculate the value of J by the formula:

$$J = \frac{E_1 I_1 - E_2 I_2}{(m_1 - m_2)(\theta_1 - \theta_2)}$$

Then any of the two sets taken, for calculation purposes.

Precautions and sources of error:—1. The heating wire should be taken in the form of a spiral. This particular shape of the wire will keep the water *automatically stirred*, and at the same time large volume of water will come in contact with the heater.

2. The rate of flow of water through the glass tube should be kept constant, otherwise θ_1 and θ_2 will not remain steady. It can be done by properly adjusting the constant level bath.

3. Current in ammeter and voltmeter should enter from the terminal marked +ve.

4. The rate of flow of water, and the current should be so adjusted that the rise in temperature is near about 4 to 5°C.

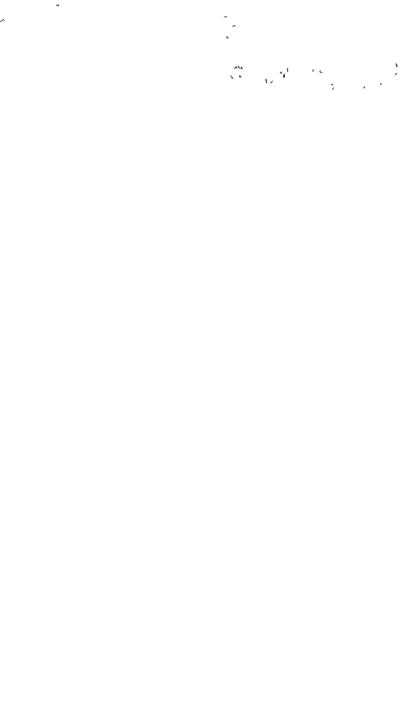
5. As the rise in temperature is small it should be measured very accurately. Preferably thermometer reading up to 1/10°C should be used.

6. The rise in temperature ($\theta_2 - \theta_1$) should be steady the same in the two sets of observations.

7. To start with let the water flow in the calorimeter and then switch on the current. Reverse this order at the end of the experiment. If it is not done so, due to excessive heat produced in the coil, there is a danger of its getting burnt.

Criticisms.—The value of J obtained by this method is fairly accurate. Losses of heat due to radiation have been eliminated to a very great extent by taking two sets of observations for the same *rise of temperature*. Hence, in these conditions the temperature at every point of the apparatus is the same as both the heat losses are also the same. The greatest advantage of the method is that when the attainment of steady state there is no change in temperature on any part of the instrument. Hence no further heat is absorbed by calorimeter, heater, or thermometer. Thus no correction is needed for their thermal capacities. As the two temperatures become steady, they can be determined with a high degree of accuracy. As the water is well stirred temperature over any cross-section of the tube remains uniform. The current enters the heat losses due to radiation the same time should be balanced by a correspondingly equal amount gained.

Thus all these advantages the accuracy of the result is improved. It is not as good as the various methods mentioned above. The method is not as accurate as the method described in the preceding chapter. It is not as accurate as the method described in the preceding chapter.



EXPERIMENT NO. 24

Experiment—To determine the frequency of an electrically maintained tuning fork with the help of Melde's experiment.

Apparatus—An electrically driven tuning fork, accumulator, thread, pulley, physical balance, weight box, metre scale, clamps etc.

Description of the apparatus—One end of a long and light string (usually in the form of a thread) is tied to one of the prongs of a large tuning fork *T* (see figs. 2 and 3.) The other end of the thread passes over a pulley and carries a pan or a hanger in which weights can be placed. By changing the weights placed in the pan, tension can be altered in the string. The vibrations of the tuning fork are maintained electrically.

Electrically maintained tuning fork—*T* is a tuning fork clamped to a stand or on a table. An electro-magnet *C* is placed between its two prongs as shown in fig. 1. One

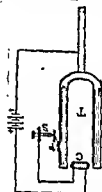


Fig. 1

terminal of the battery is connected to the shank of the tuning fork, while the other is connected to an adjustable screw *S* through the coil of the electro-magnet *C*. The screw is provided with a platinum tip. One end of a metallic strip *p* is fixed to one of the prongs of the fork, while its other end is put in front of an adjustable screw *S*. When the screw is moved forward its tip touches the free end of the strip *p*, completing the electric circuit. Due to the flow of current in the coil, the electro-magnet is actuated, and the two prongs of the fork are attracted towards the electro-magnet. Thus the two prongs are pulled inward. This results in breaking of the contact between the strip and the screw, and therefore, current stops to flow. The electro-magnet loses its magnetism and no longer keeps the prongs attracted. Hence, the prongs move outwards, and again the contact between the strip and screw is established. Again, the current flows in the coil and the whole process

the string i. e. the thread is stretched at right angles to the length of the prong. Between the two nodes formed at the ends number of nodes and antinodes are formed depending upon the number of loops.

In this arrangement, when the prong moves towards the extreme left position, a sag is produced in the thread in the downward direction. When the prong moves towards extreme right, the thread becomes straight and taut, acquiring velocity in the upward direction. When the prong again moves towards left, the thread instead of sagging moves

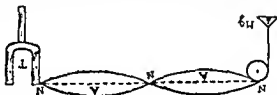


Fig. 3

upwards, on account of the velocity it possesses. Thus during the time tuning fork completes one vibration, the thread completes only half of the vibration. Hence the frequency of the thread is half that of the

the fork.

As before if p is the number of loops formed, l the length of the thread containing these p loops and n the frequency of the thread.

we have

$$n = \frac{p}{l} \sqrt{\frac{T}{m}} \quad \text{.....(iv)}$$

Where T and m are respectively the tension applied and mass per unit length of the string. As in this case, $N = 2np$, we have

$$N = \frac{l}{\lambda} \sqrt{\frac{T}{m}} \quad \text{.....(v)}$$

N , the frequency of the tuning fork can be determined either from equation (iv) or (v).

Note.—It is clear from these equations, that a string of length l , under a tension T will break up into double the number of loops as there were antinodes when it is the first produced error possible.

Method—[A] Transverse arrangement.—1. Connect one end of the string to the handle of the tuning fork (Fig. 1).

while the other to the adjustable screw *S* through the coil of the electromagnet *C*.

2. Take a fork and light thread and fix one of its ends to the prong of an electrically driven tuning fork with the help of a binding screw provided on the prong. Pass the thread over a frictionless pulley and from its other end suspend a pan. Put the tuning fork as shown in fig. 2 so that its prong is in line with the thread.

3. Now move the adjustable screw so that it touches the tip and current begins to flow in the coil of the electro magnet. Due to the flow of current the fork begins to vibrate.

4. Put suitable amount of weights to the pan, so that the thread splits up in to several loops. By using smaller weights or sand, adjust the tension in such a way that the loops become clear and well defined. The nodes must reduce to fine points.

5. After this adjustment, select a certain number of well defined loops (it is better to leave the first and the last loop). Count them. It gives *p*.

6. Determine the length of the thread between the loops counted i. e. between *p* loops) with the help of a metre scale. It gives *l*.

7. Find out the mass of the weights (including and if put) placed on the pan. Let it be $= m_1$ gm. Now weigh the pan. Let its mass be $= m_2$ gm. The total amount of mass suspended M gm. $M = m_1 + m_2$. Knowing M , determine the tension applied ($T = Mg$, here g is the acceleration due to gravity).

8. Take a certain length of the specimen thread. Determine its length (*L*) by a meter scale, its mass (*M*) by a balance, and then calculate its mass per unit length (*m*). Take atleast three different observations.

9. Knowing *l*, *p*, *T* and *m* determine the frequency *N* by this set formula (ii).

10. To take more sets of readings, alter tension varying the number of weights placed in the pan. Number of loops will consequently change. As described above, again adjust a amount of weights in the pan to obtain clear and well defined loops. Again determine corresponding values for *l* and *p*. In this way by altering tension

take at least three different sets of observations, and switch off the current.

11. Calculate N by each set, and determine the mean value of N .

[B] Longitudinal arrangement—12. In this case make connections as described in step 1, and place the tuning fork as shown in fig. 3. Now the thread is stretched perpendicular to the length of the prong.

13. As described above, adjust the tension and determine the corresponding values for p and l .

Note—It would be observed that in this case for the same values of l , T , N and m , the number of loops is reduced to half.

14. Change tension by changing the amount of weights put in the pan, and similarly take three different observations for p and l . Find out the value of T in each case as described above.

15. Knowing the value of m , the mass per unit length of the string, calculate N by each set using formula (iv). Determine the mean of N .

16. Now determine the mean of the two values of frequency obtained from transverse and longitudinal arrangements.

Observations:—

- [1] Acceleration due to gravity $g = \dots$ cm/sec./sec.
[2] For the determination of m —

S. N.	Mass of the thread (M_1) in gm.	Length of the thread (l_1) in cm.	Mass per unit length $m = \frac{M_1}{l_1}$ in gm.
1			
2			
3			

Oral Questions:—1. What type of waves are produced on a string? How are they produced? 2. Explain nodes and antinodes. What is the difference between stationary waves and progressive waves? 4. What are the laws of vibration of a string? 5. What are the two modes of vibration of the fork with respect to the three experimental arrangements in two modes? 6. What is the ratio of the frequency of the thread in the two modes? 8. What are the same values of N , T , and m do you get the same number of loops in the two modes, if not why? 8. How can you change the number of loops obtained on the thread? 9. If you are getting seven loops in the transverse arrangement, how many loops would you expect in the longitudinal arrangement? Give reasons for your answer. 10. Can you verify the laws of transverse vibration of strings by this method? Explain how the vibrations of the fork are maintained? 12. Why a spark is produced at the point of contact, and how can it be reduced or eliminated? 13. What are the sources of error in this experiment and how are they eliminated?

EXPERIMENT NO. 25

Experiment:—To find the focal length of a combination of two lenses separated by a certain distance by nodal slide method.

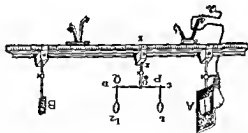


Fig. 1

Description—Nodal slide bench—It is an optical bench carrying four stands. A electric bulb closed in a box (not shown in the fig.) is mounted in one stand. There is an opening on one side of the box. A white metal screen with a cross slit is mounted on another stand just before the opening of the box. On one of the stands X, the lens system can be mounted in two lens holders P and Q fixed on a transverse rod CD. (In case of lenses separated by a distance) or the lenses can be mounted in one holder at O (in case of a single lens or in case of lenses placed in contact). The stand X can move as a whole along the bench and its position can be noted on the bench. A small linear scale is also provided on the bed of X on which OX' can be moved with the help of a rack and pinion arrangement. PQ can also be rotated about an axis ON' and its position can be read on the circular scale marked on X. The distance between the two lenses can be adjusted by moving P and Q along the rod CD. Again by sliding the rod CD through O the position of ON' (i.e. axis of rotation) can be shifted from P to Q. On the fourth stand a plane mirror (B) is mounted facing towards the lenses. Some times the lamp is supported on the same stand as the screen.

Theory:—We know that for any thin lens, the position of the object and image is given by $\frac{1}{v} = \frac{1}{f} + \frac{1}{u}$ where u is the distance of the

object, v is the distance of the image from the lens and f is the focal length of the lens. We can also locate the image of any object graphically by drawing a few set of rays.

Now consider a coaxial system of lenses separated by a certain distance. The image of any object can be located in that system by applying the above relation successively for each lens. The image is one serving as an object for the other and so on. But this method is tedious and cumbersome. Gauss defined a set of points for an optical system such that if they are known in case of any system the position of the image of any object can be located without knowing the actual nature or details of the system. These points are known as cardinal points or Gauss points. There are 3 such pairs of points (in all six points). This treatment applies to a coaxial system.

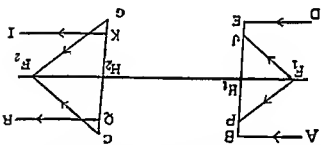


Fig. 2

Focal points:—The point F_1 , lying on the axis of the system such that the rays starting from F_1 (or proceeding towards F_1 in case of a divergent system) like F_1P and F_1J after passing through the system go parallel to the axis, is known as First principal focus or focus of the object space. A plane passing through F_1 and perpendicular to the axis is known as first focal plane. Rays diverging from any point on this plane (not on the axis), will go as a parallel beam in the image space. In this case they will not be parallel to the axis. This plane is given by the relation $v = \infty$. Again if rays

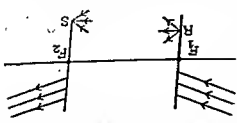


Fig. 3

parallel to the axis are incident on the system, after passing through the system they will converge at a particular point (or will appear to diverge from a particular point in case of a divergent system). This point is known as second principal focus or focal point of the image space. A plane passing through this point and perpendicular to the axis is known as second focal plane. All parallel rays (which are not parallel to the axis) will converge (appear to diverge from) at any point on this plane.

Principal points and principal planes of unit magnification.—These are two conjugate planes (BF and CG) such that if any object lies in one of them (BF), its image will lie in the other (CG). This image will be of same size and will lie on the same side of the axis. Therefore these planes are also known as planes of unit magnification. If a ray say E_1P meets the plane BF at a height H_1P , its conjugate ray QR will meet the second plane CG at the same height H_2Q , i. e. $H_1P = H_2Q$. The points of intersection H_1 and H_2 of these planes with the axis are known as principal points of the object space and image space respectively.

Again the distances of the object and image are respectively measured from these planes. The distance of E_1 from H_1 is known as focal length of the object space (F_1). The distance of R_2 from H_2 is known as focal length of image space (F_2). We know that when the medium on both the sides is the same, $F = F_2$.

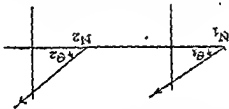


Fig. 4

Nodal points.—These are two conjugate points N_1 and N_2 such that if a ray passes through one of them, its conjugate ray will pass through another and will go parallel to the incident ray. That means their angular magnification is unity ($\frac{\tan \theta_2}{\tan \theta_1} = 1$). Again the distance between them (N_1N_2) is equal to the distance between two principal points (H_1H_2), i. e. $N_1N_2 = H_1H_2$. We also know that when the

medium is same on both the sides, the two nodal points respectively coincide with the two principal points.

Principle of auto-collimation:—Consider a lens system placed as shown in the figure. M is a plane mirror and P is an illuminated source. If the position of P is so adjusted that the image of P is formed

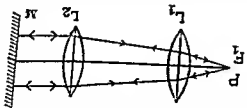


Fig. 5

at the same place i. e. at F_1 , then the rays are falling normally on the mirror and therefore retrace back their path. Since the mirror is normal to the axis therefore the rays falling on the mirror are parallel to the axis. Hence according to the definition P lies at F_1 , the focal point of the lens system. The rays after passing through the lens system fall normally on the plane mirror as a parallel beam and retrace back as a parallel beam and are converged by the system again at P . Thus here plane mirror acts as a collimator as well as reflector. This is known as auto collimation.

Principle of Nodal slide—Consider three parallel rays AB , CN_1 and DL incident on the lens system. They lie in a plane perpendicular to the plane of paper i. e. perpendicular to the vertical plane. Again this plane also makes a

certain angle with the horizontal plane passing through the axis. One of these rays CN_1 passes through the nodal point N_1 , therefore its conjugate ray N_1P will be parallel to CN_1 and meets the focal plane at P . Since the rays are parallel to

Fig. 6



CN_1 and meets the focal plane at P . Since the rays are parallel to the axis they will converge at a point in the focal plane. Similarly all the other rays will also converge to form at P . Hence P is the image of the object. Now suppose rotate the system in a horizontal plane about the axis. The position of N_1 will change but the position of P will remain the same. This is the principle of the nodal slide.

4. Now rotate the system slightly about OX' and note the shift of the image. Suppose the shift is towards left.
5. Move the rod CD such that the distance OP increases slightly.
6. Again focus the cross by moving the lens system as a whole i. e. by moving X .

7. Again rotate the system about OX' note the shift of the image.
8. In this way every time shift the axis of rotation towards O and after focusing it again note the shift. Go on doing this till the image shows no shift on rotating the system. In this position the axis OX' is passing through the second nodal point N_2 . If the axis is further shifted the direction of the shift of the image will change. Now it will shift towards right.

9. Note the position of X and that of the slit. (screen). The distance between X and the screen (AX) gives the focal length. Provided OX' lies at the O of the small scale on the bed of X . If it is not on zero then add or subtract its reading from the above distance to get the focal length.

10. Now rotate the system by 180° and again find out the focal length as shown above and find the mean. Change the position of the slit (A) and again repeat the above procedure. This gives second set Take 4 or 5 sets.

Observations:—
The distance between two lenses =cm.

Observation table for F_1 .

Set No.	when light is incident on L_1		when the light is incident on L_2		Mean F
	Position of slit (A)	Position of axis OX'	Position of slit	Position of axis	
1					
2					
3					
4					
5					

Result:— $F = \dots$ cm.

Precautions and sources of error:—1 The slit should be properly illuminated.

2. See that false image due to reflection from lens surface is not mistaken for the real image.

3. The rotation should not be more than 4° or 5°.

4. If on moving the axis towards nodal point the image shifts on one side, then on crossing the nodal point it will shift on opposite side.

Modification :—Verify the formula,

$$\frac{1}{F} = \frac{1}{f_1} + \frac{1}{f_2} + \frac{f_2}{d}$$

In this case first find out the values of f_1 and f_2 separately. For

this remove the rod CD and mount the lens (L_1) on the holder at O. Now move the lens away from or towards the screen A, till a well defined image of the cross slit is formed on the cross again. Confirm this by slightly rotating the lens about the axis OX. The image will not shift. Measure the distance of the lens from the cross slit. This gives f_1 . Rotate the lens by 180° and again repeat the above. Find out the mean focal length.

Now remove L_1 and mount L_2 in its place and find out its focal length f_2 as shown above.

Now fix up the lens in the slide assembly at a certain distance apart and find out the focal length F of the combination as shown in the above experiment. Measure the distance d also. Calculate the value of F using the above formula. Compare this value with the experimental value. If the two agree the formula is verified.

Repeat the same experiment for different values of d and verify the above relation in each case.

Observations :—

1. Focal length of lens (L_1), $f_1 = \dots \dots \text{cm.}$

2. Focal length of lens (L_2), $f_2 = \dots \dots \text{cm.}$

Set No.	Distance between lenses	Light incident on	Position of cross slit	Position of axis	Focal length F	Mean F from each set	calculated F
1		one lens					
2		other lens					
		one lens					
		other lens					
3		one lens					
		other lens					

Since the calculated and experimental values agree, hence the formula is verified.

Oral questions:—1. Define cardinal points. Focal points. Principal points and Nodal points of an optical system. 2. Why do you call principal planes as unit planes? 3. What do you mean by the focal length of object space, focal length of image space and focal length of combination? 4. What is an equivalent lens? 5. In what respects it is equivalent to the optical system. 6. What is the principle of your experiment? 7. Is this method suitable for a thick lens? 8. Where do we use combination of two lenses.

OPTICAL LEVER

Use of optical lever. To measure the depression in case of bending of beam experiment.

Description:— It consists of a metallic plate supported on three legs A, B and C. A plane mirror M is fixed perpendicularly to the plate and along the line A B. When the instrument is placed on a plane

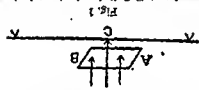


Fig. 1

glass plate A B C, lie in a horizontal plane and M remains vertical. Another part of this lever is a vertical scale and telescope fixed on a stand.

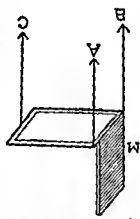


Fig. 2

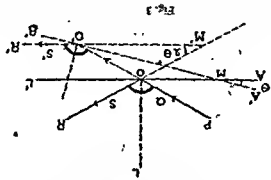


Fig. 3

Theory:—(i) when a mirror rotates by an angle θ , the reflected ray remaining constant the incident ray rotates through an angle 2θ .
(ii) When angles are small $\tan \theta = \theta$.



PART II
(For III year Degree Course)



EXPERIMENT No. 26

Experiment:—To determine the moment of inertia of wheel about its own axis.

Apparatus:—Fly wheel, weight box, vernier callipers, arch, thread, meter scale etc.

Description of apparatus:—It consists of a heavy wheel

with a horizontal axis AB mounted on two ball bearings fixed in rockers on a table. The wheel is placed at some convenient height from the ground. The axle carries a hole at P where a string can be slipped, there is a peg into which a loop of a string can be slipped, the wheel is capable of rotation about a horizontal axis.

Theory:—When a string carrying a mass m , is wrapped round the axle, and allowed to fall freely under gravity, the falling mass loses potential energy, the kinetic energy of translation to itself, (ii) K.E. of rotation to the fly wheel, and (iii) doing work against friction by the rotation.

$$mgh = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2 + F_m \dots \dots \dots (1)$$

h is the height through which the mass descends which is equal to the length of the string.
 v is the velocity of the mass when it is detached from the axle.
 ω is the angular velocity of the fly wheel when the mass is detached from it.
 I is the moment of inertia of the fly wheel
 F is the work done against the force of friction for one rotation of the wheel.
 m is the number of rotations the wheel makes till the mass is detached from it, which is equal to the

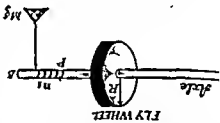


Fig. 1

number of turns of the string wrapped round the axle before the mass is made to fall

λ is acceleration due to gravity.

If the wheel makes n_1 rotations and takes t secs. before it comes to rest, after the mass has been detached, (i.e. due to friction), we have,

$$n_1 F = \frac{1}{2} I \omega^2 \dots \dots \dots (i)$$

$$W = I \alpha \dots \dots \dots (ii)$$

and $r = r_1 t \dots (iv)$ where r is the radius of the axle of the fly wheel

From eqns. (i), (ii), (iii) and (iv) we get

$$1 = \frac{n_1 + n_2}{m} \left[\frac{g h r^2}{I} - n r^2 \right] \dots \dots (v)$$

Method:—1. First of all see that the wheel can rotate freely if not, oil the bearings so that the friction is reduced.

2. Take a thread whose length is less than the height of the axle of the wheel from the ground. Tie a suitable mass (say $\frac{1}{2}$ k.gm.) to one end of the thread. Form another end into the form of a loop. Slip the loop loosely on the peg P. If there is no peg and only a hole, fit a brass pin in the hole and then put the loop.

3. Wrap the thread around the axle till the mass hangs just near it. The thread should be evenly wound. No two turns should overlap each other. Count the number of turns of the thread (n_1).

4. Now release the mass and allow it to fall freely. Count the number of rotations the wheel describes before the mass falls off and the thread is detached from the axle. It can be done by making a reference mark by a chalk on the fly wheel, and putting a pin by a separate stand in front of the mark. Let it be n_2 . Naturally the number of rotations made by the wheel is equal to the number of turns of the thread wound on the axle.

5. When the mass falls off and the thread is just detached from the axle, start a stop-watch. Count the number of rotations made by the wheel before it comes to rest on account of friction. Let them be n_3 . Stop the stop-watch when the wheel stops moving, and determine the time t for which the fly wheel moves after the detachment of the mass. It gives t .

6. Measure the length of the thread. It gives the height (h) through which the mass falls.

7. Find the V. C. of the callipers and determine the diameter of the axle with its help. It should be determined at three to four different places and then mean diameter should be found out.
8. For the same length of the thread and the mass, repeat the procedure to get m_1 , m_2 and L .
9. Change the length of the thread, and mass suspended at least for three times, and for each set take at least two different observations for m_1 , m_2 and L .
10. Calculate the moment of inertia of the fly wheel by each set, and then determine the mean moment of inertia.

Observations:—

1. For the radius of the axle:
 (A) L. C. of the vernier callipers. = ... cm
 (B) Diameter of the axle
 (1) = ... cm, (2) = ... cm, (3) = ... cm, (4) = ... cm.
 Mean diameter = ... cm.
 Mean radius (r) = ... cm.
 2. Acceleration due to gravity = cm/sec^2
 3. Length of the thread = cm.
 4. For the number of rotations and time:—

No	Helix (b)	Mass suspended in gm.	No. of rotations made by the wheel when the mass is detached (n ₁)	No. of rotations made by the wheel after the mass has fallen (n ₂)	Time taken by the wheel to come to rest (t) in sec						
						1	2	Mean	1	2	Mean
1.											
2.											
3.											

Calculations:—

Applying formula (v) calculate I.
 For the 1st Set I = $\text{gm} \times \text{cm}^2$
 2nd Set I = "
 3rd Set I = "
 Mean I = "

Result:—The moment of inertia of the fly wheel $= I$.
 Precautions and sources of error—1. The friction at the bearing is not to be too large, if it is so when the mass is released, it will fail to set the wheel in motion. It can be reduced by oiling.

2. The mass selected should not be so large that when it is detached, the wheel begins to rotate so quickly that it may become difficult to count the number of rotations made by it.
 3. The length of the string should be less than the height of the axle from the ground.

4. The loop placed on the peg should be quite loose. If it is not so when the thread unwinds completely, it will not leave the axle. Rather, it will begin to wound in the opposite direction.

5. The radius of the thread should be very very small in comparison to the radius of the axle. If it is not so the radius of the thread should be added to the radius of the axle to get r (because $v = r\omega$).

6. The stop-watch should be started exactly at the time when the thread is detached from the wheel.
 Criticism:—In this experiment it is pretty difficult to start the stop-watch just at the moment when the mass is detached. It causes error in the determination of ω and ω^2 . Furthermore, sometimes the wheel does not complete full rotations and hence n cannot be determined very accurately.

The angular velocity of the wheel (ω) has been determined ($\omega = 2\pi n/t$) on the assumption that the friction remains constant while ω is reduced from the value ω to 0. But it is not true because actually the force of friction is more at small velocities, and hence ω does not remain constant. Therefore, if more accuracy is the aim ω should be determined with the help of a turning fork, where no such assumption is made.

Oral Questions—(1) What do you understand by the term moment of inertia of a fly wheel? What is a fly wheel? (2) Why it has got a particular shape and where is its mass concentrated? (3) What is its necessity in a steam engine and automobiles? (4) Why the length of the string taken should be less than the height of the axle from the ground? (5) Can you take a string of quite a large radius, if not, why? (6) Why there should not be much friction at the bearings? If it is so, how can you reduce it? (7) Why the angular velocity (ω) determined by this experiment is not so accurate? Can you suggest some better method of determining ω ? Can the different turns of the thread overlap each other, if not, why?

EXPERIMENT No. 27

Experiment:—To determine the electro-chemical equivalent of copper with the help of a copper voltmeter, using a tangent galvanometer.

Apparatus:—A copper voltmeter, one similar extra plate of copper, a rheostat, an accumulator, a tangent galvanometer, a stop-watch, sand paper etc.

Description of the apparatus:—Copper Voltmeter:

It consists of a glass vessel nearly filled up with 15 to 20% acidulated solution of copper sulphate. Three plates of copper are dipped in the solution as shown in Fig. 1. The two outer plates A A are joined together and are having a common binding screw. They form the anode of the voltmeter. The current enters through the anode. The middle plate, also carrying a binding screw forms the cathode. The cathode is well insulated from the anode plates, and is movable. It can be taken out, dried and cleaned.

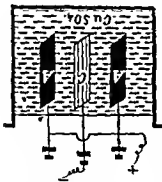


Fig. 1

Tangent galvanometer:—It consists of a circular coil of insulated copper wire of a few turns wound upon a wooden frame. The frame is capable of rotating about a vertical axis fixed at the centre of a circular horizontal disc fixed at the base. The base rests upon three leveling screws. At the centre of the coil, there is placed a cylindrical box covered with glass. The box carries a horizontal circular scale fixed at its base. The scale is divided into four quadrants reading 0° to 90° A small magnetic needle is freely pivoted at the centre of the circular scale. A long and light aluminium pointer is attached to the needle at right angles to its length. The pointer moves over the circular scale. The base of the box also carries a mirror in which the image of the pointer can be seen. The box is also capable of rotation along a vertical axis.

The two ends of the coil are connected to two binding screws fixed on the base of the instrument. The number of turns are usually written between the two binding screws. Generally the instrument carries three or four coils of different turns each connected to a different binding screw on the base of the instrument. The coils are so arranged that any one or all of them can be put in circuit in series.

Theory:—The connections are self explanatory. A copper voltmeter and a tangent galvanometer are connected in series through a commutator key K. Let i be the current flowing

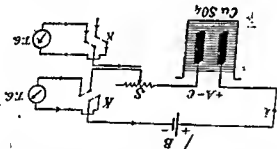


Fig. 2

through the galvanometer, when its coil is placed in the magnetic meridian and θ be the angle of deflection of its needle from the magnetic meridian, then, we have,

$$i = k \tan \theta \quad \dots \dots \dots (i)$$

where k is the reduction factor of the tangent galvanometer given by the relation,

$$k = \frac{10rH}{2\pi n} \quad \dots \dots \dots (ii)$$

where r is the radius of the coil, H the horizontal component of the earth's field, and n the number of turns in the coil.

The same current i is flowing through the copper voltmeter. Let m be the mass of copper deposited due to this flow of current for an interval of time t . Then, according to Faraday's Law of electrolysis we get,

$$m \propto i t$$

$$\text{or } m = e i t$$

where e is the electro-chemical equivalent of copper. From equations (i), (ii) and (iii) we get,

$$e = \frac{t}{m} \times \frac{10rH \tan \theta}{2\pi n} \quad \dots \dots \dots (iv)$$

Knowing m , t , n , H , r and θ , e can be calculated.

Method:—Remove the cathode plate C from the volta-mater. Clean its both the surfaces with sand paper and wash with water. Dry it completely, and weigh it in a sensitive balance. Let its mass be W_1 gm.

2. Fill two thirds of the voltmeter with the given copper sulphate solution. In place of the removed copper plate, put the extra plate of copper which is exactly similar to the former. To start with, the latter forms the cathode.

3. Now make the connections as shown in Fig. 2. connect the anode plate A of the voltmeter to the +ve terminal of the accumulator. (If there are two anode plates instead of one as shown in Fig. 1, they are internally connected to the same terminal). Connect the cathode C to the -ve terminal of the accumulator through a rheostat S, tangent galvanometer T, G, and the commutator K. (In case there are two anode plates, the third plate suspended in the middle forms the cathode.)

To adjust the tangent galvanometer:—

4. With the help of a spirit level, make the compass box horizontal by adjusting the levelling screws. Rotate the coil till it is parallel to the small magnetic needle in the compass box. Rotate the compass box keeping the coil fixed till pointer reads zero on the circular scale. Now pass some current in the galvanometer and note the deflection of the current in the galvanometer with the help of the commutator K, and note the deflection. If it is the same, the coil is in the magnetic meridian. If not so, slightly rotate the coil till the two deflections are rendered equal.

To adjust the current in the voltmeter:—

5. Close the circuit and adjust the rheostat S, so that the tangent galvanometer gives a deflection of nearly 45° . If it is not possible, the deflection should be between 35° and 60° . Wait for some time and see that the current remains constant. Now switch off the current.

6. Remove the extra plate from the voltmeter. In its place put the weighed plate (see step 1) on which the copper is to be deposited. Now this plate forms the cathode. To determine the mass (m) of copper deposited:

7. Switch on the current and immediately start the stopwatch. Care should be taken to see that the current should remain constant in the circuit. This can be done by adjusting the rheostat. Read both the ends of the pointer in the tangent galvanometer.

8. After an interval of fifteen minutes, reverse the current in the tangent galvanometer. Again read the two ends of the pointer. Pass the current for the next fifteen minutes

and then switch off the current, and stop the stop-watch (Current has been passed for nearly 30 minutes).
9. The mean of the four readings taken of the position will give the mean deflection θ .
10. Find the time t for which the current has been passed by the stop-watch. It gives t .

11. Remove the cathode plate C , and dip it in a jar filled with water to remove the traces of copper sulphate solution. Dry the plate by softly pressing its sides by either a filter paper or a blotting paper. When it has completely dried, put it in a balance and weigh it. Let its new mass be W_2 gm.
12. Subtract the former mass W_1 from this new mass W_2 and determine the mass (m) of the copper deposited.

13. Note down the number of turns (n) of the coil used.
14. Determine the radius r of the coil, by measuring the circumference of the coil with the help of a thread. If l is the length, $r = \frac{2\pi}{l}$
15. Find out the value of H at the particular place from standard tables.

16. Knowing all these things, calculate the value of θ from formula (iv),
observations :-

(1) For determining the mass of copper deposited :-
(i) Mass of the cathode plate before the deposition of copper (W_1) = ... gm.
(ii) Mass of the cathode plate after the deposition of copper (W_2) = ... gm.
(2) Time (t) for which the current has been passed = ... sec.

(3) (i) Number of turns connected (n) = ...
(ii) Circumference of the coil (l) = ... cm.
(iii) Radius of the coil $r = \frac{2\pi}{l}$ = ... cm.
(iv) H = ... Gauss.

(4) Table for determining θ :-

S.N.	Time in sec. (t)	Deflection of tangent galvanometer			
		Direct	One end and another	One end and another	Mean θ
				Reverse	

Calculations:—

1. Mass of the copper deposited (m) = $(W_1 - W_2) = \dots$ gm.
2. Knowing m , t , H , n , r and $\tan \theta$, calculate the value of e , c , e .
- Result:— c , e , of copper = \dots gm. per coulomb.

Precautions and sources of error—

1. The reagent galvanometer should be properly levelled, and its plane should always remain in the magnetic meridian.
2. All the magnetic materials or the current carrying wires should be kept as far from the galvanometer as possible otherwise the deflection will change.

3. The copper sulphate solution in the voltmeter should be made slightly more acidic by adding 0.1% by volume of sulphuric acid. It increases the conductivity of the solution. The area of the cathode plate dipped in the solution, should be nearly 50 sq. cm. per ampere, otherwise the deposit will not be smooth, and it may peel off.

4. The cathode plate should be thoroughly cleaned and dried before the deposition of copper on it. It is not perfectly clean, the deposit will not be smooth.

5. The masses of the plate, before and after deposition of copper should be determined by a sensitive balance preferably weighing up to 1/10th of a milligram.

6. During the performance of the experiment the current in the circuit should remain constant. The current strength should be nearly between 1.5 to 2 amp. Very strong current should not be passed, otherwise the deposit will be brittle.

7. As far as possible, the deflection in the galvanometer should be near about 45° . If it is not possible θ in no case be less than 30° and more than 60° .

8. Both the ends of the pointer should be read to avoid the error due to the eccentricity of the pivot with respect to the circular scale.

9. Reading for deflection should be taken first with current passing in one direction, and then after reversing the current. It removes the error if there is any, due to any want of setting of the coil in the magnetic meridian.

Criticisms:—

The method is not very accurate, due to the following reasons:

- (1) It is very difficult to set the coil of the galvanometer exactly in the magnetic meridian.
- (2) The magnetic needle though very small does not move in a uniform magnetic field.

(!!!) There is always some friction present at the pivot of the instrument.

Oral questions :—(1) Why the galvanometer is called a tangent galvanometer ? (2) What is tangent law ? (3) Why the coil of the galvanometer is placed in the magnetic meridian ? (4) Why is it levelled ? (5) Why the current is reversed in the galvanometer ? (6) Why magnetic materials should not be placed in its vicinity ? (7) What is electrolysis ? (8) What is a voltmeter, and what is the electrolyte employed in a copper voltmeter ? (9) What do you understand by e. c. of a substance ? (10) On which plate the copper is deposited ? (11) Why should this plate be thoroughly cleaned before depositing copper on it. (12) Why should the current remain constant through out the exp. ? (13) Can you employ large currents, if not, why ? (14) Why do you take two anodes and one cathode ? (15) Can you use a copper voltmeter for measuring current ? (16) Why the cathode plate should be weighed by a highly sensitive balance ?

EXPERIMENT No. 28

Experiment.—To determine the internal resistance of a primary cell i.e. a Leclanche cell with the help of a potentiometer.

Apparatus.—A potentiometer, an accumulator, a shunt wire, Leclanche cell, resistance box, two plug keys, connecting wires etc.

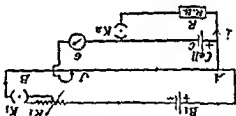


Fig. 1

Description of the apparatus.—See experiment No. 17. AB is the potentiometer wire. B, R, C, R, D, and G are respectively, the accumulator rheostat, Leclanche cell, resistance box and galvanometer. K_1 is a plug key.

Theory.—The connections are self explanatory. Let E and r be respectively the e.m.f. and internal resistance of the Leclanche cell C. If a resistance, R is connected in series with it through a plug key K_1 , current flows in it. Consequently, the potential difference across its terminals is lowered. Let the current flowing in the circuit be i , then applying Ohm's law, we get,

$$E = \frac{R + r}{i} \quad \text{--- (1)}$$

Let the potential difference across the two terminals of the resistance R be V . V is also the lowered potential difference across the two terminals of the cell in closed circuit (i.e. when current is passing through it). Then again applying Ohm's law we get,

$$V = \frac{R}{i} \quad \text{--- (2)}$$

From equations (i) and (ii) we get,

$$r = \frac{E - V}{V - R} \quad \dots \quad (iii)$$

Now let l_1 be the balancing length of the potentiometer wire when the e.m.f. E of the Leclanche cell is balanced on it (i.e. when the cell is in the open circuit and K_2 is open). Then we have,

$$E = l_1 r \quad \dots \quad (iv)$$

where r is the potential gradient along the potentiometer wire. Let l_2 be the balancing length of the wire when the potential difference V across the plates of the cell is balanced on it (i.e. when K_2 is pressed and the cell is short circuited). Then we have,

$$V = l_2 r \quad \dots \quad (v)$$

Substituting the values of E and V from eqns. (iv) and (v) in eqn. (iii) we get,

$$r = \left(\frac{l_1}{l_2} - 1 \right) R$$

knowing l_1 , l_2 and R , r can be calculated.

Method:—1. Make neat and tight connections as shown in Fig. 1. Connect the end A of the potentiometer wire to the +ve terminal of the accumulator B_1 , and the end B to the -ve terminal of the accumulator through the rheostat R_1 and key K_1 . Verify the potential of A is higher than that of B . It constitutes the primary circuit.

2. Connect the +ve pole of the Leclanche cell C to the end A , and its -ve pole to the jockey J through a galvanometer G . Put a shunt across the galvanometer.

3. Connect a resistance box R_2 across the two poles of the cell C through a plug key K_2 .

4. Keeping K_2 open, close the key K_1 , and test for the correctness of the connections. Move the jockey J to one end of the potentiometer wire and press N ote the direction of deflection in the galvanometer. Now move J to the other extreme end of the wire and press. Again note the direction of deflection in the galvanometer. If this deflection is opposite to the previous one, the connections are correct. If not so, either the connections are wrong, or the potential difference across the ends A and B is less than the e.m.f. of the cell. To increase p.d. across AB reduce the resistance to the rheostat R_1 , so that the deflection becomes two sided.

To determine l_1 :—

5. After testing for the correctness of the connections determine the balancing length of the potentiometer wire

corresponding to the e. m. f. E of the Leclanche cell (i. e. when it is in open circuit). It can be done by adjusting jockey J for no deflection in the galvanometer. The resistance R_1 in the rheostat should be so adjusted that this balance point is obtained nearly on the last wire. The final adjustment must be done by removing the shunt wire. It gives l_1 .

To determine l_2 :

6. Keeping the resistance in the rheostat R_1 constant, close the key K_2 , and introduce some resistance, say, 5 ohms in the resistance box. Now the cell is in the closed circuit. In this position, again determine the balancing length of potentiometer wire corresponding to the lowered p. d. (V) across the two plates of the cell C. Shunt should be removed while making final adjustment. It gives l_2 .

7. Repeat the above procedure, and determine l_1 and l_2 by increasing the resistance R in R. B. in steps of 1 to 2 ohms. In this way take four to five observations. See that for one set of l_1 and l_2 , R_1 remains same.

8. Now change the resistance in R_1 , and repeat the above procedure to get a new set of readings for l_1 and l_2 .

9. Knowing l_1 , l_2 and R , calculate r by each set.

Observations:—

S. N.	Balancing length of the wire When the cell is in closed circuit (l_2) (in cm.)	Resistance in R. B. (in ohm)	Internal resistance $r = \left[\frac{l_2}{l_1} - 1 \right] R$ (in ohm.)
1			
2			
3			
4			
5			
6			
7			
8			
9			
10			

Calculations:—Calculate the value of r by each set, by the formula,

$$r = \left[\frac{l_2}{l_1} - 1 \right] R$$

1. The accumulator should be fully charged, and must be of large capacity, so that the current in the primary circuit may remain constant. It must be the potential gradient will not remain constant.

2. The shunt R_s should be so adjusted that the balance point in the open circuit is obtained on the last wire of the potentiometer. It may be R_s and hence the sensitivity of the instrument.

3. The terminal of the Leclanche cell should be connected to the +ve end of the potentiometer wire.

4. The resistance in it should never be changed in the same set while taking observations for E_1 and E_2 .

5. While obtaining approximate balance point the galvanometer should always be shunted.

Criticism:—The internal resistance of the cell changes according to the current drawn from it. More is the current drawn greater will be the value of the internal resistance. It is due to the increasing polarization of the primary cell. However, the e.m.f. of the cell is determined when it is in open circuit. Therefore, this method is far more superior to that of voltmeter-ammeter method of determining internal resistance. The method is not suitable for measuring the internal resistance of an accumulator, because to obtain appreciable fall in p.d., very large currents should have to be drawn, which may spoil the plates of the same.

Oral questions:—

1. See exp. Nos. 17, 18, 19. 2. What do you understand by the internal resistance of a cell? 3. Does it remain constant if not, why? 4. How can you measure it with the help of a potentiometer? 5. Is this method superior to that of voltmeter-ammeter method of measuring internal resistance? 6. Can you measure the internal resistance of an accumulator by this method? 7. Why should the accumulator used be of fairly large capacity and constant e.m.f.? 8. What order of resistances be introduced in the cell circuit while short circuiting it? 9. Why the readings for E_1 should be checked occasionally? 10. Why the current should be kept constant while taking one set of readings for E_1 and E_2 ?

EXPERIMENT No. 29

Experiment:—To determine the internal resistance of an accumulator with the help of an ammeter and a milli-voltmeter.

Apparatus:—Two similar accumulators of exactly or nearly the same e.m.f., an ammeter (nearly of 1 amp. range), a milli-voltmeter (100 milli-volt range), a rheostat, plug key, tapping key, connecting wires etc

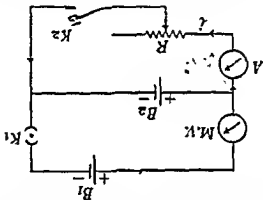


FIG. 1

Theory:—The connections are self explanatory. If B_1 and B_2 are of exactly the same e.m.f., the reading in the milli-voltmeter will be zero. However, even if there is a slight difference in the e.m.f. of the two cells, the milli-voltmeter will give some reading. Now if K_2 is pressed, current will flow through the cell B_2 and the resistance R . Consequently, the potential difference across the two plates of the cell B_2 will fall. No current will flow through the cell B_1 , because milli-voltmeter resistance is high (remains). Let this drop in potential difference be V , which will be registered by the milli-voltmeter. Let the internal resistance of the cell B_2 be r and the current flowing through it be i . Then applying Ohm's law to the lower circuit, we get,

$$r = \frac{V}{i}$$

Knowing V and i , r can be calculated.

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
[illegible][illegible]

1. The first part of the document is a letter from the President of the United States to the Congress, dated January 1, 1861. It is a formal communication, and it is written in a very dignified and official style. The President expresses his regret that he cannot deliver a message in person, and he explains the reasons for this. He then proceeds to discuss the state of the Union, and he mentions the recent events of the year. He also talks about the future of the country, and he expresses his confidence in the people. The letter is very long, and it covers a wide range of topics. It is a very important document, and it is one of the most famous speeches in American history.

[illegible]

3 Determine the difference between the two readings of the millivoltmeter, which will give the drop in potential difference $V = V - X = V$.

6. Knowing V and R , calculate r .

1. Identify the problem

Observation: _____

1. Least count of milli voltmeter = mV

2. Least count of ammeter = amp,

S. No.	Reading in the milli-voltmeter in milli volts		Drop in potential V	Current i in amp.	Internal resistance $r = \frac{V}{i}$ ohm
	when K_1 is open, K_2 is pressed	when K_1 is closed, K_2 is pressed			
1					
2					
...					
...					
6					
7					

Calculations:—Calculate r by each set and then determine the mean value of r .

Result:—The internal resistance of the accumulator $(r) = \dots \dots \dots$ ohm.

Precautions and sources of error:—

1. As far as possible the two accumulators must be of the same e.m.f. If there is a difference between their e.m.f.s, it should in no case exceed a few milli-volts, otherwise it would not be possible to take readings in the milli-voltmeter.
2. As the drop in potential V is very small, only a milli-voltmeter should be employed to measure it.
3. The two cells should be fully charged, otherwise the initial reading of the milli-voltmeter will not remain constant.
4. The +ve terminal of the cell possessing higher e.m.f. should be connected to the +ve terminal of the milli voltmeter.

Criticisms of the method:—

It is a fairly good method, because milli-voltmeter is employed.

Oral Questions:—

1. What is an accumulator, and how does it differ from a primary cell?
2. Describe the two types of accumulators, which is better and in what circumstances?
3. What is internal resistance of an accumulator, and how is it determined?
4. Can you find it by ordinary voltmeter, ammeter method or potentiometer method, if not, why?
5. Why the two accumulators should possess nearly the same e.m.f. if not so, what will be the harm?
6. Why the comparison cell should possess higher e.m.f., if not equal?
7. Can you use a ordinary voltmeter?

EXPERIMENT No. 30

Experiment:—To study the variation of magnetic field with distance, along the axis of a circular coil carrying current graphically, and hence to determine the radius of the coil with the help of the graph.

Apparatus:—Stewart and Gess type of tangent galvanometer, accumulator possessing a fairly large capacity, rheostat, commutator, connecting wires etc.

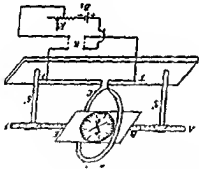


Fig. 1

Description of the apparatus:—This type of tangent galvanometer consists of a circular coil CC having a number of turns of copper wire fixed on a horizontal wooden bench. The coil is fixed in the vertical plane. A magnetic compass box with meter scales AB and EF attached to its either side is mounted at its centre. The scales rest and can slide on the two vertical supports $S'S'$ fixed on the wooden bench. The magnetometer compass box can slide on either side of the coil, such that the centre of the magnetic needle NS always remains on the axis of the coil. The distance between the centre of the needle and the coil can be determined with the help of meter scales AB and EF .

Theory:—The magnetic field F , due to a circular coil carrying current at any point P situated on its axis, at a distance



Where i is the current flowing through the coil, n the number of turns in it, and r its radius.

If the coil is placed in the magnetic meridian, F will act at right angles to the earth's horizontal field H . Consequently, under the influence of these two perpendicular fields, the magnetometer needle will be deflected. Let θ be the deflection of the needle from the direction of H . Then, applying tangent law we get,

$$F = H \tan \theta \quad \dots \quad (ii)$$

From (i) and (ii) we get

$$F = \frac{2\pi n^2 i}{r^3 + x^3} a = H \tan \theta \quad \dots \quad (iii)$$

Thus, to study the variation of magnetic field with distance, a graph may be plotted between x and $\tan \theta$ taking distances as abscissa and corresponding values of $\tan \theta$ as ordinates.

The curve will be as shown in Fig. 3. At $x = 0$ the curve is concave towards the origin O . The curvature goes on decreasing with x increasing, and for a certain value of x the curve changes sign, i. e. it becomes convex towards O (e. g. at R and T in Fig. 3). These points are known as points of inflection. At these points the rate of change of field is constant.

$$\frac{dF}{dx} = 0 \quad \dots \quad (iv)$$

Differentiating equation (iii) twice and comparing it with equation (iv), we get,

$$x = \frac{1}{2} r \quad \dots \quad (v)$$

Thus, the distance between the two points of inflection R and T situated on either side of the curve will be equal to the radius of the coil.

Method—1. By sliding the compass box over the magnetic needle at the centre of the coil C , and level the compass box with the help of a spirit level.

EXPERIMENT No. 30

Experiment:—To study the variation of magnetic field with distance, along the axis of a circular coil carrying current graphically, and hence to determine the radius of the coil with the help of the graph.

Apparatus:—Stewart and Gess type of tangent galvanometer, accumulator possessing a fairly large capacity, rheostat, commutator, connecting wires etc.

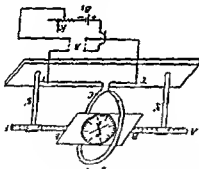


Fig. 1

Description of the apparatus:—This type of tangent galvanometer consists of a circular coil C having a number of turns of copper wire fixed on a horizontal wooden bench. The coil is fixed in the vertical plane. A magnetic compass box with meter scales AB and EF attached to its either side is mounted at its centre. The scales rest and can slide on the two vertical supports S'S' fixed on the wooden bench. The magnetometer compass box can slide on either side of the coil, such that the centre of the magnetic needle NS always remains on the axis of the coil. The distance between the centre of the needle and the coil can be determined with the help of meter scales AB and EF.

Theory:—The magnetic field H , due to a circular coil carrying current at any point P situated on its axis, at a distance



Fig. 2

11. Find out the two points of inflection on the graph and determine the distance between their X-Co-ordinates. It will give the value of the radius of the coil.

Observations :-

Observations :												
S. N.	Distance of the needle from the centre of the coil (z)	Compass box on left hand side						Compass box on the right hand side.				
		Deflection						Deflection				
		Direct		Reverse		Mean θ	Direct		Reverse		Mean θ	
		one end	another end	one end	another end		one end	another end				
		Tan θ						Tan θ				
1												
2												
3												
4												
5												
6												
7												
8												
9												
10												
11												
12												
13												

2. Now let the coil in the magnetic meridian, i.e. the plane of the coil be at right angles to the magnetic field. With the help of the theodolite, as is to obtain a deflection of about 45° in the compass box at the centre of the coil. If so much deflection is not produced by one deflection, make use of more number of coils. Reverse the current in the coil by commutator, and see whether the deflection is the same. If it varies by more than 2° , slightly rotate the coil in order to obtain the same deflection. When the deflection is equal to that of the coil, it is set in the magnetic meridian.

3. After setting the coil in the magnetic meridian, read with the ends of the pointer. Reverse the current and again read with the ends of its end. Mean of these for readings will give the deflection of the needle at this point.

7. In this way go on moving the compass box in step 2 cm. till the deflection is reduced to nearly 15° . At each step take four readings of the pointer and then determine the mean deflection of the needle at the centre of the coil.

6. Keeping the current in the coil constant, (i.e. on the same point), move the compass box either towards the right or the left by a distance of, say, 2 cm. The distance from the centre can be measured with the help of the scales attached to the box. Read both the ends of the pointer, reverse the current and again read both of its ends. Mean of these for readings will give the deflection of the needle at this point.

8. Repeat the same procedure on the other side of the coil, by taking readings of the deflection after every 2 cm. So, in this way the values of θ corresponding to various distances are obtained on both the sides of the coil.

9. Near about the points of inflection, the deflection of the needle should be obtained after every cm. because the curve becomes almost vertical.

10. Knowing deflections at various distances, plot a graph between the distances of the needle from the centre of the coil (i.e. x) and the corresponding tangents of deflection (i.e. $\tan \theta$). If x is taken +ve on the right hand side of the coil and -ve on the left hand side of the coil, the curve will be symmetrical on either side of the centre of the coil.

EXPERIMENT No. 31

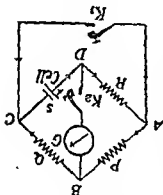
Experiment:—To determine the internal resistance of a cell by Mance's method either using a meter bridge or a post office box.

Apparatus:—A meter bridge or a post office box, a sensitive galvanometer, a high resistance like water resistance, resistance box in case of meter bridge, plug keys, given primary cell either a Leclanche cell or a Daniell cell.

Description of the apparatus:—You are quite familiar with a meter bridge and a Post Office Box.

Theory:—The theory is the same as that of the Wheat

stone net except that the fourth arm is replaced by the cell and in the cell conjugate arm a key K_1 is introduced. Even when the cell key K_1 is not pressed, current is flowing through the galvanometer, and it gives deflection when K_1 is pressed. Now this current i is independent of the resistance in the arm AC only when the Wheat-stone condition is satisfied. That is, by pressing the key K_1 , or keeping it open the value of current flowing through the galvanometer remains unaffected, if



$$\begin{aligned} P/Q &= R/S & \dots & (i) \\ S &= \frac{P}{Q} \cdot R & \dots & (ii) \end{aligned}$$

Where P, Q, R, S are the resistances in the four arms respectively, S being the internal resistance of the cell.

In case of a meter bridge Q, P is known in terms of the length of the bridge wire L and $L' = 100 - L$; where L and L' are the lengths corresponding to R and S in place of P and Q .

$$\text{Hence, } S = R \frac{L'}{L}$$

$$\dots \dots (iii)$$

Calculations:—Find out the radius of the coil by getting the distance between the X-co-ordinates of the two points of inflection.
Result:—The radius of the coil, = ... cm.
Precautions and sources of error:—1. The plane of the coil should lie in the magnetic meridian otherwise the tangent law will not apply.

2. As the current should remain constant throughout the experiment an accumulator of large capacity should be employed. Moreover, after taking four or five observations, the compass box should be brought at the centre of the coil, and it should be ensured that the current flowing is the same. If not so, adjust it with the help of the rheostat.

3. To remove the error caused by the eccentricity of the pivot both the ends of the pointer should be read.
 4. No magnetic materials or current carrying conductors should be placed in the vicinity of the coil. Even the rheostat R should be kept sufficiently far away from the coil.
 5. The deflection of the needle should be taken for both direct and reversed currents, so that even if there is any want of non-coincidence of the coil with the magnetic meridian the error will be eliminated.
 6. The pivot of the needle should be as far as possible frictionless.

7. The curve drawn should be smooth and the two points of inflection should be carefully found out.
Criticisms:—The results obtained in this method are not very accurate due to the following reasons:—

- (i) The coil may not lie exactly in the magnetic meridian,
- (ii) It may not be perfectly circular,
- (iii) It is not infinitely small, and its centre may not lie exactly on the axis of the circular coil.
- (iv) The friction at the pivot is not negligibly small. Further, it is not very easy to accurately locate the position of the points of inflection on the curve.

Oral Questions:—1. See expt. No. 16 (Questions on deflection magnetometer). 2. What is the direction of the magnetic field at the centre of the coil? 3. How does this magnetic field vary along the axis of the coil? 4. Where is it maximum? 5. In which units is the current expressed in this formula? 6. What is the practical unit of measuring current? 7. What are points of inflection? 8. How can you find out the radius of the coil by knowing the points of inflection? 9. What type of curve between x and $\tan \theta$ you get

this point by moving the jockey slightly to left and right and note change in deflection. (on pressing key K_1)

If the bridge is not very sensitive, you will find that there is a range of wire over which the balance point occurs. In such a case note the range and middle point of this range would be the balance point.

Also please note that when the variable contact is made at various points, the galvanometer deflection does not remain constant and as such on pressing the key K_1 , the change in direction should be carefully noted.

4. Note the balance point. Measure the length AB i.e. l corresponding to the resistance P and $100-l$ corresponding to Q .

5. To eliminate the end correction.—To do it, the position of the cell and the unknown resistance should be interchanged. Proper precaution must be taken to see that the pressure of tightness of connections, length of connecting wires etc., should as far as possible remain unaffected.

As explained above, again obtain the balance point. Now let the length AB be l' . Then this l' corresponds to $100-l$ and $100-l'$ corresponds to l . Take mean of l and $100-l$ and call it L . Then L and $L'=100-l$ respectively correspond to P and Q .

6 Using the formula given in theory, find out the internal resistance of the cell.

7. Now from the resistance box R , take out the resistance corresponding to this resistance and repeat the above procedure. You will now get balance point approximately in the middle of the wire.

8. Repeat the above procedure by slightly changing the resistance a little more or less than the above value (Every time do not forget to interchange the cell with resistance R)

9. Calculate r , by each observation, and then determine its mean value.

NOTE—If galvanometer is connected in place of X balance point can be obtained by simply pressing the jockey. Only a wire is connected between BD.

Observations—1. The deflection of the galvanometer is at division.

2. When the jockey is pressed at extreme left end the deflection increases decreases.

3. When it is pressed at extreme right end, the deflection increases decreases.

Therefore, connections are correct.

In P. C. Box (C) is known from the ratio arm. R is known reference which need adjustment for balance point.

Method. - 1 (i) By meter held in terminals B and D. as shown in Fig. 2 A high adjustable resistance (preferably water resistance not shown in figure) should be connected in series with galvanometer in between the terminals B and D.

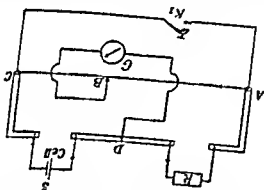


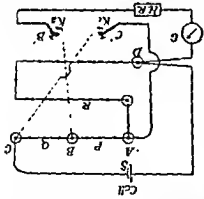
Fig. 2

Failure in doing it might lead to the damage of the galvanometer due to excessive flow of current. If you are using a Weston type of moving coil galvanometer, adjust the resistance till you get more than half scale deflection. From the resistance box R remove the plug corresponding to resistance 1 or 2 ohm. It is better to use key K_1 as contact key and not as plug key.

2. To Test whether the connections are correct—On making connections there would be deflection in the galvanometer. Adjust the variable resistance so that the deflection is not excessive. Now press the contact key K_1 . Keeping the position of the variable key to the extreme left, note the change in direction of deflection. Now take the jockey to the extreme right and repeat the above procedure, if you find that the change in deflection is to the opposite side, the connections are correct.

3. To find the balance point—In order to find the balance point, i.e., the point on the wire AC, where when contact is made with the jockey, no change in deflection in the galvanometer should occur, repeat the above procedure at various places. At one particular point, say B you will find that on pressing the jockey, the galvanometer deflection remains unaffected. Confirm

Result:—The internal resistance of the cell = ... ohm.
 (ii) By Post Office Box:—1. Make connections as shown



Finally the cell is put between these two terminals. Thus, now P, Q are the ratio arms, R is the known resistance, and S is the unknown cell resistance. Adjust the high variable resistance in series with the galvanometer so that it is a Weston moving coil galvanometer, obtain more than half the scale deflection, when the key K_1 is pressed.

2. To test whether connections are correct:—Take out 10 ohm plug each from P and Q arms. When $R = \infty$, press key K_1 , and galvanometer will give deflection. Note the direction of this deflection, and press K_2 . Now note the change in the direction of deflection in the above procedure. If you find, that the change in direction of deflection is opposite, connections are correct.
3. Keeping the ratio $P : Q$ as 10 : 10 vary the resistance R from zero in steps of 1 ohm till by pressing the key K_1 , the constant deflection in the galvanometer changes its direction. Then the resistance of the cell lies between these two resistances i.e., if for $R = 1$ ohm, deflection in the galvanometer changes its direction towards left, and for $R = 2$ ohm towards right, then the resistance of the cell lies between 1 and 2 ohm.
4. Now make the ratio $P : Q$ as 100 : 10, and determine the same limit of the resistances between which the deflection changes its direction. It gives the resistance of the cell correct upto 1/10th of an ohm.
5. Ultimately make the ratio $P : Q$ as 1000 : 10, and adjust the resistance in R in such a way that the deflection of the key K_1 does not change the deflection of the galvanometer. It

4 Known resistance is in the left gap.

S. N.	1.	2.	3.	4.
Known Resistance in ohm.				
Range of Balance point from..... to..... cm.				
Balance point				
Length corresponding to known resistance i.e. 100-l (cm.)				
Length corresponding to unknown resistance i.e. 100-l (cm.)				

5. Known resistance in right gap.

S. N.	1.	2.	3.	4.
Known Resistance in ohm.				
Range of Balance point from..... to..... cm.				
Balance point				
Length corresponding to unknown resistance i.e. l' cm. (Q)				
Length corresponding to known resistance i.e. 100-l' cm. (P)				

Calculations:—

S. N.	1.	2.	3.	4.
Known Resistance R				
Mean of l and 100-l' i.e. L cm. (P)				
Mean of l' and 100-l i.e. L' cm.				
$S = R \frac{L}{L'}$ ohm.				

Internal resistance of the cell $S = R \frac{P}{Q}$

$$= R \frac{L}{L'}$$

= ... ohm.



Precautions and Sources of error—1. The resistance of the cell is usually not very high. The connecting leads used for connections must therefore be thick and short.

2. It is always better to use the key K_1 in the galvanometer circuit. Though a separate key in series with the cell is not advised, it is better to use it. Still better would be to remove the zinc rod of the cell and put it inside only when we are in a position to start the work. This however disturbs the cell and changes its internal resistance. Therefore see, that the zinc rod used is well amalgamated and then keep it inside the cell and use a key in series.

3. When there is want of balance, the change in galvanometer deflection will depend on the strength of current which flows between A and C. This again will depend on the resistance in the arm AC—smaller it is better it will be. Therefore, see that the contact key between A and C is connected through thick copper wire.

4. In the case of meter bridge, the balance point should be nearly in the middle. For this the known resistance must be approximately equal to the unknown resistance. This ensures maximum sensitivity.

5. Interchange of positions of known and unknown resistances is necessary in the case of meter bridge, because that eliminates end corrections.

6. If the deflection (initial) in the galvanometer is very large, small changes in deflection on pressing the key may not be detected. So a large current must flow through the circuit but the current flowing in the galvanometer should not be very large. A convenient deflection would be half the scale deflection.

7. When the ratio arms are changed, the magnitude of galvanometer deflection also changes. This should be carefully noted before pressing the contact key K_1 .

8. When the jockey key is moved along the wire see that it is not kept pressed. Also the pressure which we apply to the key should be gentle. This helps in keeping the uniformity of the wire.

9. Remember that the internal resistance of a cell depends on the strength of current drawn. Also it changes due to some changes at the plates.

10. In this experiment it is important to see that the galvanometer key K_1 is pressed first before the cell key K_2 .

Criticism—This method is not very accurate, because the internal resistance of the cell changes, as the current drawn from it. Furthermore, the polarisation taking place is changing pd. across the plates of the cell, consequently, the steady deflection

gives the balance point, and the resistance of the cell can be obtained correct to 1/100th of an ohm.

6. Now put the galvanometer in the arm AC, and simply a key in the arm BD i.e. their positions have been interchanged. Again repeat the above procedure, to get the internal resistance. The interchange is necessary to know as to when the bridge is more sensitive.

NOTE—If a moving coil suspended type of galvanometer is used, use lamp and scale arrangement. First level the galvanometer, and put it in series with a variable high resistance so that a very small amount of current flows through it. Now unclamp its coil, and throw light on the mirror to get a bright spot of reflected light on the scale. When the current is passed through the galvanometer, the coil gets deflected. Thus, the spot also gets deflected. Hence in this case the spot of light moves over the scale, and therefore the direction of deflection of the spot should be noted. Rest of the procedure is the same as described above in the method. This type of galvanometer is more sensitive than that of the pivoted type.

Observations:—

N.	Ratio arms		Known Resistance in ohm.	Change in direction of deflection in the galvanometer	Inference	Unknown resistance of the cell $S = R \frac{Q}{P}$ in	Ratio arms	Q in ohm.	P in ohm.	Known Resistance in ohm.	Change in direction of deflection in the galvanometer	Inference	Unknown resistance of the cell $S = R \frac{Q}{P}$ in
	10	10	2	Left Right	Connections are correct	lies 0	10	10	1	2	Left Right	Less More	lies 1 am.
	10	100	16	17	Left Right	Less More	lies 1.6						
	10	1000	165	No change	Equal	5=1							

Result—The unknown resistance of the cell = ohm.

EXPERIMENT NO. 32

Experiment:—To determine the internal resistance of galvanometer by Kelvin's method using a P. O. Box.

Apparatus:—A Post Office Box, the given galvanometer whose resistance is to be determined, a variable high resistance (preferably a water resistance), a Leclanche cell, connecting wires etc.

Description of the apparatus:—You are quite familiar with a P. O. Box.

Theory:—The theory of this experiment is also the same

as that of the Wheatstone net, except that in the fourth unknown resistance arm galvanometer is put as shown in fig 1. In the galvanometer conjugate arm, a tapping key K_1 is introduced. When the cell key K_2 is pressed, current flows in the galvanometer and it gives deflection. Now this current is independent of the resistance in the arm BD only when the Wheatstone condition is satisfied. That is, by pressing the key K_1 or keeping it open, the value of the current flowing through the galvanometer should remain unaffected, if

$$\begin{aligned} \text{P/O} = R/S & \quad \dots \quad (i) \\ \text{or } S = \frac{P}{Q} R & \quad \dots \quad (ii) \end{aligned}$$

where P, Q, R, S are the resistances in the four arms respectively, S being the resistance of the galvanometer,

In P. O. box P/Q is known from the ratio arms, and R is known resistance in the AD arm, which is adjusted to get the balance point. Knowing P, Q and R, S can be calculated.

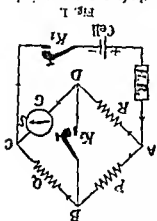


Fig. 1.

of the galvanometer does not remain constant, hence null point cannot be obtained very accurately. In this experiment the galvanometer generally becomes insensitive when the ratio $P:Q$ is made 1000:10, and therefore internal resistance cannot be determined accurately. Potentiometer method of determining internal resistance is superior to this method.

Oral Questions:—1. What is a Wheatstone net? 2. Give the construction of a P. O. Box, and show how it supplies the Wheatstone's net? 3. How are the resistances arranged in a P. O. Box? 4. Show how these resistance coils are made? 5. Why the wires are doubled and then wound? 6. What do you understand by the internal resistance of a cell? Does it remain constant? If not why? 7. How do you determine the internal resistance of a cell by a P. O. Box? 8. Why the cell arm AC is short circuited by a thick copper wire? 9. Which key should be pressed first in this experiment and why? 10. Is this an accurate method of determining internal resistance? If not why? 11. Can you suggest any better method? 12. What are the conjugate errors in this method? 13. Are the points B and D at the same potential when the balance point is obtained? 14. What are the factors upon which depend the internal resistance of a cell? 15. Is it necessary to use a key in series with the cell? 16. Can you determine the internal resistance of an accumulator by this method?

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$$\frac{P}{Q} = \frac{R}{S} \quad \text{or} \quad S = \frac{P}{Q} \cdot R \quad \text{--- (i)}$$

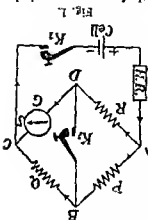
$$\text{--- (ii)} \quad \text{--- (iii)}$$


Fig. 1.

where P, Q, R, S are the resistances in the four arms respectively, S being the resistance of the galvanometer.

In P. O. box P/Q is known from the ratio arms, and R is known resistance in the AD arm, which is adjusted to get the balance point. Knowing P, Q and R, S can be calculated.

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Oral Questions:—1. See Experiment No. 31. 2. What do you understand by the resistance of a galvanometer. How is it determined by this method? 3. What are the four arms of the Wheatstone's net in this experimental arrangement? 4. Why the arm BD is short circuited by a thick copper wire? 5. Why a high variable resistance is connected in series with the cell? 6. Which key should be pressed first in this experiment and why? 7. Are the points B and D of the bridge at the same potential when the balance point is obtained? 8. Do you know any other method of determining resistance of a galvanometer? 9. Which gives better results, this or the method just mentioned? 10. What are the conjugate arms in this arrangement? 11. When is the bridge most sensitive?

NOTE : Quite a number of times particularly using the ratio $Q/P = \frac{100}{1}$, the bridge becomes insensitive, and then for a number of resistances you get balance point. In such cases find out the range in which the balance point is obtained. Then the mean reading will give the correct resistance.

Calculations:— $S = Q/P \times R = \dots$ ohm.

Result:—The resistance of the galvanometer = \dots ohm.

Precautions and sources of error.—1. See experiment

2. All the connections should be tight and no pin P, O, box should be left loose.

3. An accumulator should not be used in this experiment because constant current is not required. Furthermore, heat the wires altering their resistances.

4. The battery key K₁ should be pressed first there after the galvanometer key K₂ should be pressed.

5. The terminals B and D should be short circuited a thick copper wire of only necessary length so that it may negligible resistance. Because when there is lack of balance in galvanometer deflection will depend upon the change in the arm BD. This will further depend upon resistance of the arm BD. Smaller it is, better would be adjustment.

6. It is essential to connect a high resistance in series the cell. If it is not done so, heavy currents will pass through the galvanometer. This may damage it. Or potential divider be used.

7. If possible a P. O. box dial pattern should be preferred because in it, uncertain contact resistances will be considered.

8. In order that the bridge may be most sensitive resistances in all the four arms of the bridge should be in of the same order.

9. If a suspended coil type of galvanometer is taken should be properly levelled so that the coil moves freely between the two pole pieces of the magnet.

Criticism—This method yields quite satisfactory results if the experiment is performed carefully. When the ratio P/Q is made as 1000:10, the resistances in the four arms of the bridge differ too much from each other consequently the bridge will become insensitive.

Thus, as the resistance R_1 is very large, the current in the circuit almost remains unaffected by putting a resistance R in parallel to G . Let R be the value of the resistance put across G , so that the deflection in the latter is reduced to half of its previous value. Evidently therefore, half of the current flows through G and half of it through R . As they are in parallel,

$$G = R \quad \dots \quad (vi)$$

Method:—1. Make neat and tight connections as shown in the figure. Put the given galvanometer G in series with an accumulator through a high resistance R_1 and the key K_1 . Put a resistance box R across the two terminals of the galvanometer through a key K_2 .

2. Close K_1 and adjust R_1 , so that a convenient deflection is obtained in the galvanometer (it should be more than half of the scale divisions provided in the instrument). R_1 should be taken of the order of 10,000 ohm. Let the deflection be n divisions.

3. Close K_2 and adjust the value of R , so that the deflection in the galvanometer is reduced to half of its previous value i. e. it becomes $= n/2$ divisions. It gives the resistance of the galvanometer.

4. Change the value of R_1 and take a number of sets.

5. Determine G from each set, and then find out its mean.

Observation:—

S. N.	Deflection in the galvanometer in the beginning when K_2 is open in divisions	Resistance required for half of the previous deflection R in ohm.
1.		
2.		
3.		
4.		
5.		

Figure 1 shows the circuit for the measurement of a galvanometer's deflection in the galvanometer. The given galvanometer is represented by a circle with a cross inside. It is connected in series with a variable resistor R_1 and a battery E . The deflection is measured by a scale and a pointer. The circuit is shown in Figure 1.

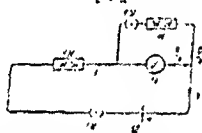


Fig. 1

For a convenient deflection in the galvanometer, let the current flow through it and the high resistance R_1 then, we have,

$$i = \frac{E}{G + R_1} \quad \dots \quad (i)$$

where E is the e. m. f. of the accumulator, G the resistance of the given galvanometer and R_1 the value of the high resistance put in series with the galvanometer. If $R_1 \gg G$, equation (i) becomes,

$$i = \frac{E}{R_1} \quad \dots \quad (ii)$$

Let the new current in the circuit be i_1 . When a resistance is put in parallel to the galvanometer, then,

$$i_1 = \frac{E}{\frac{GR}{G+R} + R_1} \quad \dots \quad (iii)$$

Again if $R_1 \gg G$ and R

$$i_1 = \frac{E}{R_1} \quad \dots \quad (iv)$$

$$i = i_1 \quad \dots \quad (v)$$

EXPERIMENT NO. 34

Experiment:—To determine the thermo-E.M.F. of a copper-iron couple; and then to draw a graph between the thermo-E.M.F. generated and the temperature of the hot junction, keeping the temperature of the cold junction constant.

Apparatus:—A potentiometer, an accumulator, a standard cell (cadmium cell is preferable, if it is not available, freshly prepared Daniell cell should be used), two resistance boxes of the range of 0-10,000 ohms, a rheostat, a Weston type galvanometer, a shunt wire, a plug key, a three way key, copper iron thermocouple, beakers, a test tube containing mercury, sand bath, thermometer, burner, connecting wires etc.

Description of the apparatus:—A copper iron thermocouple consists of an iron wire, each end of which is connected to a copper wire. The free ends of the copper wires are connected to a circuit containing a galvanometer. One junction of the couple is immersed in a cold bath made by taking cold water or ice in a beaker, while the other end is put in a hot bath prepared by taking mercury in a test tube heated on a sand bath. When temperature difference is set up between the two junctions, current begins to flow from copper to iron at the hot junction, and the galvanometer gives deflection. The current generated is known as thermo-electric current.

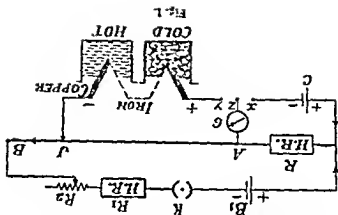


Fig. 1



That (2) is true - See question on electricity? 2.5
approximate 11 and 12. 3 is a good method of determining
it. What is called half detection method? 3. How
is it determined that the current remains the same, even after
connected a resistance in parallel to the galvanometer? 6. Why
a half resistance should be connected in series with the galvan-
ometer? 7. Can you use a primary cell instead of an accumulator?

Calibration. This is the method in use with accuracy, it
is not a satisfactory method. It is very convenient, and can
be carried out in a comparatively lower time.

The detection method in the first method should
be used in the case of the second, because more
is the accuracy, and the error will be the same in reading it.

2. The detection method is not a very accurate method.

3. The detection method is not a very accurate method.
4. The detection method is not a very accurate method.
5. The detection method is not a very accurate method.
6. The detection method is not a very accurate method.

$$E = IR$$

Electromotive

2. Connect a high resistance R in series with the potentiometer wire AB . It should be near about 1000 ohms depending upon the resistance of the potentiometer wire. Put this combination in series with an accumulator B , a high resistance R_1 (of the same order as that of R) and a rheostat R_2 through a plug key K . The current in the potentiometer wire should enter from the terminal A , as shown in Fig. 1 so that A becomes the +ve terminal of the wire.

3. Join the +ve pole of a standard cell (or a freshly prepared Daniell cell) to the higher potential terminal of the resistance box R_1 and the -ve pole to the terminal x of a three way key. Connect the terminal z of the key to the end A of the potentiometer wire through a galvanometer G . Join the free end of the copper wire of the cold junction to the third terminal y of the key, and free end of the copper wire of the hot junction to the jockey J .

4. Close K , and join x to z (by putting the plug between x and z). Introduce a resistance of nearly 1000 ohms in (R_1, B) R_1 and nearly an equal resistance in R_2 . Now by adjusting R_1 and R_2 , balance the e.m.f. of the cell against the p.d. existing between the two terminals of R . It can be done by obtaining no deflection in the galvanometer. While making final adjustment remove the shunt from the galvanometer. (Now the p.d. across $R =$ the e.m.f. E of the cell).

5. Disconnect x from z and switch off the current in the potentiometer circuit, by taking out the plug in key K .

Put the cold junction in ice. If ice is not available put it in a beaker containing cold water. Note down its temperature by a thermometer reading up to $1/5^\circ\text{C}$. It gives t_1 , the temperature of the cold junction. Now put the hot junction in mercury contained in a copper test tube. Put the latter in a sand bath heated by a burner. Again determine the temperature of the hot junction by a thermometer reading up to $1/5^\circ\text{C}$. It gives t_2 . If sand bath is not available, take glycerine or some such oil (possessing high boiling point) in a beaker, and put the hot junction in it. Heat the oil, stir it well, and determine its temperature by a thermometer put in it.

Theory—The connections are self explanatory. For a temperature difference of 100°C between the two junctions the thermo-e. m. f. generated is of the order of 0.0013 volt i. e. 1.3 millivolt. It is fairly small and to measure such small potential differences, the potential gradient along the potentiometer wire should be of the order of a micro-volt. To obtain such a low potential gradient, a high resistance R (of the order of $1000\ \text{ohm}$) is connected in series with the potentiometer wire AB . This combination is then put in series with an accumulator B_1 , a high resistance R_1 , and a rheostat R_2 . Now a standard cell or a Daniell cell is balanced across the two terminals of the resistance R by adjusting R_1 and R_2 . Let i be the current flowing through the potentiometer circuit (i. e. through R and AB), then we have,

$$E = iR \quad \dots \quad (i)$$

Now keeping i constant, the thermo-e. m. f. e generated in the couple is balanced across the potentiometer wire. Let its balancing length be l , and r be the resistance of the length l of the wire. Let r be the resistance of the wire per unit length. Then, applying Ohm's law we get,

$$e = ir = l \cdot r \cdot i \quad \dots \quad (ii)$$

\therefore From eqns. (i) and (ii) we get,

$$e = \frac{R}{l} r \quad \dots \quad (iii)$$

Let R_1 and L be respectively the resistance and total length AB of the potentiometer wire, then

$$r = \frac{L}{R_1} \quad \dots \quad (iv)$$

$$\text{or} \quad e = \frac{R}{L} \cdot \frac{L}{R_1} \cdot l \quad \dots \quad (v)$$

Knowing all the symbols in equation (v) e can be calculated. Knowing e at various temperatures, a graph is drawn between the thermo-e. m. f. generated and the difference of temperature between the two junctions. From the graph neutral point i. e. the temperature at which e is maximum is determined.

Method—1. To start with, connect the potentiometer wire AB to the unknown resistance rim of a post office box, and determine its resistance (See expt. No. 32). It gives R_1 . Find out its total length L and determine resistance per unit length

(4) For thermo-e.m.f. generated in the couple :-

S. N.	High Resistance R in ohm.	Temperature in °C		Diff. in temp. between two junctions $t_2 - t_1$ in °C	Balancing length of the potentiometer wire when temperature is		Mean length (l) in $\frac{P+Q}{2}$	Thermo-e.m.f. generated in micro-volts $E = \frac{R_1}{R_2} \cdot \frac{E}{L}, l$
		Hot junction (t_2)	cold junction (t_1)		increasing (in cm.) (P)	decreasing (in cm.) (Q)		
1								
2								
3								
4								
5								
6								
7								
8								
9								
10								

6. When the temperature of the hot junction is raised by 20° , the temperature of the cold junction, connected to the thermoe.m.f. generator of the thermoe.m.f. balance, will give some deflection. By sliding the jockey contact this is set on the potentiometer wire by observing no deflection in the galvanometer. Remove about $\frac{1}{2}$ inch of the thermoe.m.f. wire from the hot junction, and the balance point is obtained. It gives the length, it gives l . Read the thermometer attached to the hot junction when the balance point is obtained. It gives t_1 .

7. Now gradually increase the temperature of the hot junction. After every 20° rise in temperature obtain the balancing length as described above, till the hot junction is heated to a temperature of nearly 350°C . if it is possible.

8. Put off the burner, and let the hot junction cool. Again determine the balancing lengths of the wire for the same temperature (as determined above) while the temperature is falling. Thus, for the same temperature of the hot junction, two readings for l can be obtained. Determine the mean of the two readings.

9. Periodically check the temperature of the cold junction. It should remain constant at $t_2^{\circ}\text{C}$.

10. Knowing E , l and R , calculate the value of e , the thermoe.m.f. generated at different temperatures of the hot junction.

11. Determine the difference between the temperatures of the hot and the cold junction (e) for every reading. Plot a graph between this difference of temperatures between the two junctions (e) and the corresponding thermoe.m.f. generated (E). It will come out to be a parabola.

12. From the graph find out the neutral temperature corresponding to which the thermoe.m.f. generated in the couple is maximum.

Observations:—

- (1) Resistance of the potentiometer wire $AB (R_1) = \dots \text{ohm}$.
- (2) Length of the potentiometer wire $AB (L) = \dots \text{cm}$.

Oral Questions:—1. What is a thermo-couple, and how thermo-currents are produced? 2. What is the direction of the current in a thermo-couple? On what factors does it depend? 3. What is neutral temperature and how is it determined? 4. Define temperature of inversion? Does it depend upon the temperature of the cold junction? 5. What is a thermo pile and what are its uses? 6. Is thermo-e.m.f. a reversible process? If yes, how? 7. Which couple generate the maximum thermo-e.m.f. for the same difference of temperature between its two junctions? 8. What is the order of the magnitude of the thermo e.m.f. developed in an iron-copper, thermo-couple? 9. How is such a small e.m.f. measured by the potentiometer? 10. Why such high resistances are put in series, with the potentiometer wire A.B.? 11. Which end of the thermo-couple should be connected to the terminal A of the potentiometer wire and why?

Calculations:—

1. The resistance per unit length of the potentiometer wire $r = \dots \text{ohm.}$

2. Calculate the thermo-e.m.f. generated (e) by each

observation from formula (iii) or (v) and then draw a graph between the difference of temperature between the two junctions and the corresponding thermo-e.m.f. generated.

Result:—The graph is in the form of a parabola. The temperature at which the thermo-e.m.f. is maximum i. e. the neutral temperature for iron-copper couple $= \dots^\circ\text{C.}$

Precautions and sources of error:—

1. See expts. 16, 17, 18.

2. The accumulator B₁ should be fully charged and

must possess a fairly large capacity, so that the e.m.f. in the potentiometer circuit may remain constant. To keep this e.m.f.

steady a key should always be provided in the potentiometer circuit, and current should be drawn only when taking

observation.

3 The jockey should be pressed only for a small time. It should not be moved on the wire pressed, otherwise the

uniformity of the wire would be spoiled.

4 The thermo-e.m.f. generated is very small, and therefore, the p.d across the potentiometer wire AB should not be

more than 1 millivolt, so that the potential gradient becomes one micro-volt.

5. A very high sensitive galvanometer should be employed to determine the balance point. A moving coil suspended type

of galvanometer with lamp and scale arrangement will give

better result.

6. In the thermo-couple the two dissimilar metals should be in contact, with each other only at the junction.

7. Higher potential terminal of the thermo-couple should be connected to the end A of the potentiometer wire.

8. While determining balance point the current in the potentiometer wire should remain constant, otherwise the

calibration will go wrong.

Criticism:—The method gives fairly good result. However, the accuracy will largely depend upon the constancy

of e.m.f. of the accumulator, and the exact knowledge of the e.m.f. of the standard cell or the Daniell cell, used to calibrate

the potentiometer wire. The main source of error in this experiment is that as the wire used is very long, it cannot be of

uniform thickness throughout its length, hence the potential gradient will not remain constant. Thus, to avoid this error

Crompton's potentiometer is preferred.

maximum value of the alternating e.m.f. developed across the two ends of the choke coil C , and I_0 be the maximum value of the alternating current flowing through it. Then, we have,

$$I_0 = \frac{E_0}{\sqrt{R^2 + \omega^2 L^2}} \quad \dots \quad (i)$$

Where, L and R are respectively the inductance and the resistance of the coil C and $\omega = 2\pi n$, where n is the frequency of the A.C.

$$\therefore I_0 = \frac{E_0}{\sqrt{R^2 + 4\pi^2 n^2 L^2}} \quad \dots \quad (ii)$$

$\sqrt{R^2 + 4\pi^2 n^2 L^2}$ is known as the impedance of the coil. If the impedance is denoted by Z ,

$$Z = \sqrt{R^2 + 4\pi^2 n^2 L^2} \quad \dots \quad (iii)$$

$$\text{or} \quad Z = E_0 / I_0 \quad \dots \quad (iv)$$

But as the A.C. instruments only read virtual volts and virtual amperes,

$$Z = \frac{E_0 / \sqrt{2}}{\text{Virtual E.M.F.} / \sqrt{2}} = \frac{I_0 / \sqrt{2}}{\text{Virtual current}} \quad \dots \quad (v)$$

Where E and I are respectively the e.m.f. and current measured by the A.C. voltmeter, and the A.C. ammeter. If R is known, knowing Z , the value of L can be calculated from equation (iii).

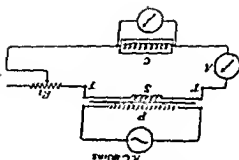
Method.—1. Connect the primary coil P to the A.C. mains. Put the choke coil C in series with the secondary coil (S) of the step-down transformer through an A.C. ammeter A and a high resistance rheostat R_1 . Connect the A.C. voltmeter across the two terminals of the choke coil.

2. Switch on the A.C. mains, and adjust the value of R_1 to obtain a potential difference of nearly 5 to 10 volts across the two terminals of the choke coil C .

3. Read the voltmeter. It gives E , the value of the virtual e.m.f. acting across the coil. Similarly read the ammeter. It gives I , the value of the virtual current flowing through C . It completes one set of readings for E and I .

4. Change the value of the resistance R_1 , and repeat the above procedure. In this way take atleast 7 to 8 different sets of readings.

5. Calculate the value of the impedance Z by each set and then determine its mean value.



connected from each other.

the beginning of the section. Primary and secondary are A.C. voltages and A.C. amperes are noted on electricity in which the A.C. of lower voltage is to be fed. For description of secondary has a lower turn, and is connected to the circuit in series to the A.C. source. In a step-down transformer, the secondary has a large number of insulated copper wires and is connected to a red metal (5) wound upon an iron core. The primary is a separate winding. It consists of two coils, a primary (P) and a secondary (S). The primary is connected to the A.C. source and the secondary is connected to the load. The primary is a device for converting

the power of the transformer. It consists of two coils, a primary (P) and a secondary (S). The primary is connected to the A.C. source and the secondary is connected to the load. The primary is a device for converting

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Criticism:—The method gives fairly good results. A large number of sets should be taken for E and I to get the correct value of the impedance Z.

Oral Questions:—1. What is an A. C. current and how does it differ from a D. C. current? 2. What is a transformer? 3. How does it step up or step down the incoming voltage? 4. Why the coils are wound over a soft iron core? 5. How is the A. C. e. m. f. and current measured? 6. What is difference between the A. C. measuring instruments and D. C. measuring instruments? 7. Why the divisions on the scale are crowded for the lower values in the A. C. measuring instruments? 8. What do you understand by the impedance of an A. C. circuit, what are the units in which it is measured? 9. Define reactance and give the relation between impedance, reactance and ohmic resistance. 10. What is the function of a choke coil in an A. C. circuit? 11. What are virtual volts and virtual amperes? 12. Do the A. C. instruments measure the virtual volts and amperes or actual volts and amperes? 13. Can these A. C. instruments be used to measure D. C. voltage and current? 14. Why a high resistance rheostat R₁ included in the circuit? 15. Does this stepping down of the incoming voltage alter the frequency?

6. Switch off the current, put the choke coil in the unknown resistance arm of a P. Q. box, and determine the resistance of the coil by the procedure described in experiment No. 32. It gives the value of R .
7. Knowing Z , R and ω determine the inductance L of the coil by the equation (iii).

Observations:—

S. N.	E. M. F. in volts	Current in amp.	Impedance $Z = E/I$ in volts	Resistance of the choke coil R in ohms	Inductance of the choke coil L in henries
1					
2					
3					
4					
5					
6					

Calculations:— Calculate the impedance Z by the formula $Z = E/I$ by each observation and determine the mean value of Z . Knowing Z and R calculate L by the formula,

$$Z^2 = 4\pi^2 n^2 L^2 + R^2$$

$$\text{or } L^2 = \frac{Z^2 - R^2}{4\pi^2 n^2}$$

Result:—

- (1) The impedance of the given choke coil = ∞ ohm.
 (2) The inductance of the coil = ∞ Henries.
- Precisions and sources of error:—** 1. Only the secondary coil of the transformer should be connected in the circuit. If the connections are done the other way, e. m. f. in the circuit will enormously increase.

2. Ammeter should be connected in series, while the voltmeter should be put in parallel to the choke coil.

3. In the A. C. measuring instrument, the divisions on the scale are not uniformly spaced. They are crowded towards the lower values, and expanded at the higher values. Therefore, to read them more accurately higher values of current and p. d. should be taken.

vibrate in loops as described in Melde's experiment. If the length of the string is adjusted to obtain well defined nodes and antinodes, the string will be in resonance with the vibrator i. e. the frequency of vibration of the string will be the same as that of the vibrator, which itself is vibrating with the frequency of A. C. mains. Let this resonant length of one loop of the cord be l , and n be its frequency of vibration, then we have,

$$n = \frac{1}{2l} \sqrt{T/m} \quad \dots \quad (1)$$

Thus, knowing l , T and m , n can be calculated.

Method:—Switch on the current and adjust the length of the rod CD so that it is in resonance with the A. C. supply. It can be obtained by getting the maximum amplitude of vibration of the free end.

2. Weigh the pan in which the weights are to be put. Take a light string and tie its one end to the vibrator, and the other end to the pan passing over the pulley. Put some weights in the pan (say 1 to 2 gm.) so that tension is applied and the string begins to vibrate. As described in Melde's experiment loops will be formed on the string.

3. By shifting the vibrator forwards or backwards change the length of the string so that the nodes and antinodes are rendered sharp and well defined. (Under these conditions the string will be in resonance with the vibrator).

4. Leaving out the two extreme loops, determine the length of the string between the rest of the intervening loops. Let it be L . Count the number of intervening loops. Let it be n . Then L/n will be the length between two consecutive nodes.

5. Keep tension constant, change the length of the string and the number of loops and similarly obtain resonance. In this way for the same tension obtain atleast three sets. Find out the value of l in each case, and then determine its mean value.

6. Add the weight of the pan to the weights put in the pan and multiply it by 8 to get the total tension (T) applied to the string.

7. Weigh the string, and find out its mass per unit length (m).

8. Knowing l , T and m calculate n . It completes one set.

9. Now change the tension for two or three times, and similarly obtain the values for l , T and m for each set.

10. Calculate the value of n from each set, and then find its mean.

EXPERIMENT No. 36

Experiment:—To determine the frequency of A.C. mains with the help of an electrical vibrator.

Apparatus: Electrical vibrator, string, pulley pan, box, table lamp etc.

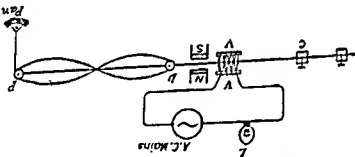


Fig. 1.

Description of the apparatus:—The electrical vibrator consists of a solenoid *VV* through which passes a thin steel wire *CD*. One end of the wire is clamped at *C*, while the free end *D* passes through the two pole pieces of a permanent magnet *NS* and carries a hook (or a hole). A string is tied at the free end. The other end of the string passes over a pulley *P* and carries a pan in which weights can be put. The two ends of the solenoid wire are connected to the A.C. mains whose frequency is to be determined through a 100 watt lamp *L*.

Theory:—When a current is allowed to pass through the solenoid the iron rod is magnetised longitudinally. Its polarity reverses with the change of sign of the current. Due to the interaction between field of the wire and field of the permanent magnet, the iron wire begins to vibrate with the frequency of A.C. supply. The length of the wire *CD* is adjusted to get the maximum amplitude of the free end.

Let the mass per unit length of the string connected to the vibrator be *m*. If it is stretched by a tension *T* (which can be obtained by putting weights in the pan) it will begin to

Calculations:—Calculate n by the formula,

$$n = \frac{1}{2l} \sqrt{\frac{T}{m}}$$

for each set, and then determine the mean value of n i. e. the frequency of the A. C. mains.

Result:—Frequency of the A. C. mains (n) = ... V/S.

Precautions and sources of error:—1. The string used must possess fairly a constant mass per unit length, hence a fishing cord is more satisfactory than an ordinary thread.

2. To start with, it should be carefully seen that the iron rod is in resonance with the A. C. supply. If it is so the free end of the rod will vibrate with maximum amplitude.

3. The pulley should be frictionless, otherwise the computed tension will not be the actual tension applied.

4. Nodes formed on the string must be sharp and well defined. As the first and the last node cannot be accurately located, the two extreme loops should not be taken in to account while finding l .

5. The hanging pan must be steady while the final reading is taken.

Criticisms:—See Meide's experiment. The greatest error is involved in measuring the length of the loops. To get better results, the number of loops taken should be large.

Oral questions.—1 See Meide's experiment. 2 What do you mean by A. C. mains and its frequency? 3. How do you determine it by this method? 4 Describe an electrical vibrator.

5. What are the functions of the solenoid and the permanent magnet? 6. Why a lamp is employed in series with the mains?

7. What is the frequency of the A. C. Supply in your city? 8. Why the length of the rod is adjusted in the beginning? 9 Is there any other method of determining this frequency?—H. L. S. 4.

Length of the string = ... cm.
 Mass of the string = ... gm.
 Mass per unit length of the string = ... gm.
 Acceleration due to gravity $g =$... cm/sec²

- 27 -

Wt. of Pan (W_1)	Wt. placed on the pan (W_2) in gm.	Tension $T = (W_1 + W_2)g$ in dynes,	S. N.	No. of loops (p)	Length of the string for p loops (L)	Length of the string for one loop (l)	Frequency $n = \frac{1}{2l} \sqrt{\frac{T}{m}}$
			1 2 3				
			1 2 3				
			1 2 3				

change in anode voltage required to cause a certain small change in anode current to the change in grid voltage required to cause the same change in anode current. See fig. 1. These curves are drawn between grid potential and anode current at three fixed anode voltages viz.

60, 80 and 100 V. It is clear that a change in anode current by an amount AB can be done either by changing the grid potential from C to B at plate potential of 60 V or by changing the anode potential from 60 V to 80 V at grid potential of B. Thus if μ represents the amplification factor,

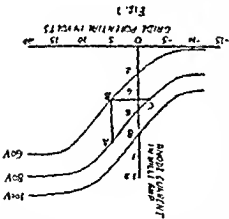


Fig. 1

Here $G_1 - G_2$ represent grid potentials at B and C respectively. This factor has no unit and its value must be greater than 1 and sometimes is higher than 100.

(ii) Grid plate transconductance or mutual conductance: It is defined as the rate of change of anode current with grid potential, keeping the plate voltage constant.

$$\text{or } g_m = \frac{I_{a2} - I_{a1}}{V_{g2} - V_{g1}} \quad \text{--- (i)}$$

In other words it is defined as the slope of the anode current and grid potential curve. From fig. 2.

$$g_m = \frac{I_{a2} - I_{a1}}{V_{g2} - V_{g1}} \quad \text{--- (ii)} \quad \text{Where } \mu \text{ and } g_m \text{ are respectively}$$

the anode current at 6.55 V and 10 V.

EXPERIMENT No. 37

Experiment:—To draw characteristic curves of a given triode valve and determine its constants.

Apparatus:—A triode valve fitted properly with a socket, a source of low tension for filament usually a 2 volt battery or a L. T. transformer, a grid bias battery capable of giving say 30 volts with a potentiometer arrangement, a high tension battery giving upto say 250 volts or any other source like a rectifier, a milliammeter, two voltmeters—one reading upto 30 V. and the other upto 250 V., rheostats, plug keys etc.

Description of Apparatus:—As the name suggests, usually there are three electrodes—cathode, grid and anode in a triode valve. Cathode is either directly or indirectly heated to give a source of electrons.

Anode is kept positive with respect to the cathode and as a result it gives anode or plate current.

This plate current is controlled by applying suitable potentials to the grid electrode-which lies nearer to the cathode. Its construction is such that it itself attracts a negligible fraction of the current but due to its nearness affects very significantly the plate current.

There are various types of triode valves and as such before using it, correct connections with various terminals of the sockets must be understood. Also remember, that filament of the valve is a very sensitive part and therefore its correct p. d. and current capacity must be known before its use.

Theory:—As we have already seen, there are three independent variables viz. cathode temperature, grid potential, and plate potential. On these depend two variables viz. plate current and grid current. By varying one of these independent variables, the dependence of these two dependent variables can be studied. These variation curves are called characteristic curves. The most important characteristic curve is that which is drawn between grid potential and plate current at a constant plate potential and filament current.

Following are the three constants of a triode valve. They

depend on its geometry.

factor—It is given by

of the

Mark these two terminals of H. T. carefully and note which is +ve and which is -ve terminal. As shown in diagram the +ve terminal is connected through a milliammeter to the plate terminal of the valve and the -ve terminal is connected to the -ve terminal of L. T. which is connected to filament.

Between the two terminals of the H. T. is also connected in parallel a high range D.C. voltmeter.

(c) Grid circuit:—The grid bias is supplied either by a lead accumulator or a dry cell. In series with it, is arranged a potentiometric circuit through a plug key. As we are required to use both +ve and -ve bias, the connections made are slightly unusual.

In series with the battery, is connected a high resistance (rheostat) and a plug key. The two fixed terminals of the rheostat must be used. Now connect the mid point of the battery to the -ve terminal of the L. T. of filament and the variable contact of the rheostat is connected to the grid terminal of the valve. In parallel with these two points is connected such a voltmeter whose zero lies in the centre of the scale and is capable of reading upto say 15 volts on either side.

The connections are now complete.

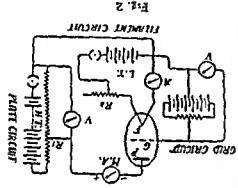


Fig. 2

volts. Thus, a +ve potential is applied between the filament and the plate.

6. Then insert the grid circuit key and adjust the sliding contact of rheostat till the voltmeter reads say -12 volts. Now the grid is -ve with respect to the filament and a p.d. of 12 volts exists between them.

7. Under the above conditions, note the current in milliammeter. This gives plate current at a plate potential of 60 V. and grid bias of -12 V.

(iii) Plate resistance (r_p)—It is the internal resistance of the valve offered to the flow of current in between the filament and the plate. It is defined as the ratio of change of anode potential to the change in anode current caused at a fixed grid potential.

$$\text{Thus } r_p = \frac{\delta V_a}{\delta i_a}$$

$$(iv) \quad \dots \dots \dots = \frac{E_a - E_c}{80 \text{ V} - 60 \text{ V}}$$

$$(v) \quad \dots \dots \dots = \frac{r_m}{\mu}$$

Method:—Generally the arrangement of apparatus varies from plate to plate and the maintenance of potentials depends on the type of triode valve. So the method given below does not mention anything in particular but describes it in a general way.

1. Before making connections it is assumed that the triode valve is properly fixed in its socket and the various terminals e.g. filament, plate etc. are clearly and correctly indicated.

2. Ascertain whether the cathode of the given triode is directly or indirectly heated one. Find out the required potential and the current for cathode heating. Violation of this precaution might fuse the valve.

3. Normally for this experiment three separate circuit plate, grid and filament are required.

(a) Filament Circuit:—As shown in figure 2 connect the two filament terminals to the low tension (L.T.) battery (say giving 2 volts or 6 volts depending on the valve) through a fine rheostat and an ammeter. It is advisable to insert a plug key also. Before inserting the plug key, gradually slide so adjusted that it offers maximum resistance. Gradually slide it till the ammeter registers proper current for the given valve.

(b) Plate circuit—High tension (H.T.) is needed for this circuit. Usually a set of dry cells or a rectifier unit is used for this purpose. It is assumed here that a student is supplied with a source of H.T. Usually a potentiometric arrangement is also incorporated in the unit and a student is not required to make it. One terminal on this potentiometer is fixed while the other can be varied to get different values of H.T.

From the graph find the change in current corresponding to BA i.e. $(i_a - i_b)$ and the change in grid potential corresponding to B and C i.e. $G_1 - G_2$.

Now with the help of equations (i), (ii) and (iv) find μ , g_m and r_p .

These calculations can be repeated by choosing B point on another curve also.

The point B is taken on 60 V curve while C and A on 80 V curve.

∴ difference in plate potential = $80\text{ V} - 60\text{ V} = 20\text{ volts}$.

Change in plate current $i_a - i_b = \dots$ milli-amp.

∴ $\mu = \frac{G_1 - G_2}{80\text{ V} - 60\text{ V}}$

$g_m = \frac{i_a - i_b}{G_1 - G_2} = \dots$ mhos

$r_p = \frac{g_m}{\mu} = \frac{\dots}{80\text{ V} - 60\text{ V}} = \dots$ ohms

Retain: $\mu = \dots$, $g_m = \dots$ mhos, $r_p = \dots$ ohms.

Sources of error and precautions:—] The characteristics of the valve must be known before use and the specifications given must not be exceeded.

The filament heating current must be maintained abnormally constant. To achieve this a sensitive ammeter and a proper rheostat must be used.

3. The electrons flow from filament to the plate inside the valve. As such the conventional direction of current is from plate to filament in side the valve. Therefore, the -ve of the milliammeter must be connected to the plate.

Normally the grid potential with respect to filament should not exceed 23 volts. Otherwise there might be excessive mechanical strain in between the two and the filament might give way.

5. If the centre of the grid bias battery is not connected to the -ve of h.t. battery, the connections will have to be changed for application of +ve and -ve grid bias. In this case simply by varying the variable rheostat, correct is achieved. Remember that use of zero centred voltmeter is convenient for this purpose.

8 Draw with the help of grid circuit a graph of plate current in milliamperes against grid bias in steps of 2 volts, viz., -10V, -8V, -6V, -4V, -2V, and 0V, and keeping plate potential constant at 80 V. Note that the plate current with the help of milliammeter decreases as the grid bias is made more negative. This is the filament current curve also be kept constant. The complete one set.

9 Keeping the filament current constant, change the plate potential to 80 V and then to 100 V. Each time repeat the above set by noting plate current at various grid bias.

10 Draw a graph between grid bias as abscissa and plate current as ordinate. You will get three such curves at 60 V, 80 V, and 100 V respectively.

Observation—Specifications of Triode valve, if any, Valve Number.

Filament heating current.

Maximum plate potential.

S. N.	Grid Potential in volts	Plate current in milli-amperes when plate potential is equal to		
		60 V	80 V	100 V.
1	-12 V			
2	-10 V			
3				
4				
5				
6				
7				
8				
9				
10				
11	+10 V			
12	+12 V			
13				

Calculations:—You will get the curves as shown in Fig. 1. The peculiarity of the curves is that their lower and upper portions are curved while the middle portion is straight.

Approximately in the middle of the straight portion on the curve for say 60 V, choose a point B. Draw two straight lines BC and BA parallel to X and Y axis respectively and intersecting the next higher curves say of 80 V at C and A.

From the graph find the change in current corresponding to BA i.e. (i_{a-1}) and the change in grid potential corresponding to B and C i. $G_1 - G_2$.

Now with the help of equations (i), (iii) and (iv) find μ , g_m and r_p .

These calculations can be repeated by choosing B point on another curve also.

The point B is taken on 60 V curve while C and A on 80 V curve.

\therefore difference in plate potential = $80 \text{ V} - 60 \text{ V} = 20 \text{ volts}$.

Change in plate current $i_{a-1} = \dots$ milli-amp.
 $\mu \dots$ amp.
 $= \dots$ volts.

$$\therefore \mu = \frac{80 \text{ V} - 60 \text{ V}}{G_1 - G_2}$$

$$g_m = \frac{i_{a-1} - i_{a-2}}{G_1 - G_2}$$

$$r_p = \frac{g_m}{\mu} = \frac{i_{a-1} - i_{a-2}}{80 \text{ V} - 60 \text{ V}}$$

Result— $\mu = \dots$; $g_m = \dots$ mhos; $r_p = \dots$ ohms.

Sources of error and precautions—1. The characteristics of the valve must be known before use and the specifications

6. It is desired to construct a vacuum tube which has a plate potential of 200 V and a grid potential of 100 V. The plate potential is to be 100 V and the grid potential is to be 100 V.

7. For calculation, only the portion of the characteristic curves must be used.

8. When a vacuum tube is not working, remove the plate from the heater. This will avoid excessive heating and save the batteries.

Class question—1 Describe a triode valve. 2 Why is it called a valve? 3 Of what materials is the filament made, and why? 4 What are the different arrangements employed for heating the filament? Why current, more than applied should not be allowed to flow through the filament? 5 What is the function of a grid, and how the grid bias is made +ve or -ve with respect to the filament? 6 How is plate potential applied? 7 Describe the construction, principle and working of a rectifier. 8 What are the characteristic curves of a triode and how are they drawn? 9 Define amplification factor, mutual conductance and plate resistance and give their units. 10 What is the relation between these triode constants? 11 Why the filament current and plate potential kept constant while taking one set of observations. 12 Why the potential difference between the grid and filament should not exceed 15 to 20 volts. 13 What are the uses of a triode valve?

where, T is its periodic time, and ϕ the steady deflection produced in it due to the flow of current c through it.

Knowing all the quantities mentioned in eqn. (vii) K can be calculated.

Method:—This experiment is generally set in a dark room, and the throw of the galvanometer is measured by lamp and scale arrangement.

Setting of the galvanometer —

1. Usually, you would find the galvanometer in more or less a set position. Assuming that, it is correctly set, following procedure is recommended:—

Study the given galvanometer very carefully and find out what type of clamping arrangement is provided in it.

2 Release its coil with the help of the clamping arrangement.

3. With the help of a spirit level, level it properly. usually it stands on three adjustable legs.

4. Opposite the galvanometer, at a distance of one meter or so, keep your lamp and scale arrangement.

5. See carefully whether the lamp is to be lighted by a 6 volt line or a 220 volt line. Accordingly light it.

6. Adjust the height of the lamp and the scale, so that a spot of light after getting reflected from the galvanometer falls on the scale.

7. Focus it by adjusting the lens fitted in the lamp. It is more convenient to first catch the spot of light on an opaque screen near the galvanometer, and then move it till we reach the scale. This setting always needs some practice. As far as possible the spot should lie at the zero of the scale.

8. Now look carefully towards the galvanometer coil. See that it hangs symmetrically round the soft iron core without touching its pole pieces.

9. Slightly blow in to the galvanometer or gently touch its terminals so that its coil is slightly deflected and begins to oscillate. Now see that the coil oscillates freely and free of light returns to its zero and initial position. Thus the galvanometer is ready and set for the experiment.

Very small currents should be allowed to enter ballistic galvanometer, because it is very sensitive. It is achieved in practice by making a potential-divider arrangement as shown in fig. 1.

Theory:—The connections are self explanatory. In resistance boxes are connected in series with an accumulator. A high resistance R_1 (nearly of the order of 100 to 500 ohms) is introduced in one of them, while in the other a small resistance R_2 (of the order of 1 to 10 ohms) is introduced. The ballistic galvanometer B, G is connected in parallel to the small resistance R_2 through a fairly high resistance K (of the order of 10,000 ohms).

Let E be the e.m.f. of the accumulator, and i be the current flowing through the resistance R_1 and R_2 , then,

$$i = \frac{R_1 + R_2}{E} \quad \dots \quad (i)$$

If V is the potential difference across the terminals of R_2 ,

$$V = R_2 i = \frac{R_2}{R_1 + R_2} E \quad \dots \quad (ii)$$

This p.d. drives the current through the ballistic galvanometer. Let c be the current flowing through the galvanometer and the high resistance R_3 , then, we have,

$$c = \frac{R + G}{V} \quad \dots \quad (iii) \text{ where } G \text{ is the}$$

resistance of the galvanometer. As $R \gg G$, G can be neglected in comparison to R .

$$\therefore c = \frac{R}{V} \quad \dots \quad (iv)$$

$$\text{or } c = \frac{R_1 E}{R(R_1 + R_2)} \quad \dots \quad (v)$$

From the theory of the ballistic galvanometer, we know that,

$$Q = K \theta (1 + \lambda \cdot 2) \quad \dots \quad (vi)$$

Where Q is the charge passing through it, θ the first deflection given by the galvanometer and K the constant of the ballistic galvanometer. λ then, is given by the relation,

$$K = \frac{2\pi}{T} \cdot \frac{\phi}{c} \quad \dots \dots \dots \text{(vii)}$$

where, T is its periodic time, and ϕ the steady deflection produced in it due to the flow of current c through it.

Knowing all the quantities mentioned in eqn. (vii) K can be calculated.

Method:—This experiment is generally set in a dark room, and the throw of the galvanometer is measured by lamp and scale arrangement.

Setting of the galvanometer:—

1. Usually, you would find the galvanometer in more or less a set position. Assuming that, it is correctly set, following procedure is recommended.—

Study the given galvanometer very carefully and find out what type of clamping arrangement is provided in it

2 Release its coil with the help of the clamping arrangement.

3. With the help of a spirit level, level it properly. usually it stands on three adjustable legs

4. Opposite the galvanometer, at a distance of one meter or so, keep your lamp and scale arrangement.

5. See carefully whether the lamp is to be lighted by a 6 volt line or a 220 volt line. Accordingly light it.

6. Adjust the height of the lamp and the scale, so that a spot of light after getting reflected from the galvanometer falls on the scale.

7. Focus it by adjusting the lens fitted in the lamp. It is more convenient to first catch the spot of light on an opaque screen near the galvanometer, and then move it till we reach the scale. This setting always needs some practice. As far as possible the spot should lie at the zero of the scale.

8. Now look carefully towards the galvanometer coil. See that it hangs symmetrically round the soft iron core without touching its pole pieces.

9. Slightly blow in to the galvanometer or gently touch its terminals so that its coil is slightly deflected and begins to oscillate. Now see that the coil oscillates freely and does not light returns to its zero and initial position. Thus the galvanometer is ready and set for the experiment.

Making connections:—

10. Make neat and tight connections as shown in fig. 2. Put a tapping key in parallel to the galvanometer coil. It is called the damping key, and is used only when we want to stop the oscillations of the coil.

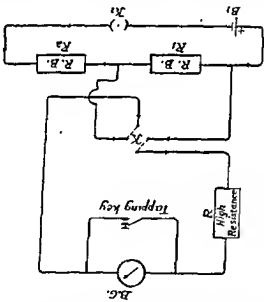


Fig. 2

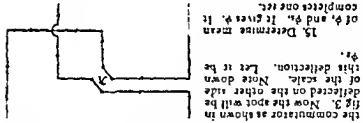
11. Connect the accumulator B₁ in series with two resistance boxes and a key K₁. Introduce a small resistance R₁ (of the order of 1 to 10 ohm.) in one of the resistance boxes and a high resistance R₂ (of the order of 100 to 500 ohm.) in another.

12. Connect the two opposite terminals of the commutator key K to the two terminals of the resistance box containing small resistance R₁, connect the other two opposite terminals of K to the two terminals of the ballistic galvanometer through a high resistance R (a 10,000 ohm. resistance coil should be taken). To determine ϕ :—

13. Close the key K₁ and the commutator K, so that a steady current flows through the galvanometer, and its coil gets deflected. Consequently, the spot of light will also get deflected.

Adjust the two resistances R_1 and R_2 in such a way that a convenient deflection of the spot is obtained on the scale. See that the spot in no case moves out of the scale. (Current in the galvanometer should not exceed a few micro-amperes. If $E=2$ volts, $R=10,000$ ohm, $R_1=1$ ohm, and $R_2=100$ ohm, C will be ≈ 19 micro-amperes.) Determine the steady deflection of the spot on the scale. Let it be ϕ_1 .

14. Reverse the current in the galvanometer with the help of



15. Determine mean of ϕ_1 and ϕ_2 . It gives ϕ . It is the deflection. Let it be ϕ .

16. Now change the values of R_1 and R_2 and repeat the above procedure, and determine the deflection ϕ in each case. In this way take 4 to 5 different sets of observations. To determine the periodic time T —

17. Pass a small momentary current through the galvanometer and then switch off the current. It gives a kick to the coil, and the latter begins to oscillate freely. Determine time for 10, 15 and 20 oscillations with the help of a stop watch, and find out the mean time T for one oscillation.

18. Calculate the current c by equation (i) and thence determine the value of $c \phi$ for each set. Find out the mean value of $c \phi$.

19. Knowing T and $c \phi$, calculate K by equation (ii).

Observations.—

- (1) Distance of the scale from the galvanometer = cm.
- (2) E.M.F. of the accumulator = V.
- (3) The value of the 2 resistances (a) = ohm, (b) = ohm.

(4) Table for determining ϕ :-

S. N.	R_1 in ohm.	R_2 in ohm.	Current in one direction		Current in reversed direction		Mean deflection in mm.
			Position of the spot		Position of the spot		
			Initial	Deflected	Initial	Deflected	
1							
2							
...							
...							
5							

5. Table for determining periodic time T :-

S. N.	No. of oscillations	Time in sec.	Time period T in sec.	Mean T in sec.
1	10			
2	15			
3	20			

Calculations—Calculate c and ϕ for each set, and then determine the mean value of c/ϕ . Knowing c and T , calculate K by formula (vi).

Calculation table—

S. N.	R_1 in ohm.	R_2 in ohm.	R in ohm.	Deflection ϕ in mm.	$c = \frac{E R_1}{R(R_1 + R_2)}$ in amp.	c/ϕ mean	$K = \frac{2c\phi}{T}$
1							
2							
3							
4							
5							

Result—The constant of the given ballistic galvanometer = ... coulombs per mm.

Precautions and sources of error—1. See that the galvanometer is properly leveled, and the coil is free to move, without touching the pole pieces.

2. A damping key should always be provided to check the undue swinging of the coil.

3. An accumulator of nearly e.m.f. should be used.

4. A very small current should be passed through the galvanometer, otherwise it will be damaged.

5. Do not unnecessarily touch the galvanometer, either wire or setting with the hand.

6. After doing the experiment, do not forget to clamp the rod

modification.—To determine the value of the logarithmic decrement.

Notes—See experiment No 37.

Great question.—1. What is a ballistic galvanometer? 2. How does it differ from an ordinary moving coil galvanometer? 3. Why its periodic time is made large, and electric damping small? 4. What is electro-damping, and how is it reduced in this case? 5. Why the coil is of large moment of inertia? 6. What do you understand by constant of a ballistic galvanometer? 7. What are the factors upon which depend this constant? 8. Will it be affected if the distance of the scale from the galvanometer is altered? 9. Why is it called steady deflection method? 10. What is current sensitivity? 11. Why only small current should be passed through these instruments? How it is secured in practice? 12. Why a damping key is used? 13. Why a high resistance is connected in series with the galvanometer coil? 14. Do you know any other method of determining this constant? 15. Why these galvanometers give only a throw when momentary currents pass through them? 16. What is logarithmic decrement, and how is it determined? 17. How can you determine the angle of dip by this instrument?

EXPERIMENT No. 39

Experiment:—To determine the constant of a moving coil ballistic galvanometer by using a standard condenser.

Apparatus:—A moving coil ballistic galvanometer, lamp and scale arrangement, a known capacity, an accumulator, a voltmeter, a Morse Key, a stop-watch, tapping key, connecting wires etc.

Theory:—We know that, if Q amount of charge flowing through a ballistic galvanometer produces a sudden deflection of θ , then,

$$Q = \frac{C T}{2\pi n A H} \theta, \quad \dots (i)$$

$$= K \theta, \quad \dots (ii)$$

Where C is the couple per unit twist, A the area of the coil, n the number of turns in the coil, H the magnetic field, T the period time, and K the constant of the ballistic galvanometer or ballistic reduction factor.

If this deflection is corrected for damping, we get,

$$Q = K \theta_1 (1 + \lambda t) \quad \dots (iii)$$

Where λ is called the logarithmic decrement, and is given by,

$$\lambda = \frac{n-1}{1} \times 2.3026 \log_{10} \frac{\theta_1}{\theta_n} \quad \dots (iv)$$

Where θ_1 and θ_n respectively stand for 1st and n th deflection throw on the either sides.

Let a condenser of capacity C be first charged to a potential V , and then discharged through the galvanometer. Let this charge Q produce a throw θ_1 in the galvanometer, then we have,

$$Q = CV = K \theta_1 (1 + \lambda t) \quad \dots (v)$$

Knowing C , V , λ , and θ , K can be calculated.

D.C.

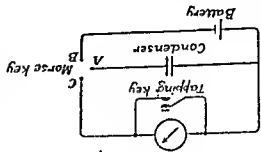


Fig. 1.

Method:—Make neat and tight connections as shown in Fig. 1. Setting of the galvanometer:—1. See previous exp. No. 38.

Making connections:—2. Put a tapping key in parallel to the galvanometer coil. It is called the damping key (explained in previous exp.).

3. Connect one plate of the condenser to one terminal of the galvanometer, while the other to the terminal A of a Morse key. The other terminal of the galvanometer is connected to the terminal C of the Morse key. Connect one terminal of the accumulator to one plate of the condenser, and the other to the terminal B of the Morse key.

The connections through the Morse key or discharge key are so made that a contact between A and C discharges the condenser through the galvanometer. A sudden contact between A and B charges it by putting it in parallel to the accumulator and simultaneously disconnects it from the galvanometer. These connections should be very carefully followed.

4. Choose a suitable capacity. By suitable we mean one which will give a throw with in the scale.

5. Press the knob to establish contact between A and B. This charges the condenser to the value of the potential equal to the e. m. f. of the accumulator (V). This is usually = 2 volts. Measure it accurately with a high resistance voltmeter.

6. Now release the knob. It disconnects A from B, and establishes its contact with the galvanometer. The condenser discharges sending its charge $Q = CV$ through the ballistic galvanometer.

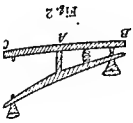


Fig. 2

7. As the throw is sudden, it should be observed carefully. It is better not to note the deflection at the very first time. Having known it approximately, focus the eyes on the approximate position of the spot, previous to the discharge, and then note the throw when the charge is passed. It will be the first throw, let it be θ_1 .

9. Then, note the eleventh successive throw. If the first throw is on the right, 2nd will be on left, 3rd on right, 4th on left....and 11th on right.

10. If damping is too much, you might note fifth or seventh throw as may be convenient.

11. Repeat the above procedure, using different quantities of capacities, and determine the corresponding throws.

12. Knowing C , V , θ_1 , and θ_n , calculate the value of K .

Observations:—
 (1) E. M. F. of the accumulator used (V) = ... volts.
 (2) Distance of the scale from the galvanometer = ... cm.
 (3) Table for θ_1 and logarithmic decrement λ .

S. N.	Capacity of condenser C in farads	Deflection of the galvanometer-coil for the first throw in mm.		Logarithmic decrement λ	$K = \frac{CV}{\theta_1(1+\lambda)}$
		the first throw in mm.	the eleventh throw in mm.		
1					
2					
3					
4					
5					
6					

Calculations—It is to be noted that according to theory θ is the angular deflection. But here we keep the distance of the scale fixed, and measure θ as the linear deflection on the scale. Actually this deflection divided by the scale distance is twice the actual angular deflection of the galvanometer coil.

Calculate λ by the formula,

$$\lambda = \frac{1}{10} \times 2.3026 \log_{10} \frac{\theta_1}{\theta_n}$$

= ...

Known C , V , A , and R , K can be calculated.

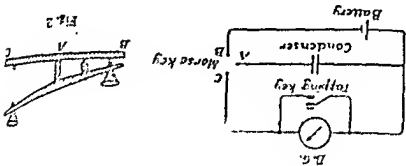


Fig. 1.

Method:—Make neat and tight connections as shown in Fig. 1. Setting of the galvanometer:—1. See previous exp^t. No. 38.

Making connections:—2. Put a tapping key in parallel to the galvanometer coil. It is called the damping key (explained in previous exp^t).

3. Connect one plate of the condenser to one terminal of the galvanometer, while the other to the terminal A of a Morse key. The other terminal of the galvanometer is connected to the terminal C of the Morse key. Connect one terminal of the accumulator to one plate of the condenser, and the other to the terminal B of the Morse key.

The connections through the Morse key are so made that a contact between A and B charges the condenser through the galvanometer, and B charges it by a contact and simultaneously discharges it by a contact. The connections should be as follows:

4. Choose a battery which will give a voltage of about 1.5 volts.

5. Press the tapping key. This charges the condenser. Measure the voltage across the condenser. This charge is equal to the e.m.f. of the battery.

6. Now repeat the experiment with the contact

EXPERIMENT No. 40

Experiment:—To determine the angle of dip by means of an earth inductor.

Apparatus:—An earth inductor with large number of coils, moving coil ballistic galvanometer, lamp and scale arrangement, compass needle, tapping key, rheostat etc.

Description:—(a) Ballistic galvanometer:—See expt. no. 39

(b) Earth inductor:—It is a coil of large area and large number of turns, so mounted that it can suddenly rotate through 180° , either along a horizontal or a vertical axis. This rotation is generally secured by a spring arrangement.

Theory:—The coil is so placed, that its axis of rotation is vertical, and its plane is at right angles to the magnetic meridian, and then turned through 180° . It cuts the magnetic flux produced by the horizontal component of the earth's field H . Consequently, induced charge Q , is generated in the coil and produces a throw θ , in the galvanometer, so that,

$$Q = \frac{2nAH}{R} = K\theta, \quad \dots \quad (i)$$

where n is the number of turns in the coil, A is its area, and R is its radius. K is the constant of the ballistic galvanometer.

If the same coil is rotated through 180° along a horizontal axis, parallel to the magnetic meridian, it cuts now the magnetic flux produced by the vertical component of the earth's magnetic field. If Q_1 is the charge produced and θ_1 is the throw in the galvanometer, we have,

$$Q_1 = \frac{2nAV}{R} = K\theta_1 \quad \dots \quad (ii)$$

Dividing eqn. (ii) by eqn. (i) we get,

$$\frac{V}{V} = \frac{\theta_1}{\theta} \text{ or } \tan \phi = \frac{\theta_1}{\theta} \quad \dots \quad (iii)$$

where ϕ is the angle of dip.

1. The capacity of the condenser should be known very accurately.

2. The observations for isothermal dilatation should be taken when the galvanometer is in the closed circuit.

3. The accumulator used should have a constant e.m.f. for such a time, that it is charged fully to the same potential as that of the battery.

4. The condenser should not be kept connected to the battery for a very long time. At the same time it should be kept charged only for a short time.

5. Give the construction of a condenser box.

6. What do you understand by the capacity of a condenser? 3. What are the factors upon which it depends? 4. Why a Morse key is employed to charge and discharge the condenser? 5. Can you use any other key? How can you reduce the throw if it is going out of the scale? 7. Why should the condenser be charged only for a short time? 8. Give the construction of a condenser box.

9. Again give it a sudden rotation through 180° by releasing the spring. (The resistance in the rheostat should not be changed in this case). Again charge is produced and the oil is deflected. Note this sudden deflection on the scale, it gives θ_2 . It completes one set.

10. Now change the resistance in the rheostat, and repeat the above procedure to get more sets for θ_1 and θ_2 .

11. Calculate the angle of dip by formula (iii) for each set and then determine the mean value of ϕ .

NOTE—In this experiment it is not necessary to determine the distance of the scale from the galvanometer, as it would cancel in calculations, and so θ is measured only in terms of distance on the linear scale. Similarly it is not necessary to find out the logarithmic decrement, which would also cancel.

Observations:—

S. No.	Deflection on the scale when the axis of rotation is vertical θ_1 in mm.	Deflection on the scale when the axis of rotation is horizontal θ_2 in mm.	$\tan \phi = \frac{\theta_2}{\theta_1}$	$\phi = \tan^{-1} \frac{\theta_2}{\theta_1}$	
1					
2					
3					

$\therefore \text{Mean } \phi = \dots$

Calculations:— $\tan \phi = \frac{\theta_2}{\theta_1}$

Angle of dip at $\dots = \dots$

no. 33 and 39.

upon the setting

red, as weak it is better to use large number

EXPERIMENT NO. 41

Experiment:—To determine wavelength of sodium light by Newton's rings.

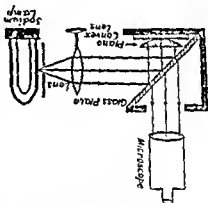
Apparatus:—Sodium lamp with necessary choke, short focus convex lens, apparatus for Newton's rings with a plano-convex lens of at least 100 cm. focal length, travelling microscope preferably with vernier constant of 0.001 cm., reading lens.

Description of the apparatus:—It consists of a wooden

box having three sides and bottom closed. A transparent glass plate is so fixed diagonally in the box such that it makes an angle of 45° with the bottom. There is a plain photographic plate (all gelatin is to be rubbed off) at the bottom of the box. On the plate, the given plano-convex lens is placed.

The travelling microscope should be with a projecting arm so that the wooden box can be placed vertically below the microscope tube. The arrangement is shown in Fig. 1.

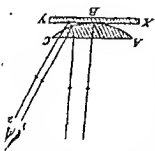
Fig. 1



Theory:—When a lens is placed on a glass plate, a thin air film is formed in between the two. The film is such that its thickness is zero at the point of contact and goes on increasing towards the periphery of the lens. The thickness of the film along a circle with the point of contact as centre is the same and goes on increasing or decreasing as we move outwards or inwards.

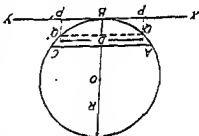
When a monochromatic beam of light is incident normally on such a lens, reflection occurs—one from the lower surface of the lens, and the other from the upper surface of the glass plate. Thus, a path difference is introduced between the two reflected rays 1 and 2 (Fig. 2.) Consequently, interference takes place giving rise to concentric bright and dark circular fringes known as Newton's rings. As the thickness of the air film is symmetrical along a circle with the point of contact B as centre, the rings so formed are circular.

Fig. 2



Let R be the radius of the lower surface of the lens ABC, which is in contact with the plane glass plate XY at B. Let t be the thickness of the air film enclosed between the two at any points P and P' equidistant from the point of contact B. Interference will take place between the reflected beams—one from the point Q lying on the lower surface of the lens, and the other from the point P, situated on the upper surface of the plate XY. They will give rise to a ring. Let its diameter be D i. e., $QQ' = D$. Evidently the path difference between these two beams $= 2t$.

Fig. 3



Hence, the points P and P' will lie on a bright or a dark ring according as the path difference,

$$2t = (2n + 1) \lambda / 2 \quad \dots (i)$$

$$2t = n\lambda \quad \dots (ii)$$

any integer, and λ is the wave length of the monochromatic light used.

From the geometry of fig. 3, we have,

$$(2R - t) = \left(\frac{D}{2}\right)^2 \dots \dots \dots (iii)$$

As t is negligible as compared to R,

$$\therefore 2t = D^2/4R$$

Therefore, if these points P and P' lie on the n th bright ring,

$$2t = \frac{D^2}{4R} = (2n+1) \lambda/2 \quad \dots \quad \dots \quad \text{(iv)}$$

Where D_n is the diameter of the n th bright ring.
If P and P' lie on $(n+p)$ th bright ring.

$$2t = \frac{D^2(n+p)^2}{4R} = [2(n+p)+1] \times \lambda/2 \dots \dots \text{(v)}$$

Where $D(n+p)$ is the diameter of the $(n+p)$ th bright ring.
From equations (iv) and (v) we get,

$$\lambda = \frac{D^2(n+p)^2 - D^2n^2}{4Rp} \dots \dots \dots \text{(vi)}$$

The order of the fringes goes on increasing or decreasing as we move outwards or inwards. D_n and D_{n+p} are measured with the travelling microscope and R with spherometer or by using any optical method.

Method:—Adjustment of box:—(a) See that the glass plate at the bottom and the inclined glass plate are clean and dust free.

(b) On the glass plate keep the given convex lens in such a way, that its convex surface touches the plate.

(c) Now put the box in such a way that its open side faces the source of light.

2. Adjustment of focusing lens:—In between the sodium lamp and the box keep the lens in such a way that approximately a parallel beam is incident on the inclined glass plate. After reflection at this inclined plate the beam should be incident vertically on the lens surface, as shown in fig. 4.

3. Adjustment of travelling microscope:—(a) Ordinarily one will find that when the above adjustments are made Newton's rings would be visible at the centre of the lens even to the naked eye. A microscope is to be focussed on it.

(b) When the rings are not visible to the naked eye, microscope becomes difficult and hence the following procedure should be adopted:—

(c) Keep the microscope in such a way that the scale is horizontal and the tube is perfectly vertical.

(d) In the position of the lens, keep a printed paper and focus the microscope on it.

(e) Remove the paper and put lens on the slide so that the centre of the lens lies vertically below the objective of the microscope.

(f) You will definitely see the fringes or parts thereof. Slightly move the lens to bring the centre of the fringes into view.

(g) Move the eye piece of the tube in such a way that one wire of the cross wire is parallel to the horizontal scale of the microscope while the other wire is perfectly at right angles to it.

(h) If you find that the fringes are not well illuminated slight adjustment of the focusing lens would do the job.

Measurement of diameter of the filogen —

4. (a) Make sure that the fringes formed are well within view.

(b) Clamp the microscope with the clamping screw so that slow motion screw can be used. See that by the help of this slow motion screw the cross wire can be moved from one end of the rings to the other end.

(c) As there is back-lash in the travelling microscope, go on moving the cross wire, say to the extreme left. Now move the cross-wire in opposite side and set the vertical wire - say, tangential to one of the bright rings.

(d) It is more convenient to fix the wire in such a way that it lies in the middle of the bright fringes.

(e) From the centre, count the number of this bright fringe. Say it is 12th.

(f) Take the reading of the microscope on the horizontal scale.

(g) Now move the slow motion screw in the same direction so that the wire moves inwards and fix it on the next inner ring, i. e. 11th exactly in the same position as above and take the reading.

(h) Repeat the above procedure till you reach to very near the centre - say, upto 3rd or 4th ring.

(i) If you find that these rings are very broad and distant of wire exactly in the centre of them is difficult, is over to the right side of the rings—always moving the slow motion screw in the same direction.

(j) If you had taken reading up to say 3rd ring on the left, fix the wire on the 3rd ring on the right side of the centre, take the reading.

(k) Repeat this, till you reach 12th ring on the right side.

(l) Record these observations in a tabular form. You see that for the same ring say 12th—there are two diameters of the micrometer—*one on left side of the centre and other when it is on the right side.* Obviously, therefore the difference between these two will give the diameter of the 12th ring.

(m) Knowing diameter, their squares can be calculated. Then you can find the difference in squares of 12th and 8th, 11th and 7th, 10th and 6th, 9th and 5th ring. This will thus give a difference between the squares of diameters of rings when $p=4$.

(n) Take mean of these differences of squares and calculate with the help of equation (vi)

5. Measurement of radius of that surface of the convex lens which is in contact with the plate:—

f spectrometer:—
(a) Usually the lens is of very big size. As such choose a spectrometer with as large a leg difference as is available in the laboratory.

(b) As it is an extremely important determination in which the value of λ (light) through which the central leg spectrometer is required to be used) is very small, repeat very observation of the spectrometer several times and then take mean observations make calculations of λ .

Optical method.—Wherever facilities are available for the method, it should be preferred over the mechanical method.

Observations:—

1. The given convex lens is plano-convex/biconcave.

2. The vernier constant of the microscope = ... cm.

3. Table for determining diameter, when the readings

are taken from left to right side:—

S. N.	No. of rings	Microscope reading when on L.H.S. of the ring in (L)	Diameter of the ring on R.H.S. of the ring in (R)	Dia. of the ring in cm. or R-L	Dia. meter (D ₁)	$D_1^{(a+p)} - D_1^p$
1	12					$D_1^{(a+p)} - D_1^p = \dots$
2	11					$D_2^{(a+p)} - D_2^p = \dots$
3						$D_3^{(a+p)} - D_3^p = \dots$
4						$D_4^{(a+p)} - D_4^p = \dots$
5						
12						

∴ Mean value of $D_1^{(a+p)} - D_1^p = \dots$ cm.

4. For determining radius:—

(a) The distance between the two legs of the

spherometer (a) = 1. ... cm, 2. ... cm, 3. ... cm.

mean (a) = ... cm.

(b) Pitch = ... cm.

Radius of convex lens $R = \frac{a^2}{2b} + \frac{b}{2} = \dots$ cm.
Wave length of sodium light will be,

$$= \frac{4Rb}{D^2(a+b) - D^2a}$$

Result:—Wave length of D lines of sodium = ... cm.

= ... Å.

Sources of errors and precautions—1. The glass plate used should be optically plane. Approximately this condition is satisfied by having a photostatic plate from which all chemicals have been removed.

Want of this plainness will not give you perfectly circular fringes.

2. It is preferable to use a plano-convex lens so that only normal reflection occurs at the first surface. In addition, the convex surface should also have large radius for the same reasons.

3. Another advantage which we get is that the thin film extends over large surface so that we get fringes having large diameters. This reduces the percentage error both in the measurement of diameter of rings as well as of radius of the surface.

4. It is necessary that the incident beam is horizontal and parallel so that after reflection at the inclined plate the incidence is normal on the lens surface and hence at the air film. As the source of light is not a point but broad source, this condition is only approximately achieved.

5. Though it is immaterial whether we use dark or bright fringes for measurement, yet it is found in practice more convenient to use bright fringes. This helps in setting of the cross wire on account of contrast which it provides.

6. It is very necessary that we measure the diameter of the fringes and not its chord. For this, in addition to the process suggested in method it is advisable first to bring the intersecting point of the two wires of the cross wire on the centre of the fringes.

7. Do not measure diameter of the first few rings as they are too thick and adjustment of cross wire becomes difficult.

8. Before start of the work see that the motion of the slow motion screw is uniform the whole range of the rings to be measured.

9. Take every precaution to see that the slow motion screw is only moved in one direction only to avoid back lash

error.

10. Remember that the fringes are localised and are formed in between the lens and the glass plate. But when we observe them they are even though the lens surface and hence are modified. So that this modification is negligible we should use as thin a lens as possible. Then the principal plane of the lens will be very close and we might assume that the fringes are formed in principal plane of object space. This assumption would give unit magnification and the modification in the diameter of the fringes would be negligible.

It is preferable if the glass plate could be placed on the top of the lens to give the thin film. The reflection through thin glass plate would be negligible. However, there are practical difficulties in this and hence is not followed.

11. The centre of the fringes should be dark but sometimes it is bright on account of some dust particles in between. To avoid this the lens should be perfectly cleaned.

Modification:—To determine refractive index of a given liquid with Newton's rings.

Theory:—When the thin film formed is of air we have

$$\lambda = \frac{D_1^2}{D_1^2 - D_2^2} \frac{t}{R} \quad \dots (1)$$

and when the thin film formed is of given liquid of refractive index μ we have,

$$\lambda = \left[\frac{(D_1^2 - D_2^2)}{(D_1^2 - D_2^2)} \right] \frac{t}{R} \quad \dots (2)$$

Dividing eqn. (2) by (1) and solving we get,

$$\mu = \frac{D_1^2}{D_1^2 - D_2^2} \frac{(D_1^2 - D_2^2)}{(D_1^2 - D_2^2)} \quad \dots (3)$$

where D_1 and D_2 respectively denote diameters of $(n+x)^2$ and n^2 fringe when the medium is liquid.

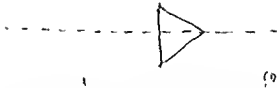
Procedure:—The method for the determination of D_1 and D_2 in air is the same having done this, put few drops of liquid on the glass plate and over it keep the lens so as to form the liquid film instead of air film. Then follow the same procedure as above to determine D_1 , D_2 and D_3 . Then calculate μ with the help of the above formula.

It will be observed that the rings are shortened in a liquid film.

For this experiment, as is obvious, determination of R is not required.

Caution.—The air film in this experiment should be thin, and the incidence of the rays should be normal, otherwise the formula employed will not hold good. The percentage error will be minimised if the diameters of the rings and the radius of curvature of the convex surface are determined accurately. Lesser will be the error in the determination of diameter if it has a large value. Consequently, the convex surface of the lens should possess large radius of curvature.

Oral questions.—1. What do you understand by the phenomenon of interference? 2. How does it take place in this particular experiment? 3. Why the Newton's rings formed are circular? 4. Where are they formed? Why the central spot is black? Can it be bright also, if so, when? 5. Why the rings are broader near the centre, and crowded as we move outwards? 6. What will happen if the air film is not of uniform thickness? 7. What are the factors upon which depend the diameters of the rings? 8. Can the plate be placed above the lens? 9. Why a broad source of light is needed in this experiment? 10. Why the radius of the convex surface should be large? 11. Can you use a biconvex lens also? 12. Why the plate should be thoroughly cleaned, before putting lens upon it? 13. Can you use white light instead of monochromatic yellow light? What difference would it make in the formation of rings? 14. Can you determine the refractive index of the liquid by this method?



EXPERIMENT NO. 42

Experiment—To determine the wave length of a monochromatic source of light with the help of Fresnel's biprism.

Apparatus—A stable optical bench, biprism of almost 180° , sodium lamp, a lens with small aperture having smaller focal length.

Description—Biprism:—It is made up of two prisms of very small refracting angle (of the order of 1° or less than 1°) placed base to base, forming a single obtuse angled prism. In practice, it is ground from the same optically true glass plate.

Optical bench—It is of a solid cast iron base, carrying a metal scale graduated in millimeters along its length and carries a

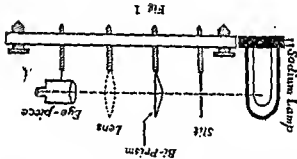


Fig 1

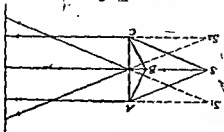


Fig. 2

trier. It supports four uprights one each for the slit, prism,

lens and the eye piece. Eye piece can be moved transversely to the bench and its position can be noted on the scale.

Theory—A biprism is simply a device to give two virtual coherent sources of light lying very close to each other. Such two narrow and coherent sources naturally, according to the conditions of interference of light, give rise to equally spaced dark and bright fringes. They are respectively formed as the path difference between the two beams is an odd number of half wave lengths or an even number of half wave lengths.

If x = fringe width i. e. the distance between two successive maxima or minima of two fringes,

d = distance between the two coherent sources,

D = distance between source of light i. e. slit and the screen i. e. eyepiece where the fringes are observed and measured,

$$\lambda = x \frac{d}{D}$$

Method—1. Before performing the experiment study the apparatus closely and understand the functions of various screws etc. provided in the various optical stands.

Setting the slit vertical :—

2. Level the optical bench with the help of a spirit level and levelling screws. Usually the bench has a three point support and as such it is more stable and can be easily adjusted for levelling.

3. Focus the eye piece on the cross wire against a white background till the cross wire appears to be distinct. Then next rotate the cross wire till one of it becomes vertical. This is done visually or with the help of a plumb line when more accurate results are expected.

4. Now bring the eye piece stand close to the slit and adjust their heights to the same level.

5. In order to make the slit vertical rotate it by means of a tangent screw provided in the stand. For verification, it is better to introduce a convex lens in between the slit and eye piece and to project the image of the slit on the eye piece. If the image of the slit is parallel to the cross wire, it is vertical.

Mounting of Biprism :—

6. Mount the biprism with its edge vertical on the upright placed next to the slit. It is immaterial as to which face is facing the slit.

7. Adjust its height so that it comes to the same level as the slit and the eye piece.

8. Next rotate the upright in such a way that its base is perpendicular to the length of the table.

9. Make the slit as narrow as possible.

10. Keep your eye on the opposite side of the slit. You will see two virtual images of the slit. Move the eye at right angle to the bench-top and fro. As you move your eye you will find that one of the images jumps across the edge of the biprism.

If the edge of the biprism is parallel to the slit the image as a whole will suddenly cross from one side to the other. If it is not parallel, either the upper or the lower portion will cross.

So with the help of tangent screw rotate the upright in such a way that the edge of the biprism becomes parallel to the slit as it is judged by the sudden transition of the image.

11. If you now look through the eye piece you will see a set of equidistant straight fringes. It necessary make the slit narrower and give slight rotations to the biprism by tangent screw to make the system of fringes more distinct.

To make the line joining slit, biprism and eye piece parallel to the length of the table :—

12. By displacing the cross wire with the help of circular scale focus it on one of the fringes.

13. Move the eyepiece away from the biprism. The fringes appear to expand but the cross wire must remain on the same fringe.

If the fringes move across the cross wire, this shift is called lateral shift and occurs when all the three, slit, biprism and eye piece are in the same straight line and parallel to the optical bench.

Therefore, displace the *lens* until the *lens* is at the optical centre and the light rays to the optical centre will then travel straight through the lens.

Now we are in a position to start the measurement.

Measurement of fringe width —

1. Fix the eye piece at such a position so that the fringes appear to be neither excessively narrow nor excessively broad.

Read the main scale and the circular scale and find the least count.

15. Now adjust the cross wire on one of the fringes. Note the reading. Then shift it to the next fringe and note the reading. Thus on taking readings of the successive fringes. Note your observations as shown in the table.

As shown calculate the fringe width corresponding to fringes by subtracting reading of 1st fringe from reading of 2nd fringe, 3rd from 2nd etc. After taking mean, calculate fringe width for one fringe.

Displacement of D i.e. distance between source (slit) and screen (eye piece) :—

16. Note the position of the slit and of the eye piece. This should give D, but we know that D is actually the distance between the slit and the focal plane of the eye piece. Therefore to know correct D we have to apply a so-called bench correction — as explained later.

Measurement of $S_1S_2 = d$ = distance between two virtual sources :—

17. See that the positions of slit and biprism remain unchanged.

18. Keep a spare upright between the biprism and the eye piece and mount a convex lens on it. It is better to cover the peripheral portion of this lens and to leave a small circular aperture in the centre to obtain well defined straight images of virtual slits. The lens should be of shorter focal length and never greater than 25 cms.

19. Fix the eye piece away from the slit at a distance greater than four times the focal length.

20. Now move the lens in between the eye piece and the biprism till we get well defined, well focussed images of the two virtual slits in the field of view of the eye piece. At this we suppose the lens is more near to the eye piece.

Then move the lens more near the slit and again the well focussed images in the eye piece. You will find that they are much enlarged. Sometimes you may find that the images are so enlarged that you cannot see both of them simultaneously in the field of view. For the sake of convenience is always better to have both of them simultaneously in view.

When you find that the distance between slit and eye piece is proper to get the above position, put the lens in the two positions mentioned above and each time measure the distance between the two images as seen in the eyepiece. Let us call these respectively d_1 and d_2 .

The distance d between two virtual images of the slit is given by $d = \sqrt{d_1 d_2}$.

determination of Bech correction for D : —

21. Remove the biprism. Take a T rod of known length. Let it be x cm. Now hold the rod parallel to the bench in such a way that its one end just touches the slit. Focus the eye piece on the other end. Read the positions of the slit and the eye piece on the bench. The difference gives y the apparent length of the T rod.

Hence the bench correction = Actual length of T rod - Apparent length of T rod as measured = $(x - y)$ cms.

Now this bench correction is to be algebraically added to the value of D measured as explained in step No. 16. This would give the final corrected value of D .

22. The above completes one set. For second set, the distance between slit and biprism may be changed and again measurements for x , d and D may be made.

Observations : — Smallest division (or Pitch) on main scale

= cm.
No. of divisions on the circular scale = cm.
Least count = cm.

No. of fringe	Micrometer reading of the eye piece (A)	No. of fringe	Micrometer reading of the eye piece (B)	Fringe width for 10 fringes (B-A)
------------------	--	------------------	--	--

No. of fringe	Micrometer reading of the eye piece (A)	No. of fringe	Micrometer reading of the eye piece (B)	Fringe width for 10 fringes (B-A)
1		11		
2		12		
3		13		
4		14		
5		15		
6		16		
7		17		
8		18		
9		19		
10		20		

Fringe width for one fringe $x = 0.5 \text{ cm.}$

—: 2221109 1011110

The distance between slit and eye piece = ... cm.

The distance between slit and eye piece = ... cm.

S. No.	Micrometer readings when lens is more near the slit	1st image P	2nd image Q
	d_1 when lens is near the eye piece	1st image P	2nd image Q
	$\sigma = \frac{d_1}{d_2}$		

3. Measurement of D = distance between slit and eyepiece where the measurement of fringes was undertaken :-

Actual length of T rod = x ... cm.
 Apparent length of T rod as measured on the optical bench, = y ... cm.
 \therefore Bench correction = $x - y$... cm.
 Hence the corrected D = observed D + Bench correction.

Position of slit	Position of eye piece where fringe width was measured	Observed value of D	Corrected D

Calculations :-

$$\lambda = x \frac{D}{d}$$

Substitute the values from above and calculate λ

Result :- The wave length of sodium light = cm.
 $\therefore A^\circ = \dots\dots\dots A^\circ$

Precautions :- 1. The slit, biquism edge and cross wire must be vertical and be in a line parallel to the optical bench.

2. The slit should be as narrow as possible.

3. The backlash error of the micrometer screw should be avoided by moving it only in one direction while taking measurements.

4. The eyepiece stand should be so fixed that the movement of the eyepiece is at right angles to the optical bench.

5. The diffraction fringes are sometimes faint. These are not equidistant fringes and so should not be confused with the equidistant interference fringes.

6. The distance between slit and eye piece should be properly set to get two positions of the lens for measuring d_1 and d_2 .

7. The axis of the lens must be parallel to the optical bench.

8. For finding fringe width σ , the position of the cross wire always must be fixed in the same way.

9. While measuring D , bench correction should always be taken into account.

Conclusion:—The chief source of error in this experiment, is introduced due to the want of parallelism between the slit, the bi-prism edge and the cross wire. The line joining the former two should also be parallel to the base of the bench. If it is not so, the fringe width will not remain x , but it will become $x \phi$ where ϕ is the angle between the line joining the slit and the edge of the bi-prism and the length of the bench. Hence the accuracy of the result will be impaired, and that is why this adjustment should be done very carefully.

Oral Questions:—1. See exp. No. 41. 2. Why two coherent sources are required to produce interference of light?

3. Will interference take place between the light given by two different candles? Why mono-chromatic light should be employed in such experiments? 5. Give the construction of a Fresnel's bi-prism. 6. How two coherent sources are obtained in this case? 7. What are the main adjustments and how are they done? 8. What harm will be done if the slit, bi-prism edge and the cross wire are not parallel to each other? 9. What do you mean by the lateral shift of the fringes? How is this shift removed? 10. What are the main precautions taken while doing this experiment? 11. What are the factors upon which depends the width of the fringe. 12. Why a lens of short focal length is used for measuring d ? 13. How will the width of the fringe change, as the eye piece is removed away from the biprism?

EXPERIMENT No. 43

Experiment:—To determine the wavelength of sodium/mercury light with the help of plane diffraction grating.

Apparatus:—Source of light—sodium/mercury lamp, spectrometer with reading lens, plane diffraction grating of known grating element.

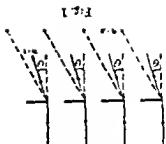
Description of apparatus:—Spectrometer:—See exp. No. 14.

Grating:—On a plane surface are drawn a very large number of straight lines so that we get a number of slits of width a , separated by an opaque distance of b . ($a + b$) is then called the grating element and gives the distance between centers of two corresponding slits.

The number of lines drawn are usually from 12,000 to 30,000 per inch and the length of ruled surface is from 2" to 5".

For usual work the grating used is replica type and hence, it should not be touched for fear, that the grating might be rubbed off.

Theory:—When a parallel beam is incident on a slit, the diffraction pattern which we get has a central maximum



with other orders of maxima of falling intensities on either side. When we have a number of parallel slits like these same plane transmission gratings, in addition, we get interference between the large number of beams. As a result, we get sharp and bright lines of light separated

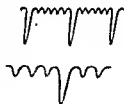


Fig. 2.

angles.

by wide dark regions. This dark region corresponds to the large number of secondary maxima of very low intensities. Thus, it is possible to get not only the direct image of the beam, but a number of secondary deviated images at different angles.

The angular separation between the zero order and n th order of primary spectrum (Maxima) is given by

$$\sin \theta = \frac{a+b}{n} \lambda \dots\dots\dots (i)$$

where, θ is the angle of diffraction or angular separation between zero and the n th order.

λ is the wave length of the colour of light used, and $(a+b)$ is the grating element.

$$\text{or } \lambda = \frac{(a+b) \sin \theta}{n} \dots (ii)$$

Method:—I. Adjustments of spectrometer to make the incident beam parallel, and to set the telescope for parallel rays etc. See expt. No. 14.

2. Setting of the grating so that incidence is normal on it:—

(a) Rotate the telescope and bring it in line with the collimator so that the image of the slit is formed on the intersection of the cross wire of the telescope. If necessary, clamp the telescope and give it slow motion for finer adjustment.

Remember that while this adjustment is being made, the prism table is already clamped.

(b) Take the reading on the scale. Read both the verniers. Call these readings a and a' respectively.

(c) Fix the given grating on the turn table. If you have the choice adjust it in such a way that the ruled surface of the grating is at the centre of the table and is at right angles to the lines drawn on it.

(d) Generally to save the ruled surface from damage, an extra glass plate is put on the grating. If so, see that the

see that the extra glass plate faces the incident beam.

(c) Now turn the telescope from its initial position through exactly 90° , so that the new readings are $a+50$ and $a'+90$. Clamp the telescope. This now ensures that the collimator and the telescope tubes are at right angles to each other. See fig. 3.

(d) Now rotate the turn table carrying the grating in such a way that the image of the slit after reflection in surface falls on the intersection of the cross wires of the telescope. If the slit image is not in the centre of the field of view, the two adjusting screws of the turn table at right angles to the length of the grating, might be slightly adjusted.

(g) To verify that your adjustment is correct you might further rotate the telescope by 180° and again turn the turn table, to get the reflected image, at the intersection of the cross wires.

Fig. 3 (i) Now under these conditions, the grating is so placed that the incidence is at 45° .

So turn the turn table through 45° or 135° so that its surface is at right angles to the incident beam and the ruled surface faces the beam.

Setting of the grating so that its ruling becomes parallel to the axis of rotation of the instrument :—

3. (a) It is assumed that when seen directly, the image of the slit is formed on the intersection of the cross wire - exactly symmetrically.

(b) Now turn the telescope to catch the 1st order spectrum and see, that again the image comes symmetrically on the intersection of the cross wire. If it is not so, adjust one of the levelling screws at right angles to the grating, to achieve this.

To make the slit parallel to the rulings of the grating:-

1. When the telescope is set on λ , the other spectrum will appear. It is the λ of the collimator, and as that is very close to λ it is not on λ , the other spectrum will appear. This is much better than the other spectrum. It is the λ of the collimator, and as that is very close to λ it is not on λ , the other spectrum will appear. This is much better than the other spectrum.

It is also to be remembered that the collimator is adjusted for parallel rays, and hence while rotating the slit at distance from the collimator lens should not be changed.

5 Measurements of the angle of diffraction:-

(a) Now substitute the source of light the wave length of which is to be determined.

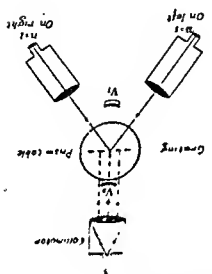


Fig 4.

(b) See that except for

properly clamped.

(c) Adjust the telescope

Clamp it, and by slow motion
of the screw turn it in the

screws are

(d) Note the readings on both the verniers- V_1 and V_2 . Normally the difference in their readings would be approximately 180° .

(e) Now bring the telescope on the first order spectrum of the same line, on the other side of the normal, and take readings of the two verniers.

(f) Remember that while recording your observations, you do not make any confusion in noting readings of V_1 and V_2 . Also note that after crossing 360° , the readings on the scale would start from $1, 2$ etc.

(g) The difference between two readings of the same vernier gives double the angle of diffraction.

(h) Knowing the number of lines drawn to an inch, the grating element is determined and hence λ is calculated.

(i) Repeat the above procedure for studying the spectrum of higher orders.

Observations :—

- [1] Particulars of spectrometer scale :—
- (i) Smallest main scale division = ... degrees, ... min.
- (ii) Total No. of vernier divisions... = ...
- (iii) Least count = ... etc.

[2] Setting of grating for normal incidence.—

- (1) Reading on the scale when collimator and telescope are in line i. e. (θ) and (θ') = ...
- (ii) Reading on scale when collimator and telescope are at right angles i. e. ($\theta + 90$) and ($\theta' + 90$) = ...
- (iii) Reading on scale when the grating is turned through 45 or 135° = ...

To make the slit parallel to the rulings of the grating :-

1. When the telescope is set on a ray, first of all spectrum very carefully locate the slit of the collimator, and see that the spectrum becomes well defined and bright. This is such a test that approximate is can be done usually, and hence only the coarse view of the slit will be needed.

It is also to be remembered that the collimator is already focused for parallel rays, and hence while focusing the slit at distance from the collimator lens should not be changed.

5 Measurement of the angle of diffraction :-

(a) Now substitute the source of light, the wave length of which is to be determined.

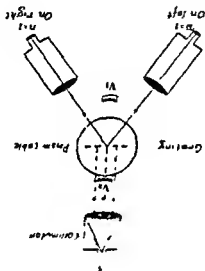


Fig. 4.

(b) See that except for telescope, all other screws are properly clamped.

(c) Adjust the telescope on the first order spectrum. Clamp it, and by slow motion screw bring the intersection of the cross wire exactly in the middle of the spectrum line.

[4] Determination of grating element $(a+b)$:—

(i) No. of lines drawn on the grating = ... per inch

∴ grating element

= ... per inch and " = ... per cm.

$$\text{Calculations :— } \lambda = \frac{(a+b) \sin \theta}{n}$$

$$= \dots \text{ cm.} \\ = \dots \text{ A.}$$

Calculations should be performed by putting $n = 1$ and 2 etc. with corresponding values of θ .

Result—The wave length of ... = $C_m = \dots$ A.

Sources of errors and precautions :— See expt. No 14.

2. Do not touch the grating surface, but hold it from its edge.

3. Sometimes, as a precaution a plane glass plate is put on its ruled surface. If it is not there, while adjusting see that the ruled surface faces collimator and not the telescope. If the glass plate is there it is immaterial which face faces the telescope.

4. Clamping of telescope and table must be studied before the start of the experiment. Both the things should never remain unclamped. Remember that one rotates the vernier while the other the main scale. If you want to rotate the telescope see that the table is firmly clamped. Also if you want to give slow motion to the telescope, it should be clamped.

5. Reading of both the verniers is essential. This eliminates the error, due to the axis of rotation not passing through the centre of the graduated circle.

6. The adjustment of grating for normal incidence must be done very carefully. An error in this, causes appreciable deviations in correct result. Therefore, use of grating in minimum deviation position is recommended.

Modification : 1—To use plane diffraction grating in the minimum deviation position, and to determine wave length of light.

Theory :—When the incidence is oblique,

$$(a+b) (\sin i + \sin \theta) = n \lambda, \text{ where angle of incidence is } i.$$

[3] *Determination of the angle of diffraction :-*

Order of Spectrum	Vernier Scale Reading	Spectrum on the right of the direct image			Spectrum on the left of the direct image			Difference of 2 readings of the same V.S. i. e. $(A-B)$	Mean θ
		M. S. Reading	V. S. Reading	Total Reading (A)	M. S. Reading	V. S. Reading	Total Reading (B)		
1	$\frac{V_1}{V_1}$								
2	$\frac{V_2}{V_1}$								
3									

Light

291]

5. Sometimes, you find that the R.P. of your grating is so small that you are not able to distinguish between the two sodium lines. In such a case, you are asked to take a mercury lamp.

6. Recognise all the prominent lines of mercury and find out their λ (either by experiment or from table, it is better to find it by experiment).

7. Having chosen as large a number of lines as possible, find out their corresponding angles of diffraction in the same order.

8. Draw a graph between λ on X axis and θ on Y axis.

9. Find out the slope of the curve at particular points corresponding to certain values of λ . That gives dispersive power at those values.

Result:—Dispersive power $\frac{d\theta}{d\lambda} = \dots$ at $\lambda = \dots$ cm.

Criticism:—The results obtained by the transmission grating are very satisfactory, provided all the precautions are taken in to account. The bias in grating may not sometimes be straight or equally spaced. This may introduce some error in the determination of the wave length.

Ques. Questions:—What do you understand by the phenomenon of diffraction? 2. What is plane transmission grating? 3. How is it prepared and what is a grating element? 4. Name the various types of diffraction gratings? 5. What is the difference between the specimens obtained by a prism and a grating? Which is better and why? 6. How you see the grating surface equal to the incident beam. 7. Why this adjustment is so very important? 8. What do you mean by different order of spectra? 9. Define dispersive power and resolving power of a plane transmission grating? What are the factors upon which they depend? 10. Why the minimum position occurs if the grating is better than the normal setup? 11. What is the difference between the interference and diffraction? 12. What will be the effect of increasing the number of lines ruled per cm? 13. See experiment No. 14.

and θ_1 .

$$\frac{d\lambda}{d\theta} = n/(a+b) \cos \theta \text{ also, where } \theta \text{ is the mean value of } \theta_1$$

4. Your result can be verified by the formula

3. Repeat the above procedure for second order.

2. Find out the angle of diffraction in 1st order corresponding to D_1 and D_2 lines as explained in main experiment. Known θ_1 and θ_2 and taking $d\lambda = 6 \times 10^{-8}$ cm, perform calculations. This gives dispersive power at $\lambda = 5890 \times 10^{-8}$ cm.

Method-1. If your grating is such that it is able to resolve the two D lines of sodium, it is best to choose them.

If a graph is drawn between λ on X axis and θ on Y axis, the slope of the curve at any point would also give the dispersive power.

where θ_1 and θ_2 are the angles of diffraction corresponding to wavelengths λ_1 and λ_2 respectively, in the same order. It is assumed here that λ_1 and λ_2 lie very close to each other.

$$\theta_1 - \theta_2$$

where $d\lambda/d\lambda$ is called the dispersive power of the grating at wave length λ . Approximately this $d\theta/d\lambda$ can be put as

$$\text{or } d\theta/d\lambda = \frac{(a+b) \cos \theta}{n}$$

$$(a+b) \cos \theta \cdot d\theta = n \cdot d\lambda$$

$$(a+b) \sin \theta = n \lambda$$

Therefore - We know that,

Calculation No. 2 - To determine dispersive power of the grating -

Result - Wavelength of light = ... cm. or ... Å.

$$= \dots \text{ cm.}$$

$$1 = 2(a+b) \sin \frac{\theta}{2}$$

Calculation -

2.25. This value is substituted in the following equation

2.26. This value is substituted in the following equation

2.27. This value is substituted in the following equation

2. Place such a sheet opposite a sodium lamp so that practice we are provided with two fine bright sources of light. Its plane should be perfectly vertical.

3. At a distance of a few feet from the plate mount the given telescope and focus it in such a way that the two bright line images of the slit are well within the field of view.

4. See that the axis of the telescope is perfectly horizontal and at right angles to the glass sheet.

5. Now mount the given rectangular adjustable slit just in front of the objective of the telescope and as near as possible.

6. Gradually reduce the width of the aperture and continue to look through the telescope.

7. A stage will be reached when you will find that the two line images are just resolved i. e. by closing the aperture just a little, the two images disappear and merge into one. Stop at this stage.

8. If it is a directly reading slit, take the reading, or measure its width with the help of a travelling microscope. This gives d .

9. Measure the distance between the glass sheet and the objective of the telescope. This gives u .

10. Measure the distance between the two slits with the help of a microscope. This gives AB .

11. The above procedure can be repeated for various values of u .

12. For every distance calculate $\frac{AB}{u}$ and compare the result. This gives limit of resolution of the telescope with aperture d .

EXPERIMENT NO. 41

Experiment—To verify the resolution for the Rayleigh criterion of a telescope.

Apparatus—A telescope with a variable section aperture of known width, a monochromatic source of two fine objects at known distance i.e. preferably a sheet coated with a tin foil in which two parallel slits at known distance, a travelling microscope etc.

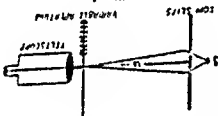


Fig. 1

$$\text{Theory:—} \theta = \frac{u}{AB} = \frac{u}{\lambda} \dots (1)$$

where, θ = limit of resolution of the telescope

AB = the distance between the two fine

objects, which serve the purpose of the

u = distance of the objects from the

eye of the telescope,

λ = Wavelength of light,

d = width of the rectangular aperture

immediately before the object of

the telescope.

Procedure—If a glass plate with tin foil is not provided, you can prepare one. Take a sheet of glass and coat it with a thick black photographic plate cover. On coating, two slits can be drawn at a distance of 2 to 3 mm.

Precautions and sources of error:—1. The telescope should be properly focussed because this will affect the expression to a very great extent.

2. Usually expression $\frac{AB}{n}$ gives higher values than

$$\frac{D}{\lambda}$$

3. The two sources of light A and B should remain perfectly vertical.

4. Back-lash error should be avoided while measuring the width of the aperture.

5. To get two readings for the same distance, it is better to measure the width of the slit also by opening the slit for the just resolution of the two objects.

Oral Questions:—1. What is the resolving power of a telescope? 2. What are the factors on which depends the resolving power? 3. How can it be increased? 4. Why the objectives of the telescopes are made up of large apertures? 5. Why the theoretical value of the resolving power generally exceeds the experimental value? 6. Why the width of the visible slit should be measured very accurately?

$$u = 79.5$$

$$d =$$

Observations :—

S.N.	Width of slit for just resolution. I	Wave length of light II	Limit of resolution $\theta = \frac{\lambda}{d}$ III	Distance of object from telescope IV	Distance between two objects AB V	Limit of resolution = AB/u VI	The expressions of III and VI cols are nearly equal
1	:						
2							
3							

Detecting devices:—Half shade plate:—It consists of two halves—One half is of quartz half wave plate cut parallel to the optic axis and of such thickness that it introduces a path difference of $\lambda/2$ between the ordinary and the extraordinary beams. The other half consists of a plane glass sheet of such a thickness that absorption of light by both the beams is equal.

For theory in details see a text book of optics.

A plane polarised beam passes through the glass plate portion. Let us call its plane as OX. When it passes through the $\frac{\lambda}{2}$ plate it decomposes into ordinary and extra ordinary. On emergence, due to phase difference of 180° , it recombines into plane polarised light but is inclined to the optic axis by an equal amount to the other side. Thus, we get two beams with their plane of polarisation along OX and OY equally inclined to the optic axis OA.

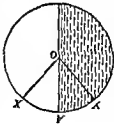


Fig. 2.

When the analyser is set in the position shown in diagram, it is asymmetrical with respect to OX and OY and hence both halves of the field of view appear equally bright. On passing through the solution, the plane of polarisation gets rotated. So both OX and OY would get rotated in the same direction. To get again the position of equal illumination, the analyser would be required to be rotated through an equal amount.

Thus, instead of using only a polariser and an analyser, use of half shade makes the detecting arrangement more sensitive.

By—quartz:—It consists of two semi-circular plates of quartz one made of right handed while the other of left handed quartz. These plates are so cut that the optic axis lies at right angles to its faces. The thickness of each plate is chosen to be near about 3.75 mm. so that the yellow light (approx. D lines of sodium) may be rotated through 90° .

When plane polarised white light is incident on this plate, as shown in fig 3 the plane of polarisation of component colours are rotated through different angles.—for red it is least, maximum for violet and 90° for yellow. In two halves the colours are rotated in opposite directions but asymmetrically. If we fix

EXPERIMENT No. 46

Experiment:—To determine the specific rotation of cane sugar solution.

Apparatus:—Polarimeter with a sensitive detecting device, sodium lamp or white lamp depending on the detecting device, beaker, flask, funnel, pipette and a balance etc.

Description of apparatus Polarimeter:—As shown in figure it consists of three main parts:—

(a) Collimating tube (b) tube for solution and (c) low power telescope.

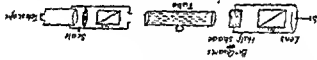


Fig. 1

Collimating tube:—At one end a convex lens is so placed, that it makes the incident beam of light almost parallel. This beam then, has to pass through a polariser (a Nicol). The plane polarised beam so produced is then incident on the detecting device - which is either a half shade or a biquartz.

Solution tube:—This is a long cylindrical tube of generally 20 cm. length. At both ends it is closed by means of optically plane glass plates with the help of metallic caps. In the middle there is the opening for filling the tube with the solution. In some tubes there is an arrangement to house the air bubble at the top, if it could not be removed completely while filling.

Low power telescope:—At the end of the tube is fixed an analyzer (a Nicol). The incident beam after passing through the analyzer passes through the eyepiece. With the eyepiece is attached a circular scale. Together with it, rotates the analyzer.

Remember that sodium lamp is to be used with half shade and white lamp with biquartz detecting arrangement.

Molecular rotation:—It is defined as product of specific rotation (α) and molecular weight (M)
 $\therefore \text{molecular rotation} = \alpha \times M$
Method:—Preparation of Solution:—1. If possible take a flask of capacity 100 c.c., i.e., a flask on which there is a mark showing 100 c.c. level.

2. Weigh it.
 3. Put in it some 25 to 20 gm. of sugar and weigh it again, to know the mass of sugar dissolved.
 4. Pour a little distilled water in it and prepare a solution
 5. Now pour more water so that the level comes up to the mark. Thus we have 100 c.c. solution of sugar of known strength.
 6. Generally we find that this solution is not very clean on account of dirt in sugar. So filter it.
 Guiding of Polarimeter:—7. Find out whether the detecting device is half shade or biquartz.

8. If it is half shade, choose a sodium lamp as source of light. For biquartz we must use white light.
 9. Study the circular scale on the eyepiece side, and note the pitch as well as the vernier constant.
 10. Rotate the analyzer and study the equal illumination or equal tint of passage upon carefully. By giving it slow rotation in either direction study if there is any range over which you are not able to distinguish between the adjustment of position. Generally you will find that this range is negligibly small. However, if no sensitive detecting device were provided you would certainly find a very big range between which you are not able to fix your analyzer

11. Fill carefully the polarimeter tube with distilled water in such a way that no air bubble remains inside the tube. Place it in the proper position.
 12. Look through the eyepiece. In general you will see that the two halves are of unequal illumination or of different colours.

13. Rotate the analyzer till you get the position of equal illumination or same colour position.
 14. Note the reading on the scale.
 15. Rotate the analyzer through 180° and again get the position of equal illumination or same colour position, and take reading. This is mutual reading.
 Filling with solution and measurement of rotation of plane of polarisation:—

an analyser crossing the red of one half, it won't be crossed by the red of the other half. But if we keep it crossing yellow of one half, it won't automatically be crossing yellow of the other half. As a result, the resultant colour produced in each half would be the same and would be a mixture of red and violet. This resultant colour will be greyish and is called the tint of passage. The analyser is kept in any other position, as indicated by dotted position, would be prominence of red tint on right hand side and violet tint on left hand side as is obvious from the diagram. The tints of two halves therefore would not be the same.

Hence, the setting of analyser for the position of tint of passage is very sensitive. A slight rotation in either direction would make the tints in two halves different.

Theory:—The amount of rotation of plane of polarization of light, when it passes through an optical medium depends,

- (1) directly on the thickness of the optically active medium actually traversed.
- (2) inversely as the square of wave length of light.
- (3) on temperature. It decreases with it.

The specific rotation of a liquid is defined as the ratio of the rotation produced by a decimeter (10 cm) thickness of the substance and its density. In case of solutions, it is defined as the rotation per decimeter length of the solution divided by the number of grams of the substance per c.c. of the solution.

$$\text{Thus, } \alpha = \frac{\theta/l}{x/v} = \frac{\theta}{x/v}$$

Here, θ = rotation of plane of polarisation in degrees.

v = volume of solution in c.c.

l = length of tube in which solution is filled in decimeters.

x = amount of sugar dissolved in gm.

α = specific rotation.

[illegible]

16. Remove distilled water. Put a few c.c. of solution in the tube and wash it carefully. Having done this, fill tube completely with the solution and place it again in position. Looking through the analyser, you will find that previous adjustment of equal illumination or tint of passage has been disturbed.

18. Rotate the analyser in such a direction as to re-attain the previous position. Take the reading.

19. Again rotate the analyser through 180° , and set position to obtain the same illumination or tint of passage take reading. This is final reading.

20. Determine the difference between the final and initial readings separately for each position. This gives angle of rotation of plane of polarisation. Find the mean of these two readings.

21. Repeat the above procedure with solution of different strengths. For this, take known volume of solution and mix it with known volume of distilled water. You can not calculate the strength of the new solution e.g. suppose you have dissolved 20 gm. of sugar in 100 c.c. solution. Let us take 10 c.c. of this solution. It will have 2 gm. of sugar in it. Make it 10 c.c. solution to 15 c.c., by adding 5 c.c. of distilled water. Now we have 2 gm. of sugar in 15 c.c. solution. Therefore,

$$100 \text{ c.c. it would be } \frac{2 \times 100}{15} = 13.33 \text{ gm. Thus, the strength of the solution is calculated in gm. of sugar dissolved in 100 c.c. of the solution.}$$

22. Plot a graph between strength of solution on X axis and rotation of plane of polarisation on Y axis. You will get a straight line, from which you can know rotation corresponding to any strength.

23. Measure the length of the tube containing sugar solution and convert it into decimeter.

Observations:—

(1) a. Mass of the flask ... gm.

b. Mass of the flask + mass of sugar ... gm.

∴ Mass of sugar = b - a ... gm.

c. Volume of solution v ... c.c.

(2) Length of the tube ... cm

(3) Temperature of the solution = ... °C.

(4) For rotation of plane of polarisation:—

Pitch (or least count) of the m.s. ...

... number of divisions on the c.s. (or v.s.) ...

Reading on analyzer for extent of passage of equal illumination in detours													
With distilled water (Initial reading)						With sugar solution (Final reading)							
S. N.	First position.			Position after rotating by 180°			Strength of solution in gm. per 100 c.c.	First position			Position after rotating by 180°		
	Main Scale	Vac- nier Scale	Total (a)	Main Scale	Vac- nier Scale	Total (b)		Main Scale	Vac- nier Scale	Total (c)	Main Scale	Vac- nier Scale	Total (d)
1													
2													
5													
6													
Rotation													
							θ_1	θ_2	Mean θ $= \frac{\theta_1 + \theta_2}{2}$ in degrees				
							$= (c-a)$	$= (d-b)$					

2. Elastic constants

Substance	Young's Modulus of rigidity $(Y) \times 10^{11}$ dynes per sq. cm.	Poisson's ratio (σ)
-----------	--	----------------------------

Aluminium	7.2-7.5	2.5 to 2.7	7.5	34
Brass	9.7-10.2	3.5	6.0	34
Copper	11.0-12.0	3.4-4.6	13.0 to 14.3	25
Constantan	16.3	6.1	15.5	32
Iron (wrought)	19-21	7.7-8.3	14.6-16.0	27
Iron (cast)	10-13	3.5-5.3	9.5-9.7	23-3
Steel (cast)	19-21	7.4-7.6	16.4-17.5	23
Steel (mild)	22	8-8.9	16-19	25-3
Lead	1.6	.6	4.5	44
Glass (crown)	6.0-7.8	2.6-3.2	4.0 to 5.0	20-2
Glass (flint)	5-6	2.3	3.7	22-26
Phosphor bronze	12.0	4.4	12.1	32.9
Silver	7.8	2.2	10.5	27
Gold	8.0	2.77	16.5	42.2
India Rubber	.05	.00015	...	48

3. Some important temperatures

Substance	Absolute scale in degrees	Centigrade scale in degrees
Absolute zero	0	-273
Boiling point of liquid helium	4.2	-268.8
Boiling point of liquid hydrogen	20.3	-252.7
Boiling point of liquid air	83	-190
Melting point of ice	273	0
Estimated temperature of the outer layer of sun	6000	6000 approx.
Temperature of hottest star	25000	25000 approx.

4. Properties of solids

Properties of solids

[in

Substance	Density gm. per c.c.	Specific heat cal./gm.	Coefficient of linear expansion (a) $\times 10^{-6}$ per °C	T_{normal} cal. cm. sec. °C. ⁻¹	Melting point °C under normal pressure
Aluminum	2.7	.22	.6	.504	657
Brass	.84-.87	.092	18.9	.76	900
Constantan	.888	.098	16	.054	1300
Copper	.899	.093	17	.918	1083
Carbon (graphite)	2.22	.16-.2	5-7	.004	>3500
Cork	.22-.26	.40012	...
Glass	.24-.28	.16	..	.0225	1000
Gold	19.3	.0916	14	.70	1063
Iron (cast)	7.6	.119	10.2	.114	1100
Iron (wrought)	7.85	.115	11.9	.16	1530
Lead	11.34	.055	28.2	.093	327
Platinum	21.25	.032	9	.165	1773
Quartz (fused)42
Silver	10.5	.056	18.2	.724	961
Steel	7.7	.11	11	.11	1420

2. Elastic constants

Substance	Young's modulus ($Y \times 10^{10}$) dynes per sq. cm.	Modulus of rigidity ($\eta \times 10^{10}$) dynes per sq. cm.	Poisson's ratio
-----------	--	---	-----------------

Aluminium	7.2-7.5	2.5 to 2.7	7.5	34
Brass	9.7-10.2	3.5	6.0	34
Copper	11.0-12.0	3.4-4.6	13.0 to 14.3	25
Constantan	16.3	6.1	15.5	32
Iron (wrought)	19-21	7.7-8.3	14.6-16.0	27
Iron (cast)	10-13	3.5-5.3	9.5-9.7	23
Steel (cast)	19-21	7.4-7.6	16.4-17.5	28
Steel (mild)	22	8-8.9	16-19	25
Lead	1.6	6	4.5	44
Glass (crown)	6.0-7.8	2.6-3.2	4.0 to 5.0	20
Glass (flint)	5-6	2.3	3.7	22
Phosphor bronze	12.0	4.4	12.1	32.9
Silver	7.8	2.2	10.5	27
Gold	8.0	2.77	16.5	42.2
India Rubber	.05	.00015	...	48

3. Some important temperatures

Absolute scale in degrees Cent.
in degrees

0	Absolute zero
+2	Boiling point of liquid helium
20.3	Boiling point of liquid hydrogen
83	Boiling point of liquid air
273	Boiling point of ice
6000	Estimated temperature of the outer layer of sun
25000	

6. Properties of water

Temperature °C	Density gm/cc.	Specific heat cal/g m.	Surface tension dynes/cm.	Coefficient of viscosity $\times 10^{-3}$
0	.9998	1.0093	1793
4	1.0000	1.0047	72.92
10	.9997	1.0019	74.22	13.09
20	.9982	.9988	75.75	10.6
30	.9956	.9976	71.18	8.00
40	.9921	.9973	6.57
50	.9881	.9978	6.50
60	.9780	.9987	4.69

7. Properties of gases

Substance	Density at N.T.P. gm./cc.	Specific heat (Cp) cal/gm.	Ratio of two Specific heat $\gamma = C_p/C_v$	Coefficient of thermal conductivity cal. cm. ² Sec.-°C.
Air	1.0123	.241	1.412	.57
Carbon dioxide	1.0147	.201	1.306	.127
Hydrogen	1.0057	3.402	1.41	.118
Nitrogen	.001251	.24	1.40	.053
Oxygen	.001427	.21	1.43	.0563
Steam	.000551	.458	1.303	.0513

8. Velocity of sound in solids, liquids and gases

Solids	Velocity at 20°C meters/sec.	Liquids	Velocity at 20°C meters/sec.	Gases	Velocity at 20°C meters/sec.
Brass	3600	Mercury	1407	Air	3317
Copper	3560	Water	1497	Carbon dioxide	2450
Glass	5200			Hydrogen	1273
Iron	5130				
Steel	4930				

5. Properties of liquids

Substance	Density at 0°C gm./c. c.	Specific heat cal./gm.	Latent heat cal./gm. at normal boiling point	coefficient of cubical expansion per °C × 10 ⁻⁴	Thermal conducti- vity cal./cm. ² sec. °C. ⁻¹	Freezing point °C at normal pressure	Boiling point °C at normal pressure	Surface tension at 20°C dynes/cm.	coefficient of vis- cosity at 20°C poise × 10 ⁻⁴
Alcohol (Ethyl)	79	58	205	11.0	4.2	-115	78.3	22.3	1192
Alcohol (Methyl)	807	60	267	12.2	5.0	-97	64.7	22.6	591
Carbon tetrachloride	1527	23	58.5	12.6	2.88	-63	61.2	27.2	564
Ether	736	56	88.4	16.3	3.03	-123	34.6	18.4	261
Cyclohexane	126	58	...	5.3	6.37	17	220	63.14	83 × 10 ⁴
Mercury	135.6	0.333	68	1.82	1.97	-38.9	356.7	520	1560
Therminol	8	52	...	9	3.6	26	...
Turpentine	873	42	70	9.4	3.25	-10	159	27.3	1490
Water	999.8	1.0013	538	1.5	14	0	100	73.5	1793

12. Specific resistance and temperature coefficient

Substance	Specific Resistance ohm-cm. $\times 10^{-8}$	Temperature Coefficient per °C	Substances	Specific resistance ohm-cm. $\times 10^{-8}$	Temperature coefficient per °C
Copper	1.78	0.0043	Brass	6-9	0.0010
Iron	9-15	0.0062	Constantan (Eureka)	4-10	0.0002
Steel	19.9	...	German silver	16-40	0.0044
Mercury	95.76	0.0088	Salver	16-40	0.0044
Silver	1.65	0.0040	Manganin	4-5	0.0001
Tungsten	5.0	0.0051	Nichrome	11.0	0.0017

13. Electro-chemical equivalents

Copper	0.00329 gm. per coulomb
Silver	0.001118 "
Nickel	0.000304 "

14. Horizontal component of earth's magnetic field (H):— It may be taken as 0.30 to 0.35 through out Rajasthan. The mean value 0.33 would more or less be correct for any place in Rajasthan.

15. A few important data and formulae

1	Cubic ft. of water weighs 62.43 lbs.	1	Atmosphere = 76 cm. of mercury or = 10^6 dynes.
	Area of circle of radius $r = \pi r^2$	1	Joule = 10^7 ergs
	Area of a sphere of radius $r = 4\pi r^2$	1	Watt = 1 Joule per sec
	Volume of a cylinder of radius r and length $l = \pi r^2 l$	1	Horsepower = 746 watts.
	Volume of a sphere = $\frac{4}{3}\pi r^3$	1	Kilo watt
	Area of the curved surface of cylinder of length l & radius $r = 2\pi r l$		hour = 1000 watts.
			R, the gas constant = 8.305×10^7 ergs per gm mol
			1 gallon of water weighs 10 lbs. approximately.

9. Refractive indices and dispersive powers
($\lambda = 5893 \text{ \AA. U. at } 20^\circ \text{C.}$)

Substance	Refractive index		Substance	Refractive index	
	Dispersive	power (c)		Dispersive	power (c)
Canada Balsam	1.530	...	Ether	1.352	1.017
Diamond	2.417	...	Glycerine	1.474	1
Crown glass	1.585	0.018	Turpentine	1.48	...
Flint glass	1.58-1.66	0.020-0.027	Water	1.333	0.018
Quartz	$\mu_0 = 1.544$				

10 Emission spectra of solids and gases

Element	Principal spectral lines		Element	Principal spectral lines	
	wave length (10 ⁻⁶ cm)	or λ units		wave length (10 ⁻⁶ cm)	or in λ units
Potassium (in flame)	4047.2 (v)		Neon	5881.9 (o)	
	4047.2 (v)			6402.3 (o)	
	7664.9 (v)				
	7702 (r)				
	D ₁ 5890.2				
	D ₂ 5896.2				
	4101.7 (v)				
	4337.4 (v)				
	4861.4 (v)				
	6562.8 (r)				
Sodium (in flame)			Mercury		
				4046.5 (v)	
				4339.2	
				4358.2 (v)	
				4916 (v)	
				4959 (v)	
				5160.7 (v)	
				5790 (v)	
				6232 (v)	
				6403 (r)	

11. Resistance of wires

S.W.G. No.	Diameter in		Resistance in ohm per metre					
	mm.	inch.	Copper	Manganese	Eureka	German Silver		
18	1.22	0.048	0.0148	0.0645	0.405	0.193		
20	0.914	0.036	0.028	0.107	1.22	0.57		
22	0.711	0.027	0.050	1.73	1.93	0.92		
24	0.559	0.0190	0.115	2.58	2.83	1.38		
26	0.457	0.0148	0.155	4.32	4.27	2.02		
28	0.376	0.0124	0.222	6.45	6.08	2.90		
30	0.351	0.0108	0.273	8.13	8.07	3.63		

10	0000	0043	0086	0128	0170	0212	0254	0296	0338	0379	0421	0462	0504	0545	0587	0628	0669	0710	0751	0792	0833	0874	0915	0956	0997	1038	1079	1119	1160	1201	1242	1283	1324	1365	1406	1447	1487	1528	1569	1609	1650	1691	1732	1773	1814	1855	1896	1937	1978	2019	2060	2101	2142	2183	2224	2265	2306	2347	2388	2429	2470	2511	2552	2593	2634	2675	2716	2757	2798	2839	2880	2921	2962	3003	3044	3085	3126	3167	3208	3249	3290	3331	3372	3413	3454	3495	3536	3577	3618	3659	3700	3741	3782	3823	3864	3905	3946	3987	4028	4069	4110	4151	4192	4233	4274	4315	4356	4397	4438	4479	4520	4561	4602	4643	4684	4725	4766	4807	4848	4889	4930	4971	5012	5053	5094	5135	5176	5217	5258	5299	5340	5381	5422	5463	5504	5545	5586	5627	5668	5709	5750	5791	5832	5873	5914	5955	5996	6037	6078	6119	6160	6201	6242	6283	6324	6365	6406	6447	6488	6529	6570	6611	6652	6693	6734	6775	6816	6857	6898	6939	6980	7021	7062	7103	7144	7185	7226	7267	7308	7349	7390	7431	7472	7513	7554	7595	7636	7677	7718	7759	7800	7841	7882	7923	7964	8005	8046	8087	8128	8169	8210	8251	8292	8333	8374	8415	8456	8497	8538	8579	8620	8661	8702	8743	8784	8825	8866	8907	8948	8989	9030	9071	9112	9153	9194	9235	9276	9317	9358	9399	9440	9481	9522	9563	9604	9645	9686	9727	9768	9809	9850	9891	9932	9973	10000
1	0000	0043	0086	0128	0170	0212	0254	0296	0338	0379	0421	0462	0504	0545	0587	0628	0669	0710	0751	0792	0833	0874	0915	0956	0997	1038	1079	1119	1160	1201	1242	1283	1324	1365	1406	1447	1487	1528	1569	1609	1650	1691	1732	1773	1814	1855	1896	1937	1978	2019	2060	2101	2142	2183	2224	2265	2306	2347	2388	2429	2470	2511	2552	2593	2634	2675	2716	2757	2798	2839	2880	2921	2962	3003	3044	3085	3126	3167	3208	3249	3290	3331	3372	3413	3454	3495	3536	3577	3618	3659	3700	3741	3782	3823	3864	3905	3946	3987	4028	4069	4110	4151	4192	4233	4274	4315	4356	4397	4438	4479	4520	4561	4602	4643	4684	4725	4766	4807	4848	4889	4930	4971	5012	5053	5094	5135	5176	5217	5258	5299	5340	5381	5422	5463	5504	5545	5586	5627	5668	5709	5750	5791	5832	5873	5914	5955	5996	6037	6078	6119	6160	6201	6242	6283	6324	6365	6406	6447	6488	6529	6570	6611	6652	6693	6734	6775	6816	6857	6898	6939	6980	7021	7062	7103	7144	7185	7226	7267	7308	7349	7390	7431	7472	7513	7554	7595	7636	7677	7718	7759	7800	7841	7882	7923	7964	8005	8046	8087	8128	8169	8210	8251	8292	8333	8374	8415	8456	8497	8538	8579	8620	8661	8702	8743	8784	8825	8866	8907	8948	8989	9030	9071	9112	9153	9194	9235	9276	9317	9358	9399	9440	9481	9522	9563	9604	9645	9686	9727	9768	9809	9850	9891	9932	9973	10000
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	0	1	2	3	4	5	6	7	8	9
00	1000	1002	1005	1007	1009	1012	1014	1016	1019	1022
01	1023	1025	1028	1030	1033	1035	1038	1040	1043	1045
02	1047	1050	1052	1054	1057	1059	1062	1064	1067	1069
03	1071	1074	1076	1079	1081	1084	1086	1089	1091	1094
04	1096	1099	1102	1104	1107	1109	1112	1114	1117	1119
05	1122	1125	1127	1130	1132	1135	1138	1140	1143	1145
06	1148	1151	1153	1156	1159	1161	1164	1167	1169	1172
07	1175	1178	1180	1183	1186	1189	1191	1194	1197	1199
08	1202	1205	1208	1211	1213	1216	1219	1222	1225	1227
09	1230	1233	1236	1239	1242	1245	1247	1250	1253	1256
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11	1288	1291	1294	1297	1300	1303	1306	1309	1312	1315
12	1318	1321	1324	1327	1330	1333	1336	1339	1342	1345
13	1348	1352	1355	1358	1361	1365	1367	1371	1374	1377
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17	1479	1483	1486	1489	1493	1496	1500	1503	1507	1510
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19	1549	1552	1556	1559	1563	1567	1570	1574	1578	1581
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22	1659	1663	1667	1671	1675	1679	1683	1687	1691	1694
23	1698	1702	1706	1710	1714	1718	1722	1726	1730	1734
24	1738	1742	1746	1750	1754	1758	1762	1766	1770	1774
25	1778	1782	1786	1791	1795	1799	1803	1807	1811	1815
26	1818	1823	1827	1831	1835	1839	1843	1847	1851	1855
27	1859	1863	1867	1871	1875	1879	1883	1887	1891	1895
28	1899	1903	1907	1911	1915	1919	1923	1927	1931	1935
29	1939	1943	1947	1951	1955	1959	1963	1967	1971	1975
30	1979	1983	1987	1991	1995	1999	2003	2007	2011	2015
31	2019	2023	2027	2031	2035	2039	2043	2047	2051	2055
32	2059	2063	2067	2071	2075	2079	2083	2087	2091	2095
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35	2179	2183	2187	2191	2195	2199	2203	2207	2211	2215
36	2219	2223	2227	2231	2235	2239	2243	2247	2251	2255
37	2259	2263	2267	2271	2275	2279	2283	2287	2291	2295
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39	2339	2343	2347	2351	2355	2359	2363	2367	2371	2375
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42	2459	2463	2467	2471	2475	2479	2483	2487	2491	2495
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44	2539	2543	2547	2551	2555	2559	2563	2567	2571	2575
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46	2619	2623	2627	2631	2635	2639	2643	2647	2651	2655
47	2659	2663	2667	2671	2675	2679	2683	2687	2691	2695
48	2699	2703	2707	2711	2715	2719	2723	2727	2731	2735
49	2739	2743	2747	2751	2755	2759	2763	2767	2771	2775

ANTILOGARITHMS

[illegible]

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RECEIVED AT THE OFFICE OF THE SECRETARY OF THE ARMY
JAN 1 1915

Distance	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
0	0.0000	0.0001	0.0002	0.0003	0.0004	0.0005	0.0006	0.0007	0.0008	0.0009	0.0010	0.0011	0.0012	0.0013	0.0014	0.0015	0.0016	0.0017	0.0018	0.0019	0.0020	0.0021	0.0022	0.0023	0.0024	0.0025	0.0026	0.0027	0.0028	0.0029	0.0030	0.0031	0.0032	0.0033	0.0034	0.0035	0.0036	0.0037	0.0038	0.0039	0.0040	0.0041	0.0042	0.0043	0.0044	0.0045	0.0046	0.0047	0.0048	0.0049	0.0050	0.0051	0.0052	0.0053	0.0054	0.0055	0.0056	0.0057	0.0058	0.0059	0.0060	0.0061	0.0062	0.0063	0.0064	0.0065	0.0066	0.0067	0.0068	0.0069	0.0070	0.0071	0.0072	0.0073	0.0074	0.0075	0.0076	0.0077	0.0078	0.0079	0.0080	0.0081	0.0082	0.0083	0.0084	0.0085	0.0086	0.0087	0.0088	0.0089	0.0090	0.0091	0.0092	0.0093	0.0094	0.0095	0.0096	0.0097	0.0098	0.0099	0.0100

NATURAL TANGENTS

NATURAL SINES

[illegible]

Depth	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																				
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(Numbers in different columns to be subtracted, not added)

NATURAL COSINES

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